

Modelling of a Steady Flow in a Cascade with Separate Boundary Conditions for Vorticity and Bernoulli's Pressure on the Outflow

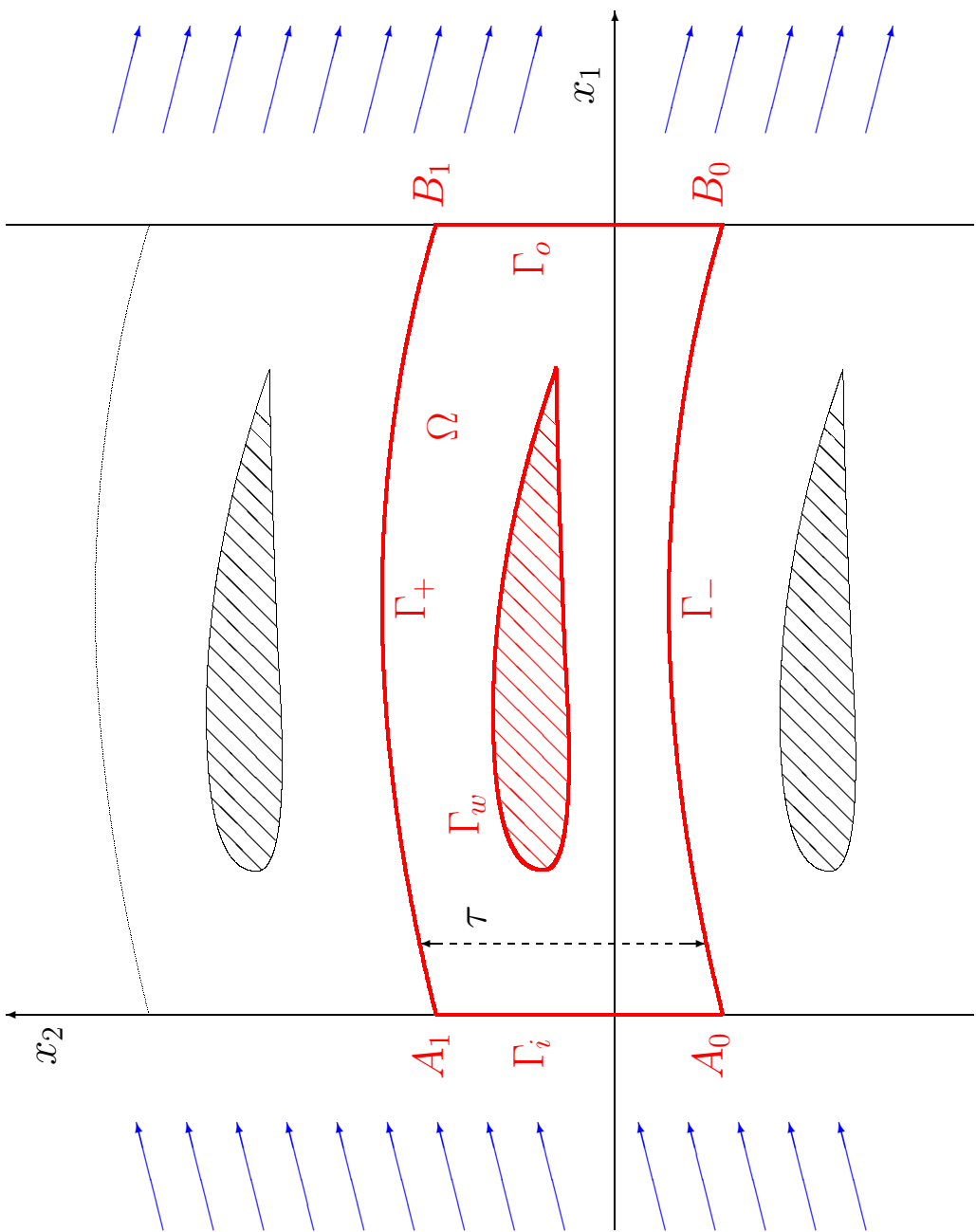
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We consider a flow through a cascade of profiles (2D model of a blade machine). We assume that the fluid is viscous, incompressible and Newtonian, and the flow is 2-dimensional.

1. Used equations

We use the 2-dimensional **Navier–Stokes equations**

$$\begin{aligned}u_1 (\partial_1 u_1) + u_2 (\partial_2 u_1) &= -\partial_1 p + \nu \Delta u_1 + f_1 \\u_1 (\partial_1 u_2) + u_2 (\partial_2 u_2) &= -\partial_2 p + \nu \Delta u_2 + f_2\end{aligned}$$

and the **equation of continuity**

$$\boxed{\operatorname{div} \mathbf{u} = 0} \tag{1}$$

where $\mathbf{u} = (u_1, u_2)$ is the **velocity**.

Using equation (1), the Navier–Stokes equations can also be written in the form

$$\begin{aligned} -u_2 (\partial_1 u_2) + u_2 (\partial_2 u_1) &= -\partial_1 q - \nu \partial_2 (\partial_1 u_2 - \partial_2 u_1) + f_1 \\ u_1 (\partial_1 u_2) - u_1 (\partial_2 u_1) &= -\partial_2 q + \nu \partial_1 (\partial_1 u_2 - \partial_2 u_1) + f_2 \end{aligned}$$

where $q = p + \frac{1}{2} (u_1^2 + u_2^2)$ is the so called **Bernoulli pressure**, or in the equivalent form of one vector equation

$$\omega(\mathbf{u}) \mathbf{u}^\perp = -\nabla q + \nu (-\partial_2, \partial_1) \omega(\mathbf{u}) + \mathbf{f} \quad (2)$$

where $\omega(\mathbf{u}) = \partial_1 u_2 - \partial_2 u_1$ is the **vorticity**, $\mathbf{f} = (f_1, f_2)$ is the **external body force** and

$$\mathbf{u}^\perp = (-u_2, u_1).$$

2. Boundary conditions

The **inhomogeneous Dirichlet condition on the inflow**:

$$\mathbf{u} = \mathbf{g} \quad \text{on } \Gamma_i \quad (3)$$

where \mathbf{g} is a given velocity on Γ_i .

The **conditions of periodicity on Γ_- and Γ_+** :

$$\mathbf{u}(x_1, x_2 + \tau) = \mathbf{u}(x_1, x_2) \quad (4)$$

$$\frac{\partial \mathbf{u}}{\partial \mathbf{n}}(x_1, x_2 + \tau) = -\frac{\partial \mathbf{u}}{\partial \mathbf{n}}(x_1, x_2) \quad (5)$$

for $(x_1, x_2) \in \Gamma_-$

$$q(x_1, x_2 + \tau) = q(x_1, x_2) \quad (6)$$

The **homogeneous Dirichlet condition on the profile**:

$$\mathbf{u} = \mathbf{0} \quad \text{on } \Gamma_w \quad (7)$$

3. The weak formulation

We need the following function spaces:

- $H^1(\Omega)$ (respective $H^1(\Omega)^2$) is the Sobolev space of scalar (respective vector) functions, defined a.e. in Ω , with the norm $\|\cdot\|_1$.
- $H^s(\Gamma_i)^2$ (for $0 < s < 1$) is the Sobolev–Slobodetski space of vector functions, defined a.e. in Γ_i , with the norm $\|\cdot\|_{s;\Gamma_i}$.
- $\mathcal{X} = \{\mathbf{v} \in C^\infty(\bar{\Omega})^2; \mathbf{v} = \mathbf{0} \text{ on } \Gamma_i \cup \Gamma_w, \mathbf{v}(x_1, x_2 + \tau) = \mathbf{v}(x_1, x_2) \forall (x_1, x_2) \in \Gamma_-\}$
- $\mathcal{V} = \{\mathbf{v} \in \mathcal{X}; \operatorname{div} \mathbf{v} = 0 \text{ in } \Omega\}$
- $H \dots$ the closure of \mathcal{V} in $L^2(\Omega)^2$
- $V \dots$ the closure of \mathcal{V} in $H^1(\Omega)^2$

The spaces H and V can be characterized:

H is the space of functions $\mathbf{v} \in L^2(\Omega)^2$ such that

- $\operatorname{div} \mathbf{v} = 0$ in the sense of distributions in Ω ,
- $\mathbf{v} \cdot \mathbf{n} = 0$ in the sense of traces on $\Gamma_i \cup \Gamma_w$,
- $\mathbf{v}(x_1, x_2 + \tau) \cdot \mathbf{n} = -\mathbf{v}(x_1, x_2) \cdot \mathbf{n}$ for $(x_1, x_2) \in \Gamma_-$
in the sense of traces

V is the space of functions $\mathbf{v} \in H^1(\Omega)^2$ such that

- $\operatorname{div} \mathbf{v} = 0$ a.e. in Ω ,
- $\mathbf{v} = \mathbf{0}$ on $\Gamma_i \cup \Gamma_w$,
- $\mathbf{v}(x_1, x_2 + \tau) = \mathbf{v}(x_1, x_2)$ for $(x_1, x_2) \in \Gamma_-$

$$-\nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = \mathbf{f}$$

Now we multiply this equation by an arbitrary test function $\mathbf{v} = (v_1, v_2) \in V$ and integrate in Ω . We get

$$-\int_{\Omega} \nu \Delta \mathbf{u} \cdot \mathbf{v} \, d\mathbf{x} + \int_{\Omega} (\mathbf{u} \cdot \nabla) \mathbf{u} \cdot \mathbf{v} \, d\mathbf{x} + \int_{\Omega} \nabla p \cdot \mathbf{v} \, d\mathbf{x} = \int_{\Omega} \mathbf{f} \cdot \mathbf{v} \, d\mathbf{x}$$

we apply Green's theorem

$$\begin{aligned} & \nu \int_{\Omega} \sum_{i,j=1}^2 \frac{\partial u_i}{\partial x_j} \frac{\partial v_i}{\partial x_j} \, d\mathbf{x} - \nu \int_{\partial\Omega} \frac{\partial \mathbf{u}}{\partial \mathbf{n}} \cdot \mathbf{v} \, dS + \int_{\Omega} \sum_{i,j=1}^2 \frac{\partial u_i}{\partial x_j} v_i \, d\mathbf{x} \\ & - \int_{\Omega} p \operatorname{div} \cdot \mathbf{v} \, d\mathbf{x} + \int_{\partial\Omega} p \cdot \mathbf{v} \, \mathbf{n} \, dS = \int_{\Omega} \mathbf{f} \cdot \mathbf{v} \, d\mathbf{x} \end{aligned}$$

because $\operatorname{div} \mathbf{v} = 0$ for all $\mathbf{v} \in V$, we have

$$-\int_{\Omega} p \operatorname{div} \mathbf{v} \, d\mathbf{x} = 0$$

using fact that $\mathbf{v}|_{\Gamma_i \cup \Gamma_w}$, conditions of periodicity and relation $\mathbf{n}(x_1, x_2) = -\mathbf{n}(x_1, x_2 + \tau)$ for $(x_1, x_2) \in \Gamma_-$, only this term remain on boundary

$$\int_{\Gamma_0} \left(-\nu \frac{\partial \mathbf{u}}{\partial \mathbf{n}} + p \mathbf{n} \right) \cdot \mathbf{v} \, dS$$

For our form of Navier–Stokes equations we obtain this term in boundary integral:

$$\int_{\Gamma_o} \omega(\mathbf{u}) v_2 - q v_1 \, dS$$

for all $\mathbf{v} \in V$. Let us take $\mathbf{v} = (v_1, 0)$, we have

$$-q v_1 + (h_1) = 0$$

and, using this and an arbitrary function \mathbf{v} ,

$$\omega(\mathbf{u}) v_2 + (h_2) = 0$$

From these equations our conditions on Γ_o follows in this way

$$q = h_1 \quad - \omega(\mathbf{u}) = h_2$$

The **condition used on the outflow** Γ_o arises from the weak formulation of the problem, similarly as the so called “do nothing” condition. If the weak solution \mathbf{u} is “smooth enough” then there exists a scalar function q such that \mathbf{u} , q is a classical solution of the equations (1), (2) and \mathbf{u} , q satisfy

$$q = h_1$$

$$-\omega(\mathbf{u}) = h_2$$

$$\text{on } \Gamma_o$$

$$(8)$$

where $\mathbf{h} = (h_1, h_2)$ is a given function on Γ_o .

3.1 Formal derivation of the weak formulation

In order to derive formally the weak formulation of the problem, we multiply equation (2) by an arbitrary test function $\mathbf{v} = (v_1, v_2) \in V$ and integrate in Ω . We obtain

$$\begin{aligned} & \int_{\Omega} \omega(\mathbf{u}) \mathbf{u}^{\perp} \cdot \mathbf{v} \, d\mathbf{x} \\ &= - \int_{\Omega} \nabla q \cdot \mathbf{v} \, d\mathbf{x} + \nu \int_{\Omega} \nabla^{\perp} \omega(\mathbf{u}) \cdot \mathbf{v} \, d\mathbf{x} + \int_{\Omega} \mathbf{f} \cdot \mathbf{v} \, d\mathbf{x}. \end{aligned}$$

Where $\nabla^{\perp} = (-\partial_2, \partial_1)$. If we apply Green's theorem and use all the boundary conditions (3)–(8), we finally arrive at the equation

$$\begin{aligned} & \int_{\Omega} \omega(\mathbf{u}) \mathbf{u}^{\perp} \cdot \mathbf{v} \, d\mathbf{x} + \nu \int_{\Omega} \omega(\mathbf{u}) \cdot \omega(\mathbf{v}) \, d\mathbf{x} \\ &= \int_{\Omega} \mathbf{f} \cdot \mathbf{v} \, d\mathbf{x} - \int_{\Gamma_0} \mathbf{h} \cdot \mathbf{v} \, dS. \end{aligned}$$

This integral equation can be written in a simple form

$$a(\mathbf{u}, \mathbf{v}) = (\mathbf{f}, \mathbf{v})_0 + b(\mathbf{h}, \mathbf{v})$$

where $(\cdot, \cdot)_0$ denotes the scalar product in $L^2(\Omega)$ or in $L^2(\Omega)^2$ and

$$a_1(\mathbf{u}, \mathbf{v}) = (\omega(\mathbf{u}), \omega(\mathbf{v}))_0,$$

$$a_2(\mathbf{u}, \mathbf{v}, \mathbf{w}) = \int_{\Omega} \omega(\mathbf{u}) \mathbf{v}^\perp \cdot \mathbf{w} \, d\mathbf{x},$$

$$a(\mathbf{u}, \mathbf{v}) = a_1(\mathbf{u}, \mathbf{v}) + a_2(\mathbf{u}, \mathbf{u}, \mathbf{v}),$$

$$b(\mathbf{h}, \mathbf{v}) = - \int_{\Gamma_o} \mathbf{h} \cdot \mathbf{v} \, dS.$$

All these forms are defined for $\mathbf{u}, \mathbf{v}, \mathbf{w} \in H^1(\Omega)^2$, $\mathbf{f} \in L^2(\Omega)^2$ and $\mathbf{h} \in L^2(\Gamma_o)^2$.

3.2 The weak formulation of the problem (1)–(8)

Definition 1. Let $\mathbf{g} \in H^s(\Gamma_i)^2$ (for some $s \in (\frac{1}{2}, 1]$) satisfy the condition $\mathbf{g}(A_1) = \mathbf{g}(A_0)$. Let $\mathbf{f} \in L^2(\Omega)^2$ and $\mathbf{h} \in L^2(\Gamma_o)^2$. The **weak solution** of the problem (1)–(8) is a vector function $\mathbf{u} \in H^1(\Omega)^2$ which satisfies the identity

$$a(\mathbf{u}, \mathbf{v}) = (\mathbf{f}, \mathbf{v})_0 + b(\mathbf{h}, \mathbf{v}) \quad (9)$$

for all test functions $\mathbf{v} \in V$, the equation of continuity (3) a.e. in Ω and the boundary conditions (3)–(8) (on Γ_i , Γ_w , Γ_- and Γ_+) in the sense of traces.

3.3 Existence of a weak solution

Lemma 1. *There exists a constant $c_1 > 0$ independent of \mathbf{g} and a divergence-free extension $\mathbf{g}^* \in H^1(\Omega)^2$ of function \mathbf{g} from Γ_i onto Ω such that $\mathbf{g}^* = \mathbf{0}$ on Γ_w , \mathbf{g}^* satisfies the condition of periodicity*

$$\mathbf{g}^*(x_1, x_2 + \tau) = \mathbf{g}^*(x_1, x_2) \quad \text{for } (x_1, x_2) \in \Gamma_- \quad (10)$$

and the estimate

$$\|\mathbf{g}^*\|_1 \leq c_1 \|\mathbf{g}\|_{s; \Gamma_i}. \quad (11)$$

Now we construct the weak solution \mathbf{u} in the form $\mathbf{u} = \mathbf{g}^* + \mathbf{z}$ where $\mathbf{z} \in V$ is a new unknown function. Substituting $\mathbf{u} = \mathbf{g}^* + \mathbf{z}$ into equation (9), we get the following problem: *Find a function $\mathbf{z} \in V$ such that it satisfies the equation*

$$a(\mathbf{g}^* + \mathbf{z}, \mathbf{v}) = (\mathbf{f}, \mathbf{v})_0 + b(\mathbf{h}, \mathbf{v}) \quad (12)$$

for all $\mathbf{v} \in V$.

Theorem (on the existence of a weak solution). *There exists $\varepsilon > 0$ such that if $\|\mathbf{g}\|_{s;\Gamma_i} < \varepsilon$ then there exists a solution \mathbf{u} of the problem defined in Definition 1.*

3.4 Principle of the proof

We use the Galerkin method and we construct approximations \mathbf{z}_n in n -dimensional subspaces V_n of V . A fundamental property which guarantees the existence of the approximations is the **coerciveness of the bilinear form a in space V** . Applying successively estimates of the forms a_1 , a_2 and b , we can derive the next lemma.

Lemma 2. *There exist positive constants c_2 , c_3 and c_4 such that*

$$\begin{aligned} a(\mathbf{g}^* + \mathbf{z}, \mathbf{z}) &\geq \|\nabla \mathbf{z}\|_0 \left(\nu \|\nabla \mathbf{z}\|_0 - \nu c_2 \|\mathbf{g}\|_{s;\Gamma_i} \right. \\ &\quad \left. - c_3 \|\mathbf{g}\|_{s;\Gamma_i}^2 - c_4 \|\mathbf{g}\|_{s;\Gamma_i} \|\nabla \mathbf{z}\|_0 \right) \end{aligned} \quad (13)$$

for all $\mathbf{z} \in V$.

Now the coerciveness of the form a follows from (13) and the assumption on a sufficient smallness of $\|\mathbf{g}\|_{s;\Gamma_i}$.

Advantage of the usage of Bernoulli's pressure:

As a part of necessary estimates which lead to (13), we need to estimate the term

$$a_2(\mathbf{z}, \mathbf{z}, \mathbf{v}) = \int_{\Omega} \omega(\mathbf{z}) \mathbf{z}^{\perp} \cdot \mathbf{v} \, d\mathbf{x}$$

in the case when $\mathbf{v} = \mathbf{z}$. However, the integrand equals zero a.e. in Ω in this case because $\omega(\mathbf{z}) \mathbf{z}^{\perp} \cdot \mathbf{z} = 0$.