On the Continuous Dependence on a Parameter of Solutions of IVP's for Linear GDE's

Milan Tvrdý *

Mathematical Institute Academy of Sciences of the Czech Republic 115 67 PRAHA 1, Žitná 25, Czech Republic (e-mail: tvrdy@math.cas.cz)

Abstract. In the contribution the continuous dependence of solutions to linear generalized differential equations (GDE's) of the form

$$x(t) = x(0) + \int_0^t d[A_k(s)]x(s), \quad t \in [0, 1]$$

on a parameter $k \in \mathbf{N}$ is discussed.

Keywords. Generalized linear differential equation, correctness, continuous dependence on a parameter, Perron–Stieltjes integral, Kurzweil–Henstock integral.

AMS Subject Classification. 34A37, 45A05, 34A30.

1. Introduction

Throughout the paper **N** stands for the set of positive integers. Furthermore, $\mathbf{R}^{n \times m}$ denotes the space of real $n \times m$ -matrices, $\mathbf{R}^n = \mathbf{R}^{n \times 1}$, $\mathbf{R}^1 = \mathbf{R}$. For a given $n \times m$ -matrix $A \in \mathbf{R}^{n \times m}$, by |A| we denote its norm,

$$|A| = \max_{i=1,\dots,n} \sum_{j=1}^{m} |a_{i,j}|,$$

and det A is its determinant. The symbols I and 0 stand respectively for the identity and the zero matrix of the proper type.

^{*}Supported by the grant No. 201/97/0218 of the Grant Agency of the Czech Republic

As usual, by [0,1] and (0,1) we denote the corresponding closed and open intervals, respectively. Furthermore, [0,1) and (0,1] are the corresponding half-open intervals.

The space of all functions $F : [0, 1] \to \mathbf{R}^{n \times m}$ of bounded variation on [0, 1] is denoted by $\mathbf{BV}^{n \times m}$. It is well known that $\mathbf{BV}^{n \times m}$ equipped with the norm

$$F \in \mathbf{BV}^{n \times m} \to ||F||_{\mathbf{BV}} = |F(0)| + \operatorname{var}_{0}^{1}F$$

is a Banach space. For a given $F \in \mathbf{BV}^{n \times m}$, we denote

$$F(t-) = \lim_{\tau \to t-} F(\tau) \text{ and } \Delta^{-}F(t) = F(t) - F(t-) \text{ for } t \in (0,1],$$

$$F(t+) = \lim_{\tau \to t+} F(\tau) \text{ and } \Delta^{+}F(t) = F(t+) - F(t) \text{ for } t \in [0,1),$$

$$F(0-) = F(0), \Delta^{-}F(0) = 0, F(1+) = F(1), \Delta^{+}F(1) = 0.$$

As usual, the space of $n \times m$ -matrix valued functions continuous on [0, 1] is denoted by $\mathbf{C}^{n \times m}$ and the space of $n \times m$ -matrix valued functions Lebesgue integrable on [0, 1] is denoted by $\mathbf{L}_1^{n \times m}$. Instead of $\mathbf{BV}^{n \times 1}$ or $\mathbf{C}^{n \times 1}$ or $\mathbf{L}_1^{n \times 1}$ we write \mathbf{BV}^n or \mathbf{C}^n or \mathbf{L}_1^n , respectively. For given $F \in \mathbf{L}_1^{n \times m}$ and $G \in \mathbf{C}^{n \times m}$, we denote

$$||F||_{\mathbf{L}_1} = \int_0^1 |F(t)| \mathrm{d}t$$
 and $||G|| = \sup_{t \in [0,1]} |G(t)|.$

The integrals are considered in the *Perron-Stieltjes* sense. We work with the equivalent summation definition due to J. Kurzweil (cf. [5]) which is now usually called the *Kurzweil* - *Henstock integral* or the *gauge integral*.

Let $P_k \in \mathbf{L}_1^{n \times n}$ for $k \in \mathbf{N} \cup \{0\}$ and let $X_k \in \mathbf{AC}^{n \times n}$ be the corresponding fundamental matrices, i.e.

$$X_k(t) = I + \int_0^t P_k(s) X_k(s) ds$$
 on $[0, 1]$ for $k \in \mathbb{N} \cup \{0\}$.

The following two assertions are relatively representative examples of theorems on the continuous dependence of solutions of ordinary differential equations on a parameter.

1.1. Theorem. If

$$\lim_{k \to \infty} \int_0^1 |P_k(s) - P_0(s)| \mathrm{d}s = 0,$$

then

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad uniformly \ on \ [0,1].$$

1.2. Theorem. (Kurzweil & Vorel, [6]) Let there exist $m \in \mathbf{L}_1^1$ such that

(1.1)
$$|P_k(t)| \le m(t) \quad a.e. \text{ on } [0,1] \quad for \ all \ k \in \mathbf{N}$$

 $and \ let$

(1.2)
$$\lim_{k \to \infty} \int_0^t P_k(s) \mathrm{d}s = \int_0^t P_0(s) \mathrm{d}s \quad uniformly \ on \ [0,1].$$

Then

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad uniformly \ on \ [0,1]$$

1.3. Remark. For $t \in [0, 1]$ and $k \in \mathbb{N} \cup \{0\}$ denote

$$A_k(t) = \int_0^t P_k(s) \mathrm{d}s.$$

Then the assumptions of Theorem 1.2 may be reformulated for A_k as follows:

(1.3)
$$A_k \in \mathbf{AC}^{n \times n} \quad \text{for all} \ k \in \mathbf{N} \cup \{0\},$$

(1.4)
$$\sup_{k\in\mathbf{N}} \|A_k'\|_{\mathbf{L}_1} < \infty,$$

(1.5)
$$\lim_{k \to \infty} A_k(t) = A_0(t) \quad \text{uniformly on } [0, 1].$$

Besides, the assumption (1.1) means that there exists a nondecreasing function $h_0 \in \mathbf{AC}$ such that

$$|A_k(t_2) - A_k(t_1)| \le |h_0(t_2) - h_0(t_1)|$$
 for all $t_1, t_2 \in [0, 1].$

In fact, we may put

$$h_0(t) = \int_0^t m(s) ds$$
 on $[0, 1].$

2. Linear GDE's - a survey of known results

The following basic existence result for linear generalized differential equations of the form

$$x(t) = \widetilde{x} + \int_0^t \mathbf{d}[A(s)]x(s), \quad t \in [0, 1]$$

may be found e.g. in [9] (cf. Theorem III.1.4) or in [8] (cf. Theorem 6.13).

2.1. Theorem. Let $A \in \mathbf{BV}^{n \times n}$ be such that

(2.1)
$$\det \left[\mathbf{I} - \Delta^{-} A(t) \right] \neq 0 \quad for \ all \ t \in (0, 1].$$

Then there exists a unique $X \in \mathbf{BV}^{n \times n}$ such that

(2.2)
$$X(t) = \mathbf{I} + \int_0^t \mathbf{d}[A(s)]X(s) \quad on \quad [0,1].$$

2.2. Definition. For a given $A \in \mathbf{BV}^{n \times n}$, the $n \times n$ -matrix valued function $X \in \mathbf{BV}^{n \times n}$ such that (2.2) holds is called the *fundamental matrix corresponding to A*.

When restricted to the linear case, Theorem 8.8 from [8] modifies to

2.3. Theorem. Let $A_0 \in \mathbf{BV}^{n \times n}$ satisfy (2.1) and let X_0 be the corresponding fundamental matrix. Let $A_k \in \mathbf{BV}^{n \times n}$, $k \in \mathbf{N}$, and scalar nondecreasing and left-continuous on (0, 1] functions h_k , $k \in \mathbf{N} \cup \{0\}$, be given such that h_0 is continuous on [0, 1] and

(2.3)
$$\lim_{k \to \infty} A_k(t) = A_0(t) \quad on \ [0,1],$$

(2.4)
$$|A_k(t_2) - A_k(t_1)| \le |h_k(t_2) - h_k(t_1)|$$

for all $t_1, t_2 \in [0, 1]$ and $k \in \mathbf{N} \cup \{0\},$

(2.5)
$$\limsup_{k \to \infty} \left[h_k(t_2) - h_k(t_1) \right] \le h_0(t_2) - h_0(t_1)$$

whenever $0 \le t_1 \le t_2 \le 1$.

Then for any $k \in \mathbf{N}$ sufficiently large there exists a fundamental matrix X_k corresponding to A_k and

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad uniformly \ on \ [0,1].$$

2.4. Lemma. Under the assumptions of Theorem 2.3 we have

(2.6)
$$\sup_{k \in \mathbf{N}} \operatorname{var}_{0}^{1} A_{k} < \infty$$

and

(2.7)
$$\lim_{k \to \infty} \left[A_k(t) - A_k(0) \right] = A_0(t) - A_0(0) \quad uniformly \ on \ [0,1].$$

*Proof.*¹ i) By (2.5) there is $k_0 \in \mathbf{N}$ such that

$$h_k(1) - h_k(0) \le h_0(1) - h_0(0) + 1$$
 for all $k \ge k_0$.

Hence for any $k \in \mathbf{N}$ we have

$$\operatorname{var}_{0}^{1}A_{k} \leq \alpha_{0} = \max\left(\left\{\operatorname{var}_{0}^{1}A_{k}; k \leq k_{0}\right\} \cup \left\{h_{0}(1) - h_{0}(0) + 1\right\}\right) < \infty.$$

Thus we conclude that (2.6) is true.

ii) Suppose that

(2.8)
$$\lim_{k \to \infty} A_k(t) = A_0(t) \quad \text{uniformly on } [0,1]$$

is not valid. Then there is $\tilde{\varepsilon} > 0$ such that for any $\ell \in \mathbf{N}$ there exist $m_{\ell} \ge \ell$ and $t_{\ell} \in [0, 1]$ such that

(2.9)
$$|A_{m_{\ell}}(t_{\ell}) - A_0(t_{\ell})| \ge \tilde{\varepsilon}.$$

We may assume that $m_{\ell+1} > m_{\ell}$ for any $\ell \in \mathbf{N}$ and

(2.10)
$$\lim_{\ell \to \infty} t_{\ell} = t_0 \in [0, 1].$$

Let $t_0 \in (0, 1)$ and let an arbitrary $\varepsilon > 0$ be given. Since h_0 is continuous, we may choose $\eta > 0$ in such a way that $t_0 - \eta, t_0 + \eta \in [0, 1]$ and

(2.11)
$$h_0(t_0 + \eta) - h_0(t_0 - \eta) < \varepsilon.$$

Furthermore, by (2.3) there is $\ell_1 \in \mathbf{N}$ such that

(2.12)
$$|A_{m_{\ell}}(t_0) - A_0(t_0)| < \varepsilon \quad \text{for all} \quad \ell \ge \ell_1$$

and by (2.4), (2.5) and (2.11) there is $\ell_2 \in \mathbf{N}$, $\ell_2 \geq \ell_1$, such that

(2.13)
$$|A_{m_{\ell}}(\tau_2) - A_{m_{\ell}}(\tau_1)| \le h_0(t_0 + \eta) - h_0(t_0 - \eta) + \varepsilon < 2\varepsilon$$

whenever $\tau_1, \tau_2 \in (t_0 - \eta, t_0 + \eta)$ and $\ell \ge \ell_2$.

The relations (2.3) and (2.13) imply immediately that

(2.14)
$$|A_0(\tau_2) - A_0(\tau_1)| = \lim_{\ell \to \infty} |A_{m_\ell}(\tau_2) - A_{m_\ell}(\tau_1)| \le 2\varepsilon$$

whenever $\tau_1, \tau_2 \in (t_0 - \eta, t_0 + \eta)$.

 $^{^1{\}rm The}$ author is indebted to Ivo Vrkoč for his suggestions which led to a considerable simplification of this proof.

Finally, let $\ell_3 \in \mathbf{N}$ be such that $\ell_3 \geq \ell_2$ and

$$(2.15) |t_{\ell} - t_0| < \eta \quad \text{for all} \quad \ell \ge \ell_3$$

then in virtue of the relations (2.10)-(2.15) we have

$$\begin{aligned} |A_{m_{\ell}}(t_{\ell}) - A_{0}(t_{\ell})| \\ &\leq |A_{m_{\ell}}(t_{\ell}) - A_{m_{\ell}}(t_{0})| + |A_{m_{\ell}}(t_{0}) - A_{0}(t_{0})| + |A_{0}(t_{0}) - A_{0}(t_{\ell})| \\ &\leq 5\varepsilon. \end{aligned}$$

Hence, choosing $\varepsilon < \frac{1}{5}\widetilde{\varepsilon}$, we obtain by (2.9) that

$$\widetilde{\varepsilon} > |A_{m_{\ell}}(t_{\ell}) - A_0(t_{\ell})| \ge \widetilde{\varepsilon}.$$

This being impossible, the relation (2.8) has to be true. The modification of the proof in the cases $t_0 = 0$ or $t_0 = 1$ and the extension of (2.8) to (2.7) is obvious.

Thus, Theorem 2.3 is a special case of the following result due to M. Ashordia (cf.[1]).

2.5. Theorem. Let $A_0 \in \mathbf{BV}^{n \times n}$ satisfy (2.1), let X_0 be the corresponding fundamental matrix and let $\{A_k\}_{k=1}^{\infty} \subset \mathbf{BV}^{n \times n}$ be such that (2.6) and (2.7) hold. Then for any $k \in \mathbf{N}$ sufficiently large there exists a fundamental matrix X_k corresponding to A_k and

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad uniformly \ on \ [0,1].$$

2.6. Remark. Under the assumptions of Theorem 2.5 we obviously have

$$\lim_{k \to \infty} A_k(t-) = A_0(t-) \text{ and } \lim_{k \to \infty} A_k(s+) = A_0(s+)$$

for all $t \in (0, 1]$ and all $s \in [0, 1)$, respectively. Thus Theorem 2.5 cannot cover the case that there is a $t_0 \in (0, 1]$ such that

$$A_k(t_0-) = A_k(t_0)$$
 for all $k \in \mathbf{N}$, while $A_0(t_0-) \neq A_0(t_0)$.

In particular, Theorem 2.5 does not apply to the following simple example.

2.7. Example. Consider the sequence of initial value problems

$$x'_{k} = a'_{k}(t)x_{k}$$
 on $[-1,1], \quad x(-1) = \widetilde{x},$

where

$$a_k(t) = \begin{cases} 0 & \text{if } t \leq \alpha_k, \\ \frac{t - \alpha_k}{\beta_k - \alpha_k} & \text{if } t \in (\alpha_k, \beta_k), \\ 1 & \text{if } t \geq \beta_k; \end{cases}$$

 $\{\alpha_k\}_{k=1}^\infty$ is an arbitrary increasing sequence in [-1,0) such that

$$\lim_{k \to \infty} \alpha_k = 0;$$

 $\{\beta_k\}_{k=1}^\infty$ is an arbitrary decreasing sequence in (0,1] such that

$$\lim_{k \to \infty} \beta_k = 0$$

 $\quad \text{and} \quad$

$$\lim_{k \to \infty} \frac{\alpha_k}{\alpha_k - \beta_k} = \varkappa \in [0, 1).$$

For the corresponding solutions we have

$$x_{k}(t) = \begin{cases} \widetilde{x} & \text{if } t \leq \alpha_{k}, \\ e^{\frac{t-\alpha_{k}}{\beta_{k}-\alpha_{k}}} \widetilde{x} & \text{if } t \in (\alpha_{k}, \beta_{k}), \\ e \widetilde{x} & \text{if } t \geq \beta_{k} \end{cases}$$
$$x_{0}(t) = \lim_{k \to \infty} x_{k}(t) = \begin{cases} \widetilde{x} & \text{if } t < 0, \\ e^{\varkappa} \widetilde{x} & \text{if } t = 0, \\ e \widetilde{x} & \text{if } t > 0, \end{cases}$$

while the unique solution x(t) of the "limit" equation

$$x(t) = \tilde{x} + \int_{-1}^{t} d[a(s)]x(s), \quad t \in [-1, 1],$$

where

$$a(t) = \lim_{k \to \infty} a_k(t) = \begin{cases} 0 & \text{if } t < 0, \\ \varkappa & \text{if } t = 0, \\ 1 & \text{if } t > 0, \end{cases}$$

is given by

$$x(t) = \left\{ \begin{array}{ll} \widetilde{x} & \text{if } t < 0\\ \frac{1}{1-\varkappa} \widetilde{x} & \text{if } t = 0\\ \frac{2-\varkappa}{1-\varkappa} \widetilde{x} & \text{if } t > 0 \end{array} \right\} \neq x_0(t).$$

On the other hand, x_0 is a solution to

$$x_0(t) = \widetilde{x} + \int_{-1}^t d[a_0(t)]x_0(s)$$
 on $[-1, 1],$

where

$$a_0(t) = \begin{cases} 0 & \text{if } t < 0, \\ 1 - e^{-\varkappa} & \text{if } t = 0, \\ (e - 1) e^{-\varkappa} & \text{if } t > 0 \end{cases}$$

and a_k tends to a_0 in the following sense:

- (a) given arbitrary $\alpha \in (-1,0)$ and $\beta \in (0,1)$, $\lim_{k\to\infty} a_k(t) = a_0(t)$ uniformly on $[-1,\alpha]$ and $\lim_{k\to\infty} [a_k(t) a_k(\beta)] = a_0(t) a_0(\beta)$ uniformly on $[\beta, 1]$;
- (b) $\lim_{k\to\infty} a_k(t) = a_0(t) + \widetilde{a_0}(t)$, where

$$\widetilde{a_0}(t) = \begin{cases} 0 & \text{if } t < 0, \\ \varkappa + e^{-\varkappa} - 1 & \text{if } t = 0, \\ 1 - e^{1-\varkappa} + e^{-\varkappa} & \text{if } t > 0; \end{cases}$$

(c) for any $z \in \mathbf{R}$ and $\varepsilon > 0$, there is $\delta > 0$ such that for any $\delta' \in (0, \delta)$ there is $k_0 \in \mathbf{N}$ such that for any $k \ge k_0$ we have $\alpha_k \ge -\delta'$, $\beta_k \le \delta'$ and the relations

$$\left|y_k(0) - y_k(-\delta') - \frac{\Delta^- a_0(0)z}{1 - \Delta^- a_0(0)}\right| < \varepsilon$$

and

$$|z_k(\delta') - z_k(0) - \Delta^+ a_0(0)z| < \varepsilon$$

are satisfied for any solution y_k on $[-\delta', 0]$ of

$$y'_k = a'_k(t)y_k$$
 with $y_k(-\delta') \in (z - \delta, z + \delta)$

and any solution z_k on $[0, \delta']$ of

$$z'_k = a'_k(t)z_k$$
 with $z_k(0) \in (z - \delta, z + \delta)$

In fact, for given $z \in \mathbf{R}$, $\delta' > 0$ and $k \in \mathbf{N}$ such that $\alpha_k \ge -\delta'$ we have

$$y_k(t) = e^{\frac{t-\alpha_k}{\beta_k - \alpha_k}} y_k(-\delta') \quad \text{on} \ [\alpha_k, 0]$$

and thus

$$\begin{aligned} \left| y_k(0) - y_k(-\delta') - \frac{\Delta^- a_0(0)z}{1 - \Delta^- a_0(0)} \right| \\ &= \left| \left(e^{\frac{-\alpha_k}{\beta_k - \alpha_k}} - 1 \right) y_k(-\delta') - \left(e^{\varkappa} - 1 \right) z \right| \\ &\leq \left| e^{\frac{-\alpha_k}{\beta_k - \alpha_k}} - e^{\varkappa} \right| |z| + \left| e^{\frac{-\alpha_k}{\beta_k - \alpha_k}} - 1 \right| |z - y_k(-\delta')|, \end{aligned}$$

where

$$\lim_{k \to \infty} \left| e^{\frac{-\alpha_k}{\beta_k - \alpha_k}} - e^{\varkappa} \right| = 0, \quad \left| e^{\frac{-\alpha_k}{\beta_k - \alpha_k}} - 1 \right| \le 2$$

 $\quad \text{and} \quad$

$$\left|z - y_k(-\delta')\right| \le \delta.$$

Analogously, if $k \in \mathbf{N}$ is such that $\beta_k \leq \delta'$, we have

$$z_k(t) = e^{\frac{\beta_k}{\beta_k - \alpha_k}} z_k(0)$$
 on $[0, \delta']$

and thus

$$\begin{aligned} \left| z_k(\delta') - z_k(0) - \Delta^+ a_0(0) z \right| \\ &= \left| \left(e^{\frac{\beta_k}{\beta_k - \alpha_k}} - 1 \right) z_k(-\delta') - \left(e^{1 - \varkappa} - 1 \right) z \right| \\ &\leq \left| e^{\frac{\beta_k}{\beta_k - \alpha_k}} - e^{1 - \varkappa} \right| |z| + \left| e^{\frac{\beta_k}{\beta_k - \alpha_k}} - 1 \right| |z - z_k(0)|, \end{aligned}$$

where

$$\lim_{k \to \infty} \left| e^{\frac{\beta_k}{\beta_k - \alpha_k}} - e^{1 - \varkappa} \right| = 0, \quad \left| e^{\frac{\beta_k}{\beta_k - \alpha_k}} - 1 \right| \le 2$$

 $\quad \text{and} \quad$

$$\left|z-z_k(0)\right|\leq\delta.$$

Notice that if

$$x_0(t) = \widetilde{x} + \int_{-1}^t d[a_0(t)]x_0(s)$$
 on $[-1, 1],$

then

$$\Delta^{-}x_{0}(0) = \left(\frac{1}{1 - \Delta^{-}a_{0}(0)} - 1\right)x_{0}(0 - 0) = \frac{\Delta^{-}a_{0}(0)}{1 - \Delta^{-}a_{0}(0)}x_{0}(0 - 0).$$

The convergence described in Example 2.7 is closely related to the notion of the *emphatic convergence* introduced by J. Kurzweil (cf. [5]).

2.8. Definition. A sequence $\{A_k\}_{k=1}^{\infty} \subset \mathbf{BV}^{n \times n}$ converges emphatically to $A_0 \in \mathbf{BV}^{n \times n}$ on [0, 1] if

(i) there exist nondecreasing functions $h_k : [0,1] \to \mathbf{R}, k \in \mathbf{N} \cup \{0\}$, which are left-continuous on (0,1] and such that

$$|A_k(t_2) - A_k(t_1)| \le |h_k(t_2) - h_k(t_1)|$$

for all $k \in \mathbf{N} \cup \{0\}$ and $t_1, t_2 \in [0, 1];$

- (ii) $\limsup_{k \to \infty} \left[h_k(t_2) h_k(t_1) \right] \leq \left[h_0(t_2) h_0(t_1) \right]$ whenever $0 \leq t_1 \leq t_2 \leq 1$ and h_0 is continuous at t_1 and t_2 ;
- (iii) there is $\widetilde{A}_0 \in \mathbf{BV}^{n \times n}$ such that $\lim_{k \to \infty} A_k(t) = A_0(t) + \widetilde{A}_0(t)$ whenever $h_0(t) = h_0(t+)$ and $|\widetilde{A}_0(t_2) \widetilde{A}_0(t_1)| \le |\widetilde{h}_0(t_2) \widetilde{h}_0(t_1)|$ for all $t_1, t_2 \in [0, 1]$, where \widetilde{h}_0 stands for the break part of h_0 ;
- (iv) if $h_0(t_0+) > h_0(t_0)$, then for any $z \in \mathbf{R}^n$ and any $\varepsilon > 0$ there exists $\delta > 0$ such that for any $\delta' \in (0, \delta)$ there is $k_0 \in \mathbf{N}$ such that

$$|y_k(t_0 + \delta') - y_k(t_0 - \delta') - \Delta^+ A_0(t_0)z| \le \varepsilon$$

holds for any $k \ge k_0$, any $\tilde{y}_k \in \mathbf{R}^n$ such that $|z - \tilde{y}_k| \le \delta$ and any solution y_k of the equation

$$y_k(t) = \widetilde{y}_k + \int_{t_0 - \delta'}^t d[A_k(s)]y_k(s) \text{ on } [t_0 - \delta', t_0 + \delta'].$$

The following assertion is a restriction of Theorem 4.1 from [5] to the linear case.

2.9. Theorem. Let A_k converge emphatically on [0,1] to A_0 . Let the sequence $\{X_k\}_{k=1}^{\infty} \subset \mathbf{BV}^{n \times n}$ of the fundamental matrices corresponding respectively to A_k , $k \in \mathbf{N}$, be uniformly bounded on [0,1] and such that

$$\lim_{k \to \infty} X_k(t) = Z_0(t) \quad on \ [0,1] \quad whenever \ h_0(t+) = h_0(t).$$

Then $Z_0 \in \mathbf{BV}^{n \times n}$ and the function X_0 defined by

$$X_{0}(t) = \begin{cases} Z_{0}(t) & \text{if } h_{0}(t+) = h_{0}(t), \\ Z_{0}(t-) & \text{otherwise} \end{cases}$$

is the fundamental matrix corresponding to A_0 .

2.10. Remark. Let us notice that necessary and sufficient conditions assuring the uniform convergence of fundamental matrices X_k corresponding to A_k , $k \in \mathbf{N}$, to the fundamental matrix X_0 corresponding to A_0 may be found in the paper [2] by M. Ashordia.

Results related to Theorem 2.9 obtained by the method of "prolongation" of functions of bounded variation to continuous functions along monotone functions and using the concept of convergence under substitution instead of the emphatic convergence were obtained by D. Fraňková in [3] (cf. also [4]), as well.

3. Linear GDE's - new results

3.1. Notation. For a given function $F \in \mathbf{BV}^{n \times n}$, the symbol $\mathbf{S}(F)$ stands for the set of the points of discontinuity of F in [0, 1], while

$$\mathbf{S}^{+}(F) = \{ t \in [0,1); \Delta^{+}F(t) \neq 0 \} \text{ and } \mathbf{S}^{-}(F) = \{ t \in [0,1); \Delta^{-}F(t) \neq 0 \}.$$

If F is such that $\mathbf{S}(F)$ possesses at most a finite number of points, then for an arbitrary compact set M such that

$$M = \bigcup_{j=1}^{m} [\alpha_j, \beta_j] \subset [0, 1] \setminus \mathbf{S}(F)$$

with $[\alpha_j, \beta_j] \cap [\alpha_k, \beta_k] = \emptyset$ for $j \neq k$, we define

$$F^M(t) = F(t) - F(\alpha_j)$$
 if $t \in [\alpha_j, \beta_j]$

Provided the set $\mathbf{S}(A_0)$ contains at most a finite number of elements, we can extend Theorem 2.9 to the case that the functions A_k , $k \in \mathbf{N} \cup \{0\}$, need not be left-continuous on (0, 1] in the following way.

3.2. Theorem. Let $A_0 \in \mathbf{BV}^{n \times n}$, $\mathbf{S}(A_0) = \{\tau_j\}_{j=1}^m$,

$$\det \left[\mathbf{I} - \Delta^{-} A_0(t) \right] \neq 0 \quad on \ [0, 1]$$

and let X_0 be the fundamental matrix solution corresponding to A_0 . Let the sequence $\{A_k\}_{k=1}^{\infty} \subset \mathbf{BV}^{n \times n}$ be such that

- (i) $\sup_k \operatorname{var}_0^1 A_k < \infty$ and $\det \left[I \Delta^- A_k(t) \right] \neq 0$ on (0, 1] for all $k \in \mathbf{N}$;
- (ii) $\lim_{k\to\infty} A_k^M(s) = A_0^M(s)$ uniformly on M for any $M \subset [0,1] \setminus \mathbf{S}(A_0)$ such that $M = \bigcup_{j=1}^m [\alpha_j, \beta_j]$, where $[\alpha_j, \beta_j] \cap [\alpha_k, \beta_k] = \emptyset$ for $j \neq k$;

(iii) if $\tau \in \mathbf{S}(A_0)$ then for any $z \in \mathbf{R}^n$ and any $\varepsilon > 0$ there exists $\delta > 0$ such that for any $\delta' \in (0, \delta)$ there is $k_0 \in \mathbf{N}$ such that the relations

$$\left|y_{k}(\tau)-y_{k}(\tau-\delta')-\Delta^{-}A_{0}(\tau)\left[\mathbf{I}-\Delta^{-}A_{0}(\tau)\right]^{-1}z\right|\leq\varepsilon$$

and

$$\left|z_k(\tau+\delta')-z_k(\tau)-\Delta^+A_0(\tau)z\right|\leq\varepsilon$$

are satisfied for any $k \ge k_0$ and y_k and z_k such that

$$y_k(t) = y_k(\tau - \delta') + \int_{\tau - \delta'}^t d[A_k(s)]y_k(s) \quad on \quad [\tau - \delta', \tau],$$

$$z_k(t) = z_k(\tau) + \int_{\tau}^t d[A_k(s)]z_k(s) \quad on \quad [\tau, \tau + \delta']$$

and

$$|z - y_k(\tau - \delta')| \le \delta$$
 and $|z - z_k(\tau)| \le \delta$.

Then for any $k \in \mathbb{N}$ sufficiently large the fundamental matrix X_k corresponding to A_k is defined on [0, 1] and

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad on \ [0, 1].$$

Proof. Let us restrict ourselves to the case that m = 1, i.e. let $\mathbf{S}(A_0) = \{\tau\}$, where $\tau \in (0, 1)$.

Let an arbitrary $\tilde{x} \in \mathbf{R}^n$ be given and let x_k for any $k \in \mathbf{N} \cup \{0\}$ denote the solution to the equation

$$x_k(t) = \tilde{x} + \int_0^t d[A_k(s)]x_k(s)$$
 on $[0, 1]$.

Our assumptions (i) and (ii) by Theorem 2.5 imply that for any $\alpha \in (0, \tau)$ we have

(3.1)
$$\lim_{k \to \infty} x_k(t) = x_0(t) \quad \text{uniformly on } [0, \alpha].$$

Consequently,

(3.2)
$$\lim_{k \to \infty} x_k(t) = x_0(t) \quad \text{for all} \ t \in [0, \tau).$$

Furthermore, for any $\delta' \in (0, \tau)$ and $k \in \mathbf{N}$ we have

(3.3)
$$|x_{0}(\tau) - x_{k}(\tau)|$$

$$\leq |x_{0}(\tau) - x_{0}(\tau - \delta') - \Delta^{-}A_{0}(\tau)[I - \Delta^{-}A_{0}(\tau)]^{-1}x_{0}(\tau -)|$$

$$+ |\Delta^{-}A_{0}(\tau)[I - \Delta^{-}A_{0}(\tau)]^{-1}x_{0}(\tau -) - (x_{k}(\tau) - x_{k}(\tau - \delta'))|$$

$$+ |x_{0}(\tau - \delta') - x_{k}(\tau - \delta')|.$$

Let an arbitrary $\varepsilon > 0$ be given. By the assumption (iii) there exists $\delta \in (0, \varepsilon)$ such that for all $\delta' \in (0, \delta)$ there exists $k_1 = k_1(\delta') \in \mathbf{N}$ such that for any $k \ge k_1$ and for any solution y_k of the equation

$$y_k(t) = y_k(\tau - \delta') + \int_{\tau - \delta'}^t d[A_k(s)]y_k(s) \quad \text{on} \quad [\tau - \delta', \tau]$$

such that $|y_k(\tau - \delta') - x_0(\tau -)| < \delta$ we have

(3.4)
$$|y_k(\tau) - y_k(\tau - \delta') - \Delta^- A_0(\tau) [I - \Delta^- A_0(\tau)]^{-1} x_0(\tau -)| < \varepsilon$$

Let us choose $\delta' \in (0, \delta)$ in such a way that

(3.5)
$$|x_0(\tau-) - x(\tau-\delta')| < \frac{\delta}{2}$$

is true. Furthermore, according to (3.2) there is $k_0 \in \mathbf{N}$ such that $k_0 \geq k_1$ and

(3.6)
$$|x_0(\tau - \delta') - x_k(\tau - \delta')| < \frac{\delta}{2} \quad \text{for all} \quad k \ge k_0.$$

In particular, for $k \ge k_0$ we have

$$(3.7) |x_0(\tau-)-x_k(\tau-\delta')| < \delta.$$

Thus, if we put $y_k(t) = x_k(t)$ on $[\tau - \delta', \tau]$, then the relation (3.4) will be satisfied for any $k \ge k_0$, i.e. we have

(3.8)
$$\left| x_k(\tau) - x_k(\tau - \delta') - \Delta^- A_0(\tau) \left[\mathbf{I} - \Delta^- A_0(\tau) \right]^{-1} x_0(\tau -) \right| < \varepsilon$$

for all $k \ge k_0$. Now, inserting (3.6)-(3.8) into (3.3), we obtain that

$$|x_k(\tau) - x_0(\tau)| < \frac{\delta}{2} + \frac{\delta}{2} + \varepsilon < 2\varepsilon$$

is satisfied for any $k \ge k_0$, i.e.

(3.9)
$$\lim_{k \to \infty} x_k(\tau) = x_0(\tau)$$

Further, we will prove that there is $\eta > 0$ such that

$$\lim_{k \to \infty} x_k(t) = x_0(t)$$

is true on $(\tau, \tau + \eta)$ as well. To this aim, let $\varepsilon > 0$ be given and let $\eta_0 \in (0, \varepsilon)$ be such that

(3.10)
$$|x_0(s) - x_0(\tau +)| < \varepsilon \quad \text{for all} \quad s \in (\tau, \tau + \eta_0).$$

By the assumption (iii) there exists $\eta \in (0, \eta_0)$ such that for any $\eta' \in (0, \eta)$ there is $\ell_1 = \ell_1(\eta') \in \mathbf{N}$ such that for any $k \ge \ell_1$ and for any solution z_k of the equation

$$z_k(t) = z_k(\tau) + \int_{\tau}^t \mathbf{d}[A_k(s)] z_k(s) \text{ on } [\tau, \tau + \eta']$$

such that $|z_k(\tau) - x_0(\tau)| < \eta$ we have

(3.11)
$$\left|z_k(\tau+\eta')-z_k(\tau)-\Delta^+A_0(\tau)x_0(\tau)\right|<\varepsilon.$$

Let us choose $\eta' \in (0, \eta)$ arbitrarily. By (3.10), we have

(3.12)
$$|x_0(\tau - \eta') - x_0(\tau +)| < \varepsilon.$$

Furthermore, by (3.9) there is $\ell_0 \in \mathbf{N}$ such that $\ell_0 \geq \ell_1$ and

(3.13)
$$|x_k(\tau) - x_0(\tau)| < \eta \quad \text{for all} \quad k \ge \ell_0.$$

Thus, by (3.11), for any $k \ge \ell_0$ we have

(3.14)
$$\left|x_k(\tau+\eta')-x_k(\tau)-\Delta^+A_0(\tau)x_0(\tau)\right|<\varepsilon.$$

Making use of (3.12)-(3.14) we finally get for any $k \ge k_0$

$$\begin{aligned} |x_{k}(\tau + \eta') - x_{0}(\tau + \eta')| \\ &\leq |x_{k}(\tau + \eta') - x_{k}(\tau) - x_{0}(\tau +) + x_{0}(\tau)| \\ &+ |x_{0}(\tau + \eta') - x_{0}(\tau +)| + |x_{k}(\tau) - x_{0}(\tau)| \\ &= |x_{k}(\tau + \eta') - x_{k}(\tau) - \Delta^{+}A_{0}(\tau)x_{0}(\tau)| \\ &+ |x_{0}(\tau +) - x_{0}(\tau + \eta')| + |x_{k}(\tau) - x_{0}(\tau)| < 3\varepsilon \end{aligned}$$

i.e.

$$\lim_{k \to \infty} x_k(t) = x_0(t) \quad \text{for all} \ t \in (\tau, \tau + \eta).$$

,

The proof of the theorem can be completed by making use of Theorem 2.5 and taking into account that $\tilde{x} \in \mathbf{R}^n$ was chosen arbitrarily. The extension to a general case $m \in \mathbf{N}$ is obvious.

3.3. Remark. Obviously, if we did not restrict ourselves to the case of only a finite number of discontinuities of A_0 , we should replace the assumptions (i)-(ii) in Theorem 3.2 by assumptions of the form (i)-(ii) from Definition 2.8.

3.4. Remark. The following concept due to M. Pelant (cf. [7]) leads to another interesting convergence effect which most probably cannot be explained by Theorem 3.2.

Let $A \in \mathbf{BV}^{n \times n}$ and let the divisions $\mathcal{P}_k = \{0 = t_0^k < \cdots < t_{p_k}^k = 1\}, k \in \mathbf{N}$, of [0, 1] be such that

$$\mathcal{P}_k \supset \mathcal{D}_k = \{ t \in [0, 1]; t = \frac{i}{2^k}, i = 0, 1, \dots 2^k \}$$
$$\cup \{ t \in (0, 1]; |\Delta^- A(t)| \ge \frac{1}{k} \}$$
$$\cup \{ t \in [0.1); |\Delta^+ A(t)| \ge \frac{1}{k} \}.$$

For a given $k \in \mathbf{N}$, let us put

$$A_k(t) = \begin{cases} A(t) & \text{if } t \in \mathcal{P}_k, \\ A(t_{i-1}^k) + \frac{A(t_i^k) - A(t_{i-1}^k)}{t_i^k - t_{i-1}^k} (t - t_{i-1}^k) & \\ & \text{if } t \in (t_{i-1}^k, t_i^k). \end{cases}$$

Then we say that the sequence $\{A_k, \mathcal{P}_k\}_{k=1}^{\infty}$ piecewise linearly approximates A.

Furthermore, for a given $A \in \mathbf{BV}^{n \times n}$, let us define A_0 on [0, 1] by

(3.15)
$$A_{0}(t) = A(t) - \sum_{s \in \mathbf{S}^{-}(A)} \Delta^{-}A(s)\chi_{[s,1]}(t) - \sum_{s \in \mathbf{S}^{+}(A)} \Delta^{+}A(s)\chi_{(s,1]}(t) + \sum_{s \in \mathbf{S}^{-}(A)} \left(I - \left[\exp\left(\Delta^{-}A(s)\right) \right]^{-1} \right) \chi_{[s,1]}(t) + \sum_{s \in \mathbf{S}^{+}(A)} \left(\exp\left(\Delta^{+}A(s)\right) - I \right) \chi_{(s,1]}(t).$$

Then, obviously

$$\det \left[\mathbf{I} - \Delta^{-} A_0(t) \right] \neq 0 \quad \text{on} \quad [0, 1]$$

holds and the following assertion may be proved (cf. [7]).

Let $A \in \mathbf{BV}^{n \times n}$, let A_0 be given by (3.15), let $\{A_k, \mathcal{P}_k\}_{k=1}^{\infty}$ piecewise linearly approximate A and let for a given $k \in \mathbf{N}$, X_k denote the fundamental matrix corresponding to A_k . Then

$$\lim_{k \to \infty} X_k(t) = X_0(t) \quad for \ all \ t \in [0, 1].$$

Furthermore, if $A \in \mathbf{BV}^{n \times n}$ is such that the relations

(3.16)
$$\det \left[\mathbf{I} - \Delta^{-} A(t) \right] \neq 0 \quad \text{and} \quad \det \left[\mathbf{I} + \Delta^{+} A(t) \right] \neq 0 \quad \text{on} \quad [0, 1]$$

are true, then for $t \in [0, 1]$ we can define

(3.17)
$$A_{0}^{*}(t) = A(t) - \sum_{s \in \mathbf{S}^{-}(A)} \Delta^{-}A(s)\chi_{[s,1]}(t) - \sum_{s \in \mathbf{S}^{+}(A)} \Delta^{+}A(s)\chi_{(s,1]}(t) + \sum_{s \in \mathbf{S}^{-}(A)} \ln \left[I - \Delta^{-}A(s)\right]^{-1}\chi_{[s,1]}(t) + \sum_{s \in \mathbf{S}^{+}(A)} \ln \left[I + \Delta^{+}A(s)\right]\chi_{(s,1]}(t)$$

and the following assertion is an immediate corollary of the above mentioned result of M. Pelant.

3.5. Theorem. Let $A \in \mathbf{BV}^{n \times n}$ be such that (3.16) holds and let X be the fundamental matrix corresponding to A. Let A_0^* be given by (3.17), let $\{A_k, \mathcal{P}_k\}_{k=1}^{\infty}$ piecewise linearly approximate A_0^* and let for a given $k \in \mathbf{N}$, X_k denote the fundamental matrix corresponding to A_k . Then

$$\lim_{k \to \infty} X_k(t) = X(t) \quad for \ all \ t \in [0, 1].$$

References

- Ashordia M., On the correctness of linear boundary value problems for systems of generalized ordinary differential equations, Proc. of the Georgian Academy of Sciences. Mathematics, 1 (1993), 385–394.
- [2] Ashordia M., Criteria of correctness of linear boundary value problems for systems of generalized ordinary differential equations, *Czechoslovak Math. J.*, 46 (121) (1996), 385-403.

- [3] Fraňková D., Continuous dependence on a parameter of solutions of generalized differential equations, *Časopis pěst. mat.*, **114** (1989), 230–261.
- [4] Fraňková D., Substitution method for generalized linear differential equations, Math. Bohem., 116 (1991), 337–359.
- [5] Kurzweil J., Generalized ordinary differential equations, Czechoslovak Math. J., 24 (83) (1958), 360–387.
- [6] Kurzweil J., Vorel Z., Continuous dependence of solutions of differential equations on a parameter, *Czechoslovak Math. J.*, **23** (82), (1957), 568–583.
- [7] Pelant M., On approximations of solutions of generalized differential equations (in Czech), *Dissertation, Charles University*, (Praha, 1997)
- [8] Schwabik Š., Generalized Ordinary Differential Equations, (World Scientific, Singapore, 1992).
- [9] Schwabik Š., Tvrdý M., Vejvoda O., Differential and Integral Equations: Boundary Value Problems and Adjoints, (Academia, Praha & Reidel, Dordrecht, 1979).