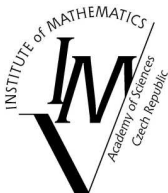


Higher Order Approximations and Discrete Maximum Principles

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Outline



- ▶ Model problem
- ▶ hp -FEM
- ▶ (Discrete) Maximum Principle (DMP)
- ▶ Classical results about DMP
- ▶ New result about DMP for higher-order approximations

Model Problem

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

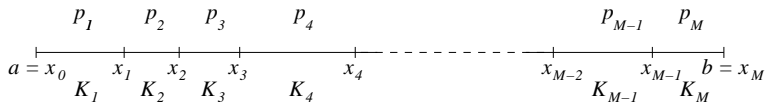
Model Problem

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Weak formulation: $V = H_0^1(\Omega)$

$$u \in V : \quad \underbrace{\int_{\Omega} \nabla u \cdot \nabla v}_{a(u,v)} = \underbrace{\int_{\Omega} fv}_{F(v)} \quad \forall v \in V.$$

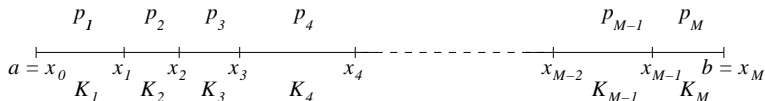
hp-FEM:



$$V_{hp} = \{v_{hp} \in V : v_{hp}|_{K_i} \in P^{p_i}(K_i)\}$$

$$u_{hp} \in V_{hp} : a(u_{hp}, v_{hp}) = F(v_{hp}) \quad \forall v_{hp} \in V_{hp}$$

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$\varphi_1, \varphi_2, \dots, \varphi_N$ – basis in V_{hp}

$$u_{hp}(x) = \sum_{j=1}^N c_j \varphi_j(x) \quad \Rightarrow \quad Ac = b, \quad \text{where} \quad \begin{aligned} A_{ij} &= a(\varphi_j, \varphi_i) \\ b_i &= F(\varphi_i) \end{aligned}$$

Maximum Principle

$$\begin{aligned} -\Delta u &= f && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

Maximum Principle:

$$f \geq 0 \quad \Rightarrow \quad u \geq 0$$

Discrete Maximum principle (DMP):

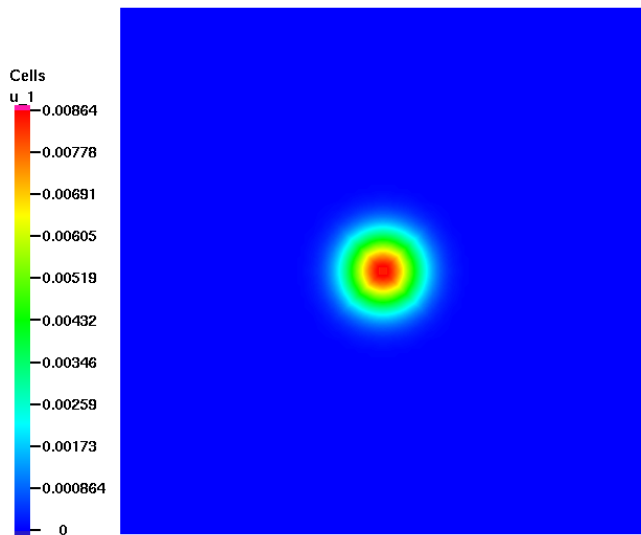
$$f \geq 0 \quad \Rightarrow \quad u_{hp} \geq 0$$

Example

$$\begin{aligned} -\Delta u &= f \text{ in } \Omega, \quad u = 0 \text{ on } \partial\Omega, \quad \Omega = (-1, 1)^2, \\ f(x, y) &= \exp(-50(x^2 + y^2)) \end{aligned}$$

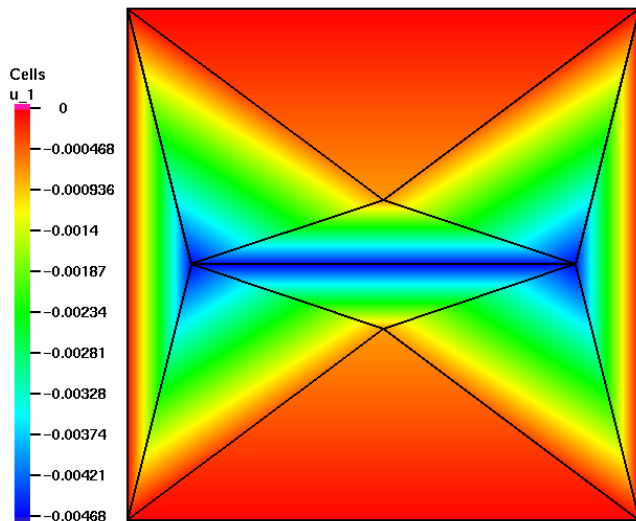
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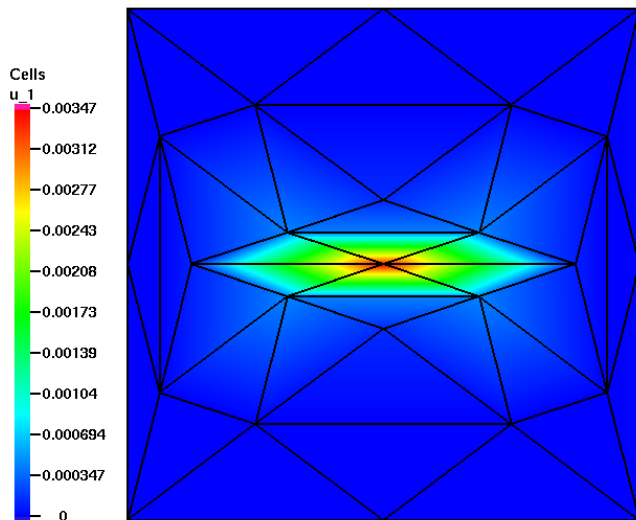
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DMP – classical result

$$\begin{aligned}
 -\Delta u &= f && \text{in } \Omega \\
 u &= 0 && \text{on } \partial\Omega
 \end{aligned}$$

$\Omega \subset \mathbb{R}^2$, piecewise linears on triangles

Theorem (Ciarlet \approx 1970)

All angles in triangulation are non-obtuse \Rightarrow DMP

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All angles in triangulation are non-obtuse \Rightarrow DMP

Proof.

Based on the fact that $A^{-1} \geq 0$.

$$\begin{aligned} A_{ij} &= \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \, dx & F_j &= \int_{\Omega} f \varphi_j \, dx \\ u_{hp}(x) &= \sum_{i=1}^N c_i \varphi_i(x), & Ac &= F, & c &= \underbrace{A^{-1}}_{\geq 0} \underbrace{F}_{\geq 0} \geq 0 \end{aligned}$$

M-matrices

$$A = \begin{pmatrix} + & - & - & - \\ - & + & - & - \\ - & - & + & - \\ - & - & - & + \end{pmatrix} \quad \text{and} \quad A \text{ is s.p.d.} \quad \Rightarrow \quad A^{-1} \geq 0$$

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▶ $A_{ii} = \int_{\Omega} |\nabla \varphi_i|^2 dx > 0$

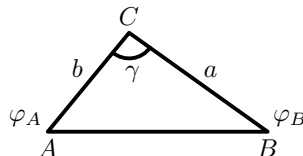
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▶ $A_{ii} = \int_{\Omega} |\nabla \varphi_i|^2 dx > 0$

▶ $A_{ij} = \sum_k \int_{K_k} \nabla \varphi_i \cdot \nabla \varphi_j dx$

$$\nabla \varphi_A \cdot \nabla \varphi_B = -\frac{ab}{(2 \text{ meas}_2 K)^2} \cos \gamma$$



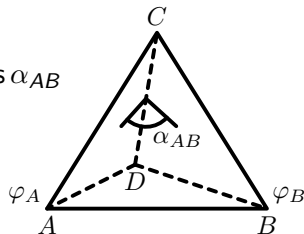
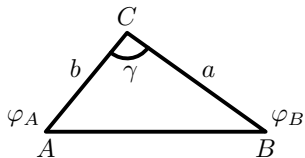
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$$\nabla \varphi_A \cdot \nabla \varphi_B = -\frac{\text{meas}_2(BCD) \text{meas}_2(ADC)}{(3 \text{meas}_3 K)^2} \cos \alpha_{AB}$$



Higher order approximation

Theorem (Ciarlet \approx 1970)

All angles in triangulation are non-obtuse \Rightarrow DMP

Proof.

$$A_{ij} = \int_{\Omega} \nabla \varphi_i \cdot \nabla \varphi_j \, dx \quad F_j = \int_{\Omega} f \varphi_j \, dx$$

$$u_{hp}(x) = \sum_{i=1}^N c_i \varphi_i(x), \quad Ac = F, \quad c = \underbrace{A^{-1}}_{\geq 0} \underbrace{F}_{\geq 0} \geq 0$$

□

Higher order approximation

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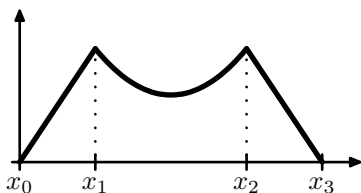
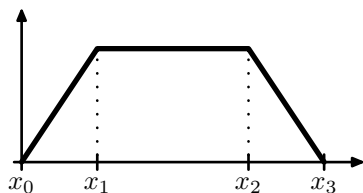
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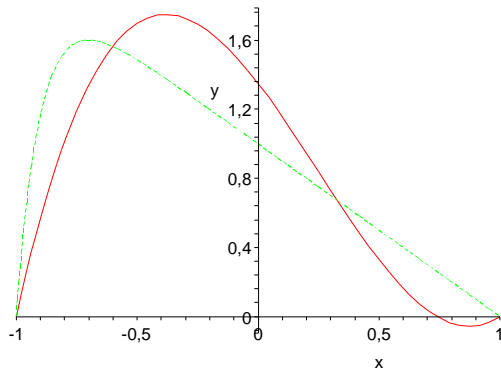
□



Counter Example

$$-u'' = f \text{ in } (-1, 1), \quad u(\pm 1) = 0,$$

$$K_1 = (-1, 1), \quad p_1 = 3, \quad f(x) = 200e^{-10(x+1)}$$



Green's function

- ▶ Find $u \in V : a(u, v) = F(v) \quad \forall v \in V$.
- ▶ Green's function

$$G_y \in V : a(w, G_y) = \underbrace{\delta_y(w)}_{w(y)} \quad \forall w \in V, y \in \Omega$$

- ▶ $u(y) = a(u, G_y) = F(G_y)$

Discrete Green's function (DGF)

- ▶ Find $u_{hp} \in V_{hp} : a(u_{hp}, v_{hp}) = F(v_{hp}) \quad \forall v_{hp} \in V_{hp}$
- ▶ Discrete Green's function

$$G_{hp,y} \in V_{hp} : a(w_{hp}, G_{hp,y}) = \underbrace{\delta_y(w_{hp})}_{w_{hp}(y)} \quad \forall w_{hp} \in V_{hp}, y \in \Omega$$

- ▶ $u_{hp}(y) = a(u_{hp}, G_{hp,y}) = F(G_{hp,y})$

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▶ $u_{hp}(y) = a(u_{hp}, G_{hp,y}) = F(G_{hp,y})$

▶ $G_{hp}(x, y) = G_{hp,y}(x)$

▶ If $a(\cdot, \cdot)$ is symmetric $\Rightarrow G_{hp}(x, y) = G_{hp}(y, x)$.

▶ $G_{hp}(x, y) = \sum_{i=1}^N \sum_{j=1}^N A_{ij}^{-1} \varphi_i(x) \varphi_j(y)$

▶ If A s.p.d. $\Rightarrow G_{hp}(x, x) > 0 \quad \forall x \in \Omega$.

Lemma

Let $\{\varphi_1, \varphi_2, \dots, \varphi_N\}$ be a basis in V_{hp} . If $A_{ij} = a(\varphi_j, \varphi_i)$ then

$$G_{hp}(x, y) = \sum_{j=1}^N \sum_{k=1}^N A_{jk}^{-1} \varphi_k(x) \varphi_j(y), \quad \text{where } \sum_{j=1}^N A_{ij} A_{jk}^{-1} = \delta_{ik}.$$

Proof.

$$a(v_{hp}, G_{hp, y}) = v_{hp}(y)$$

$$G_{hp}(x, y) = \sum_{i=1}^N c_i(y) \varphi_i(x)$$

$$v_{hp} = \varphi_j$$

$$\sum_{i=1}^N c_i(y) \underbrace{a(\varphi_j, \varphi_i)}_{A_{ij}} = \varphi_j(y)$$

$$c_k(y) = \sum_{j=1}^N \varphi_j(y) A_{jk}^{-1}$$



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Corollary

If $a(\cdot, \cdot)$ is symmetric then $G_{hp}(x, y) = G_{hp}(y, x)$.

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If $a(\cdot, \cdot)$ is symmetric then $G_{hp}(x, y) = G_{hp}(y, x)$.

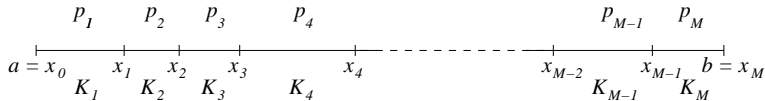
Corollary

Let $\{l_1, l_2, \dots, l_N\}$ be a basis of V_{hp} such that $a(l_i, l_j) = \delta_{ij}$. Then

$$G_{hp}(x, y) = \sum_{i=1}^N l_i(x) l_i(y).$$

$$-\Delta u = f \quad \text{in } \Omega$$

$$u = 0 \quad \text{on } \partial\Omega$$



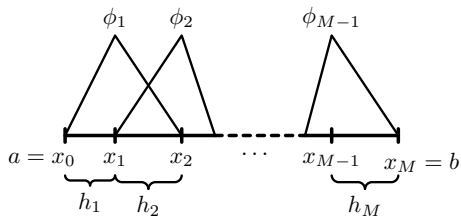
$$\blacktriangleright V_{hp} = \{v_{hp} \in H_0^1(\Omega) : v_{hp}|_{K_i} \in P^{p_i}(K_i)\}$$

$$\blacktriangleright u_{hp} \in V_{hp} : \underbrace{\int_{\Omega} \nabla u_{hp} \cdot \nabla v_{hp} \, dx}_{a(u_{hp}, v_{hp})} = \underbrace{\int_{\Omega} f v_{hp} \, dx}_{F(v_{hp})} \quad \forall v_{hp} \in V_{hp}$$

$$\blacktriangleright u_{hp}(y) = \int_{\Omega} G_{hp}(x, y) f(x) \, dx$$

$$\blacktriangleright \text{DMP} \Leftrightarrow G_{hp}(x, y) \geq 0 \quad \forall (x, y) \in \Omega^2.$$

hp-FEM basis in 1D



$$\begin{aligned}
 -u'' &= f && \text{in } \Omega \\
 u &= 0 && \text{on } \partial\Omega \\
 \underbrace{\int_a^b u'v' dx}_{a(u,v)} &= \underbrace{\int_a^b fv dx}_{(f,v)}
 \end{aligned}$$

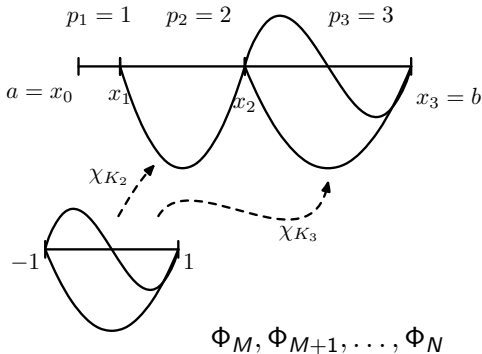
$$l_0(\xi) = (1 - \xi)/2$$

$$l_1(\xi) = (1 + \xi)/2$$

$$l_j(\xi) = \sqrt{\frac{2j-1}{2}} \int_{-1}^{\xi} P_{j-1}(x) dx$$

$$\int_{-1}^1 l'_i(\xi) l'_j(\xi) d\xi = \delta_{ij}$$

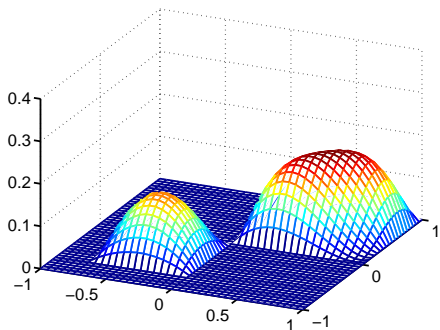
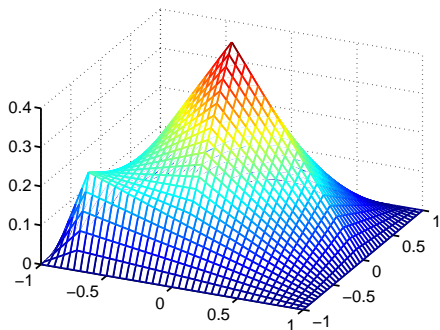
$$l_j(\xi) = l_0(\xi) l_1(\xi) \kappa_j(\xi)$$



Explicit expression of DGF

$$A = \begin{pmatrix} A^L & 0 \\ 0 & D \end{pmatrix}, \quad A^{-1} = \begin{pmatrix} (A^L)^{-1} & 0 \\ 0 & D^{-1} \end{pmatrix}$$

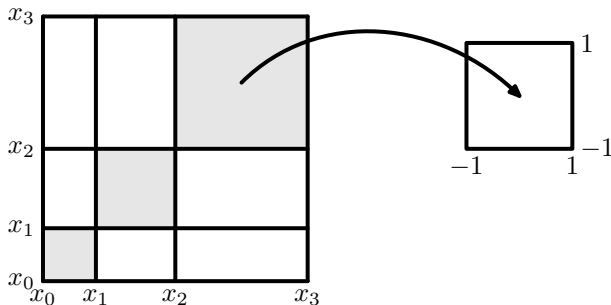
$$G_{hp}(x, y) = \sum_{j=1}^N \sum_{k=1}^N A_{jk}^{-1} \Phi_k(x) \Phi_j(y) = \underbrace{G_{hp}^L(x, y)}_{\geq 0} + \underbrace{G_{hp}^B(x, y)}_{\geq 0}$$



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Explicit expression of DGF

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$$K_i = [x_{i-1}, x_i] \quad G_{hp}(x, y)|_{K_i \times K_i} \mapsto \hat{G}_{hp}(\xi, \eta)$$

$$H = x_i - x_{i-1} \quad H_{\text{rel}} = H/(b-a) \quad t \in [0, 1] \quad l_k(\xi) = l_0(\xi)h_1(\xi)\kappa_k(\xi)$$

$$\frac{\hat{G}_{hp}(\xi, \eta)}{H} = t(1-t) \frac{(1-H_{\text{rel}})^2}{H_{\text{rel}}}$$

$$+ t l_0(\xi) l_0(\eta) \left[1 + \frac{1}{2} h_1(\xi) h_1(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) - H_{\text{rel}} \right]$$

$$+ (1-t) h_1(\xi) h_1(\eta) \left[1 + \frac{1}{2} l_0(\xi) l_0(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) - H_{\text{rel}} \right]$$

Relative Critical Element Length

$$\begin{aligned} \frac{\hat{G}_{hp}(\xi, \eta)}{H} &= t(1-t) \frac{(1-H_{\text{rel}})^2}{H_{\text{rel}}} \\ &+ t l_0(\xi) l_0(\eta) \left[1 + \frac{1}{2} l_1(\xi) l_1(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) - H_{\text{rel}} \right] \\ &+ (1-t) l_1(\xi) l_1(\eta) \left[1 + \frac{1}{2} l_0(\xi) l_0(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) - H_{\text{rel}} \right] \end{aligned}$$

Definition

$$H_{\text{rel}}^*(1) = 1$$

$$\begin{aligned} H_{\text{rel}}^*(p) &= 1 + \frac{1}{2} \min_{(\xi, \eta) \in \hat{K}^2} l_0(\xi) l_0(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) \\ &= 1 + \frac{1}{2} \min_{(\xi, \eta) \in \hat{K}^2} l_1(\xi) l_1(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta) \quad \text{for } p \geq 2 \end{aligned}$$

Theorem

If the partition $a = x_0 < x_1 < \dots < x_M = b$ of the domain $\Omega = (a, b)$ satisfies the condition

$$\frac{x_i - x_{i-1}}{b - a} \leq H_{\text{rel}}^*(p_i) \quad \text{for all } i = 1, 2, \dots, M,$$

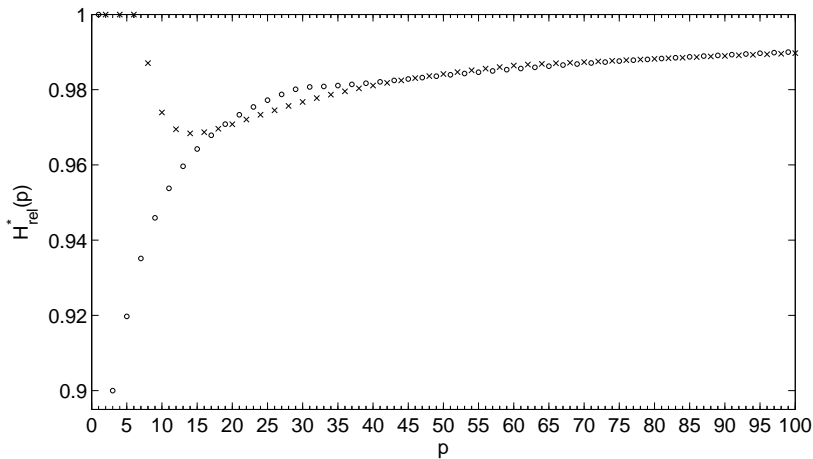
where $p_i \geq 1$ is the polynomial degree assigned to the element $K_i = [x_{i-1}, x_i]$, then the 1D Poisson problem satisfies the discrete maximum principle (i.e., $u_{hp} \geq 0$ in Ω for arbitrary $f \in L^2(\Omega)$ which is nonnegative a.e. in Ω).

Computation of $H_{\text{rel}}^*(p)$

p	$H_{\text{rel}}^*(p)$	p	$H_{\text{rel}}^*(p)$
1	1	11	0.953759
2	1	12	0.969485
3	9/10	13	0.959646
4	1	14	0.968378
5	0.919731	15	0.964221
6	1	16	0.968695
7	0.935127	17	0.967874
8	0.987060	18	0.969629
9	0.945933	19	0.970855
10	0.973952	20	0.970814

$$H_{\text{rel}}^*(p) = 1 + \frac{1}{2} \min_{(\xi, \eta) \in \hat{K}^2} l_0(\xi) l_0(\eta) \sum_{k=2}^p \kappa_k(\xi) \kappa_k(\eta)$$

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Conclusions

DMP for 1D Poisson equation

- ▶ Dirichlet BC – if $H_{\text{rel}} \leq 9/10$.

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Generalization

$$-(au')' = f, \quad a \text{ is piecewise constant.}$$

- ▶ Dirichlet BC – if $\tilde{H}_{\text{rel}} \leq 9/10$

$$\tilde{H}_{\text{rel}} = \frac{\tilde{h}_k}{\sum_{i=1}^M \tilde{h}_i} \quad \tilde{h}_k = \frac{x_k - x_{k-1}}{a_k}$$

- ▶ mixed BC – valid on arbitrary hp -mesh.

Thank you for your attention

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