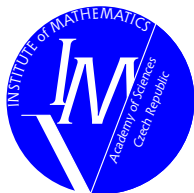


A posteriori error estimates in the finite element method

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Poisson problem



- ▶ Classical formulation: find $u \in C^2(\Omega) \cap C(\bar{\Omega})$:

$$-\Delta u = f \quad \text{in } \Omega \quad u = 0 \quad \text{on } \partial\Omega$$

Poisson problem



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$$u \in H_0^1(\Omega) : \int_{\Omega} \nabla u \cdot \nabla v \, dx = \int_{\Omega} f v \, dx \quad \forall v \in H_0^1(\Omega)$$

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- ▶ Galerkin method $V_h \subset H_0^1(\Omega) \quad \dim V_h < \infty$

$$u_h \in V_h : \int_{\Omega} \nabla u_h \cdot \nabla v_h \, dx = \int_{\Omega} f v_h \, dx \quad \forall v_h \in V_h \quad \Leftrightarrow \quad Ay = F$$

$$u_h(x) = \sum_{j=1}^N y_j \varphi_j(x) \quad \sum_{j=1}^N y_j \underbrace{\int_{\Omega} \nabla \varphi_j \cdot \nabla \varphi_i \, dx}_{A_{ij}} = \underbrace{\int_{\Omega} f \varphi_i \, dx}_{F_i}$$

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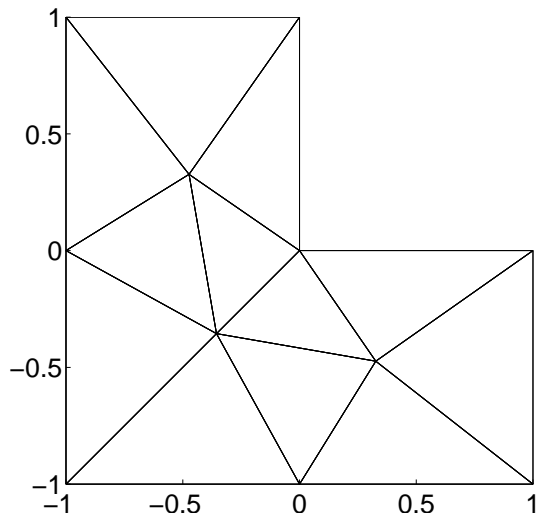
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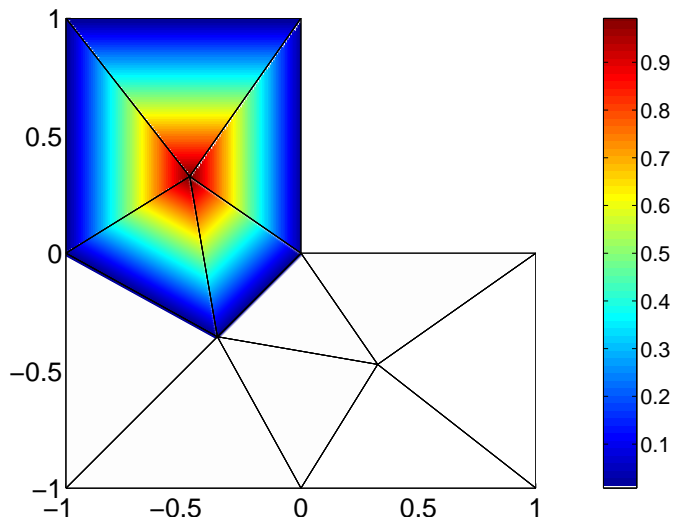
- ▶ FEM

$$V_h = \{v_h \in H_0^1(\Omega) : v_h|_K \in P^1(K) \quad \forall K \in \mathcal{T}_h\}$$

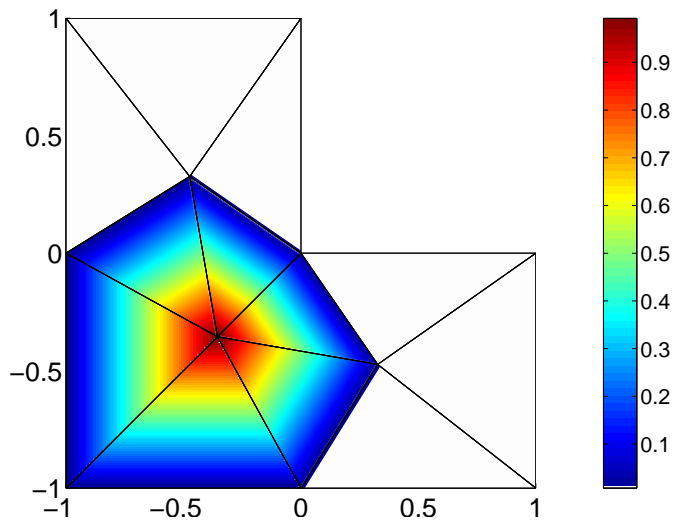
$\varphi_1, \dots, \varphi_N \dots$ FEM basis functions $\varphi_i(x_j) = \delta_{ij}$

Mesh 1

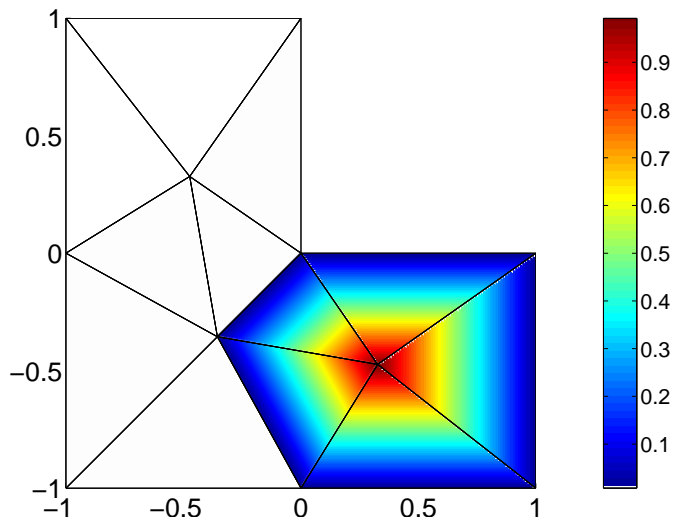




FEM



FEM



A priori error estimates



► Discretization error: $e = u - u_h$

► Energy norm: $\|u\|^2 = \int_{\Omega} \nabla u \cdot \nabla u \, dx = |u|_{H^1(\Omega)}^2$

►

$$u \in H^2(\Omega) \quad \Rightarrow \quad \|e\| \leq C h |u|_{H^2(\Omega)}$$

A posteriori error estimates



- ▶ $\|e\| \approx \eta$, where $\eta = \eta(u_h)$
- ▶ Efficient and reliable $C_1\eta \leq \|e\| \leq C_2\eta$
- ▶ Local $\eta^2 = \sum_{K \in \mathcal{T}_h} \eta_K^2$
- ▶ Guaranteed upper (lower) bound $\|e\| \leq \eta$ ($\eta \leq \|e\|$)
- ▶ Asymptotic exactness $\lim_{h \rightarrow 0} \frac{\eta}{\|e\|} = 1$

A posteriori error estimates



$$\underbrace{\int_{\Omega} \nabla u \cdot \nabla v \, dx - \int_{\Omega} \nabla u_h \cdot \nabla v \, dx}_{\int_{\Omega} \nabla e \cdot \nabla v \, dx} = \underbrace{\int_{\Omega} f v \, dx - \int_{\Omega} \nabla u_h \cdot \nabla v \, dx}_{\mathcal{R}(v)}$$

- ▶ Explicit residual $\|e\| = \|\mathcal{R}\|_*$

A posteriori error estimates



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► Explicit residual $\|e\| = \|\mathcal{R}\|_*$

► Implicit residual

$$e_K \in H^1(K) : \int_K \nabla e_K \cdot \nabla v \, dx = \mathcal{R}_K(v) \quad \forall v \in H^1(K)$$

A posteriori error estimates



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► Hierarchical $W_h = V_h \oplus \hat{V}_h \quad \eta \in \hat{V}_h$

A posteriori error estimates



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► Error majorant (complementary energy)

$$\|e\|^2 \leq \|\nabla u_h - y^*\|_0^2 + C_{\Omega}^2 \|f + \operatorname{div} y^*\|_0^2 \quad \forall y^* \in \mathbf{H}(\operatorname{div}, \Omega)$$

A posteriori error estimates



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► Quantity of interest $Q(e) \approx \eta$



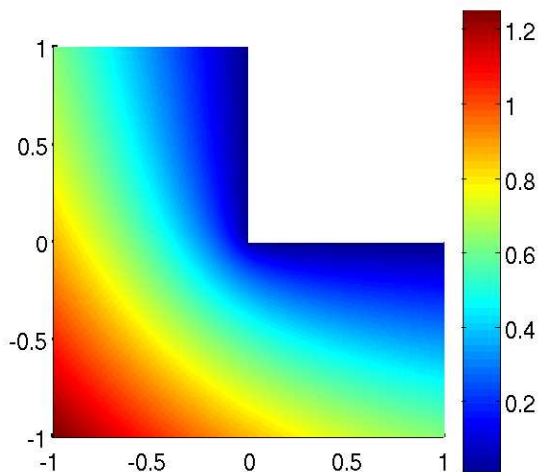
1. Construct the initial mesh \mathcal{T}_h .
2. Find u_h on \mathcal{T}_h .
3. Compute η_K for all $K \in \mathcal{T}_h$.
4. If $\sum_{K \in \mathcal{T}_h} \eta_K^2 \leq \text{TOL}^2 \Rightarrow \text{STOP}$.
5. If $\eta_K \geq \Theta \eta_{K, \max} \Rightarrow \text{mark } K$. $0 < \Theta < 1$
6. Refine marked elements and build the new mesh \mathcal{T}_h .
7. GO TO 2.

Example



$$\begin{aligned} -\Delta u &= 0 && \text{in } \Omega \\ u &= g_D && \text{on } \partial\Omega \end{aligned}$$

$$u = r^{\frac{2}{3}} \sin \frac{2\theta - \pi}{3}$$

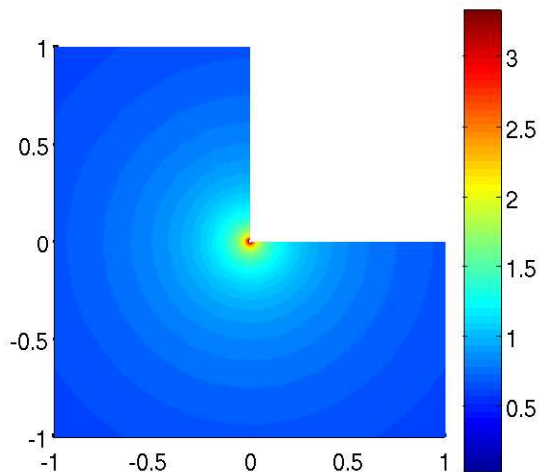


Example

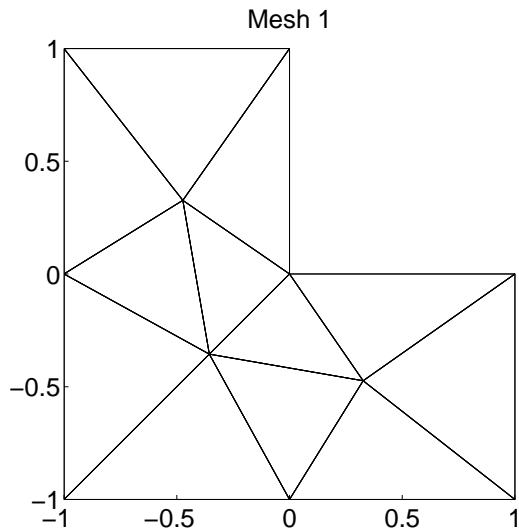


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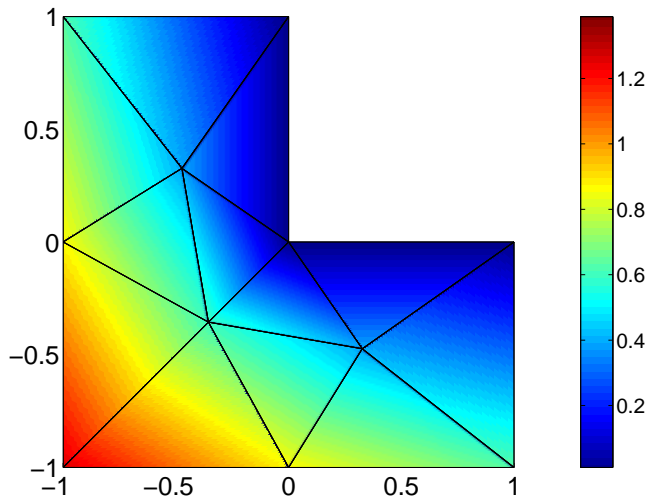
Adaptive algorithm



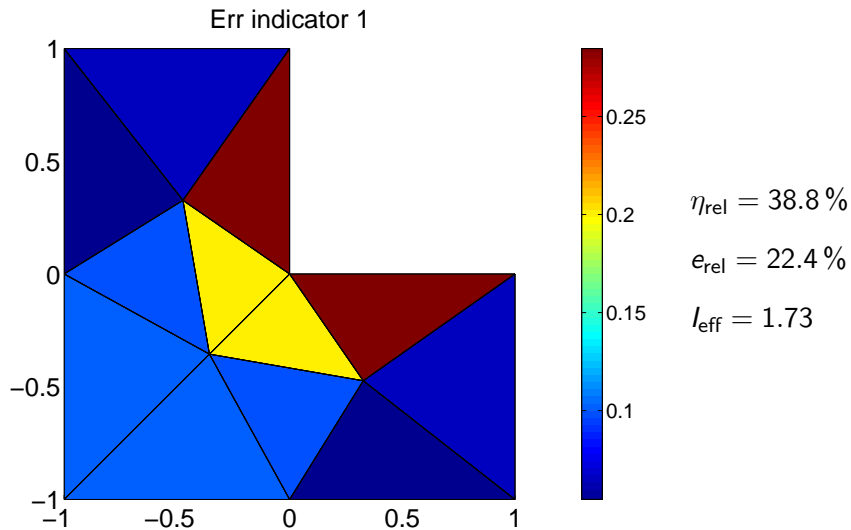
Adaptive algorithm



FEM solution 1



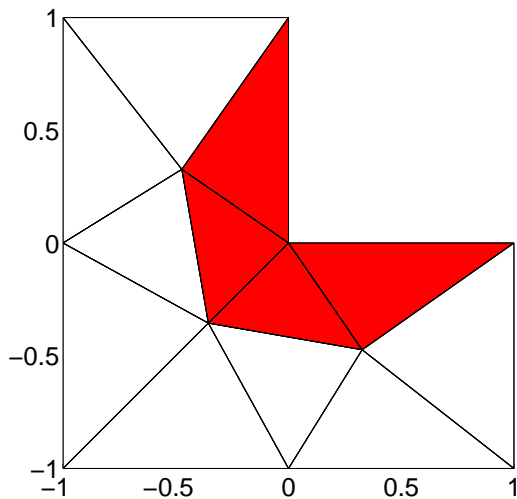
Adaptive algorithm



Adaptive algorithm



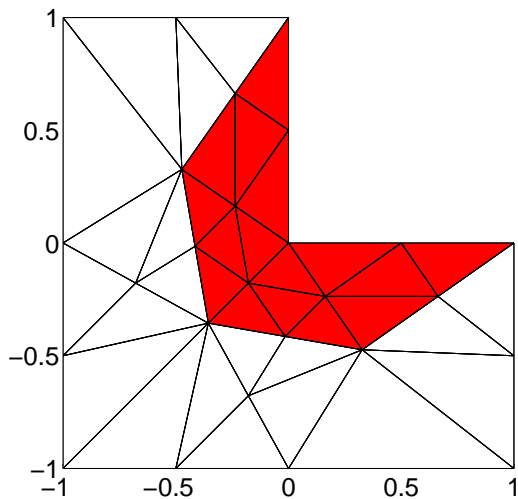
Marked elements 1



Adaptive algorithm



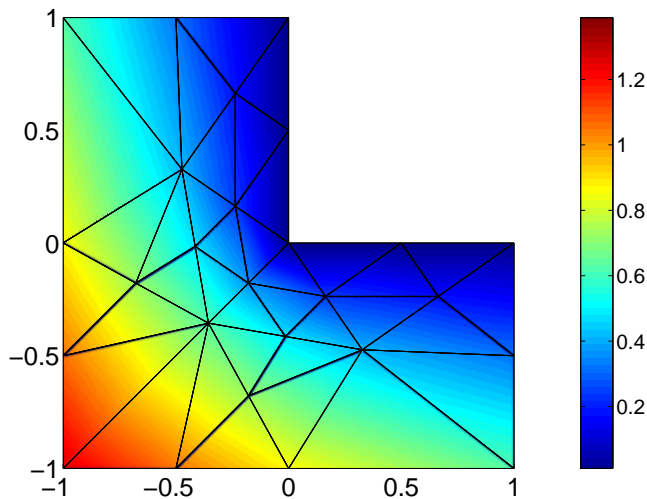
Refined mesh 1



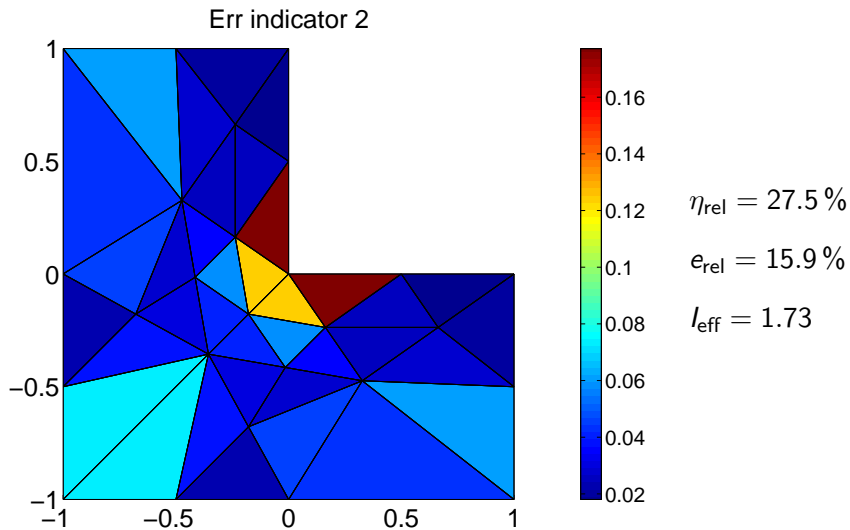
Adaptive algorithm



FEM solution 2



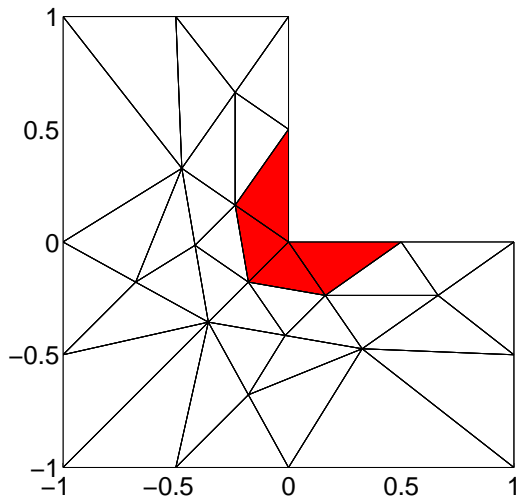
Adaptive algorithm



Adaptive algorithm



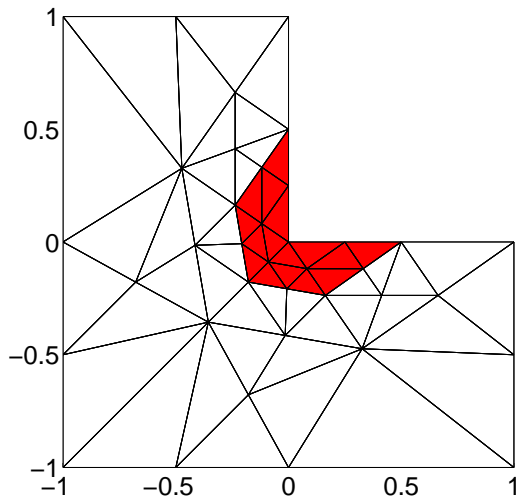
Marked elements 2



Adaptive algorithm



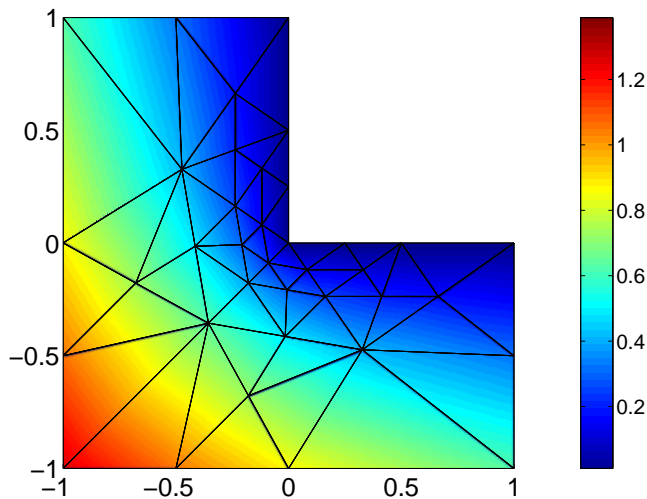
Refined mesh 2



Adaptive algorithm



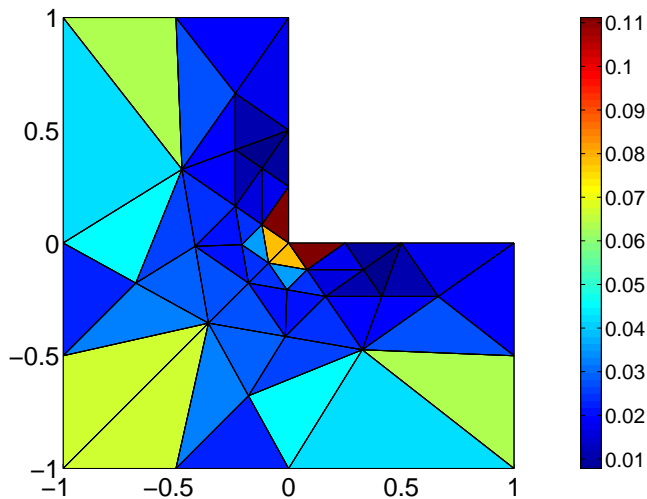
FEM solution 3



Adaptive algorithm



Err indicator 3



$$\eta_{\text{rel}} = 20.9\%$$

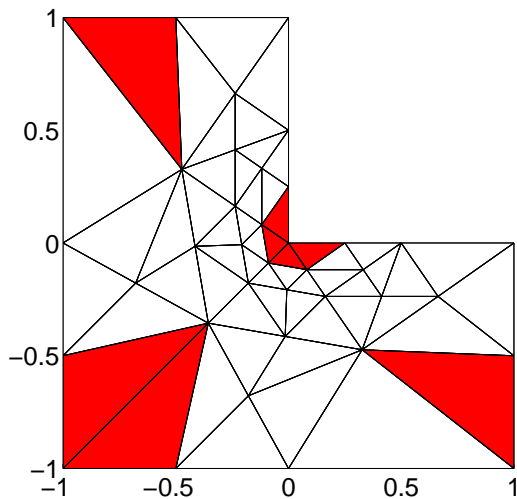
$$e_{\text{rel}} = 12.7\%$$

$$l_{\text{eff}} = 1.65$$

Adaptive algorithm



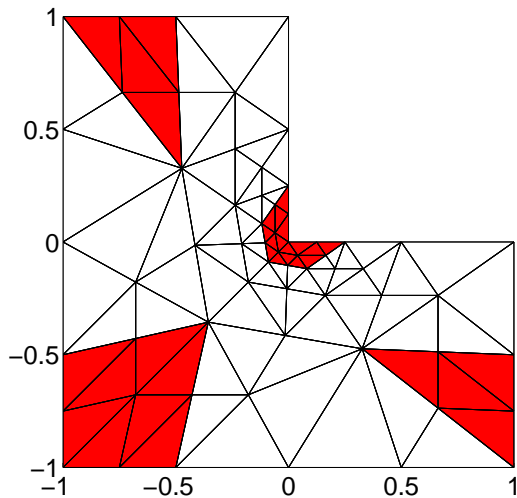
Marked elements 3



Adaptive algorithm



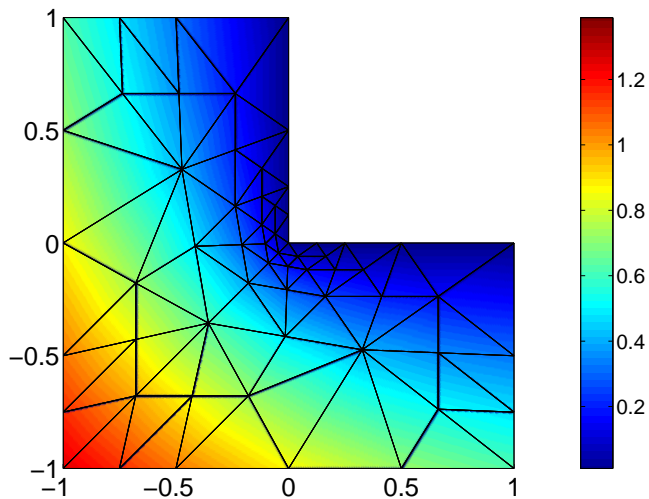
Refined mesh 3



Adaptive algorithm



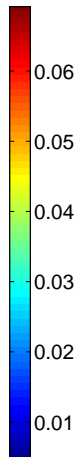
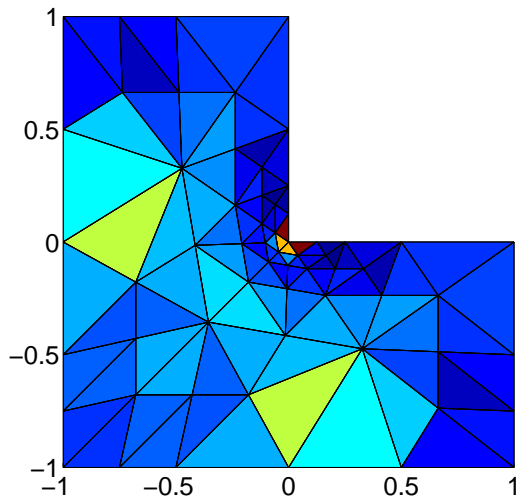
FEM solution 4



Adaptive algorithm



Err indicator 4



$$\eta_{\text{rel}} = 15.4 \%$$

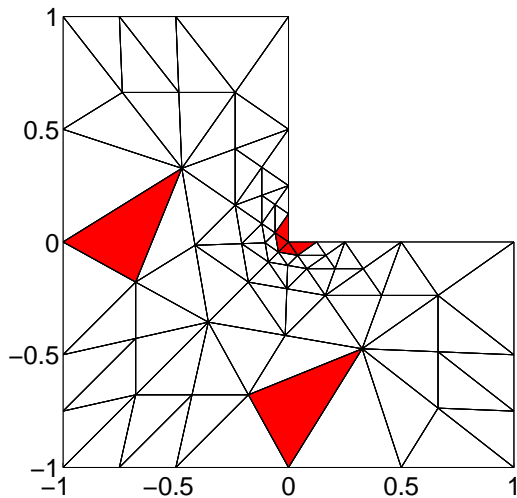
$$e_{\text{rel}} = 9.55 \%$$

$$l_{\text{eff}} = 1.61$$

Adaptive algorithm



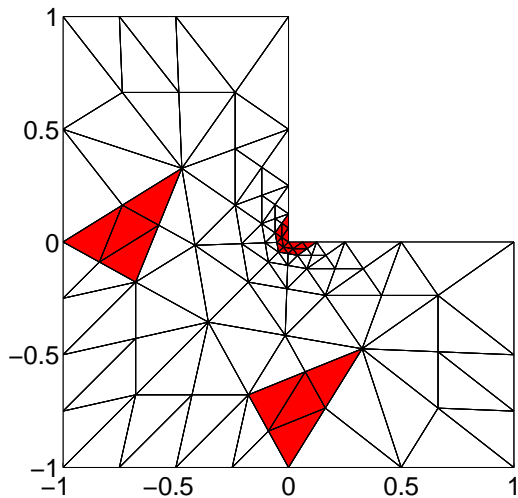
Marked elements 4



Adaptive algorithm



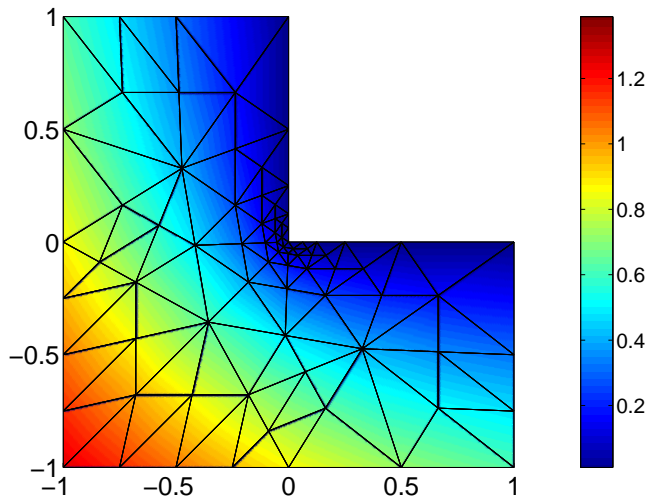
Refined mesh 4



Adaptive algorithm



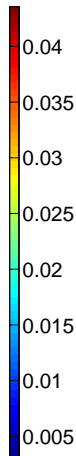
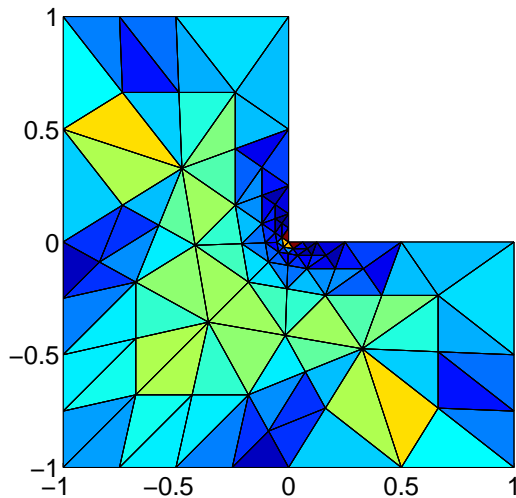
FEM solution 5



Adaptive algorithm



Err indicator 5

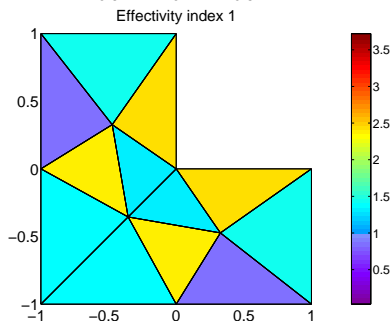
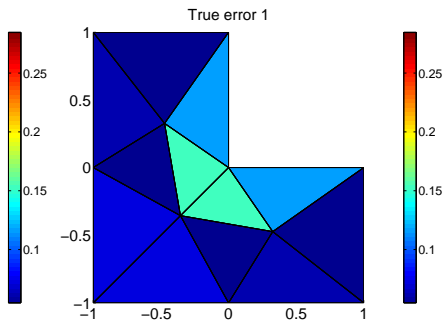
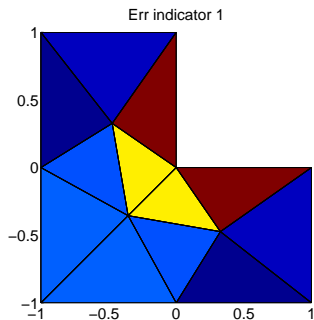


$$\eta_{\text{rel}} = 13.4\%$$

$$e_{\text{rel}} = 8.32\%$$

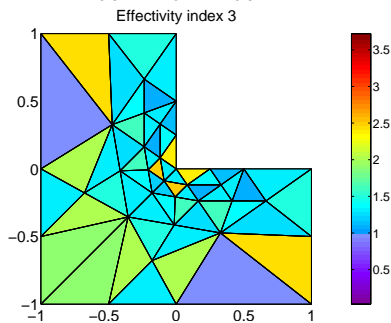
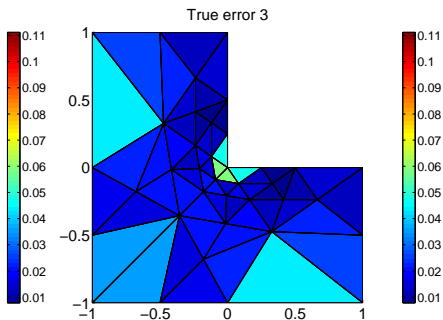
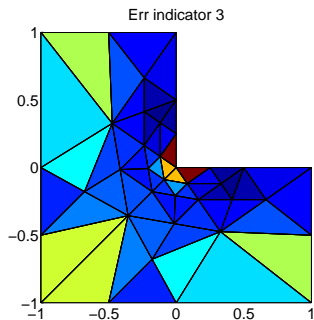
$$l_{\text{eff}} = 1.61$$

Effectivity index



$$I_{\text{eff}} = \frac{\eta}{\|e\|} = 1.73$$

Effectivity index



$$I_{\text{eff}} = \frac{\eta}{\|e\|} = 1.65$$



$$\begin{aligned} -\Delta u + \kappa^2 u &= f \quad \text{in } \Omega \subset \mathbb{R}^2 \\ u &= 0 \quad \text{on } \partial\Omega \end{aligned}$$

$$\|e\|^2 \leq \sum_{K \in \mathcal{T}_h} \underbrace{\left(\left\| \frac{1}{\kappa} (r + \operatorname{div} \sigma_K) \right\|_{0,K}^2 + \|\sigma_K\|_{0,K}^2 \right)}_{\eta_K^2}$$

- ▶ $r = f + \Delta u_h - \kappa^2 u_h$
- ▶ $\sigma_K \in \mathbf{H}(\operatorname{div}, K)$
- ▶ $\sigma_K \cdot n_K = g_K - \frac{\partial u_h}{\partial n_K} \quad \text{on } \partial K$
- ▶ $g_K \approx \frac{\partial u}{\partial n_K} \quad \text{on } \partial K$

Thank you for your attention

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