Mapping of diffusion in quasi-1D systems onto the longitudinal coordinate

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Brownian pumps

Diffusion in a 2D channel



as the current density $\mathbf{j}(x, y, t) = -D\nabla\rho(x, y, t)$ at the hard walls is parallel to them.

Is there any corresponding equation for $p(x,t) = \int_0^{A(x)} \rho(x,y,t) dy$?

Exact formulation: the 1D density p(x,t) is determined by

the diffusion equation + BCs + an initial condition $\rho(x, y, 0) = \rho_0(x, y)$. We can:

- either to solve the 2D problem
- and to map the solution $\rho(x, y, t)$

$$p(x,t) = \int_0^{A(x)} \rho(x,y,t) dy$$

Our goal:

to find the operator $\hat{Q}(x, \partial_x)$ to make both treatments equivalent.

- or to map the initial condition
- and to solve some equation

$$\frac{\partial p(x,t)}{\partial t} = \hat{Q}(x,\partial_x)p(x,t)$$

The simplest approximations:

Fick – Jacobs equation :
$$\frac{\partial p(x,t)}{\partial t} = D \frac{\partial}{\partial x} A(x) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)} ,$$

Zwanzig's correction (1992):
$$\frac{\partial p(x,t)}{\partial t} = D \frac{\partial}{\partial x} A(x) \left(1 - \frac{1}{3} A'^2(x) \right) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)}$$

Reguera and Rubí (2001) concluded from the non-equilibrium TD

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial}{\partial x} A(x) \mathbf{D}(x) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)}$$

with D(x) estimated as $D(x) \simeq \left(1 + A'^2(x)\right)^{-1/3}$.

Trick #1: suppose anisotropy of the diffusion constant D

$$\frac{\partial \rho(x, y, t)}{\partial t} = \left(D_x \frac{\partial^2}{\partial x^2} + D_y \frac{\partial^2}{\partial y^2} \right) \rho(x, y, t) ; \qquad D_y \gg D_x$$

Rescaling time $D_x t \rightarrow t \Rightarrow$ we introduce a small parameter $\epsilon = D_x/D_y$;

$$\left(\frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2} - \frac{1}{\epsilon} \frac{\partial^2}{\partial y^2}\right) \rho(x, y, t) = 0; \quad \left(\frac{\partial}{\partial y} - \epsilon A'(x) \frac{\partial}{\partial x}\right) \rho(x, y, t) \Big|_{y = A(x)} = 0.$$

After integration of the diffusion equation over y and using BC:

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial^2 p(x,t)}{\partial x^2} - \frac{\partial}{\partial x} \Big(A'(x) \ \rho(x,A(x),t) \Big)$$



Then

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial^2 p(x,t)}{\partial x^2} - \frac{\partial}{\partial x} \left(A'(x) \frac{p(x,t)}{A(x)} \right) = \frac{\partial}{\partial x} A(x) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)} = \text{FJ eq.}$$



- this is substituted for $\rho(x, A(x), t)$ in the mapped equation:

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial^2 p(x,t)}{\partial x^2} - \frac{\partial}{\partial x} \Big(A'(x) \ \hat{\omega}(x,A(x),\partial_x) \frac{p(x,t)}{A(x)} \Big)$$

Trick #2: search for the operator of backward mapping $\hat{\omega}$

a) $\hat{\omega}$ does not depend on time, hence

$$\frac{\partial}{\partial t}\,\hat{\omega}(x,y,\partial_x) = \hat{\omega}(x,y,\partial_x)\,\frac{\partial}{\partial t}$$

b) $\hat{\omega}$ satisfies the inverse (unity) relation

$$\frac{1}{A(x)} \int_0^{A(x)} dy \,\hat{\omega}(x, y, \partial_x) \frac{p(x, t)}{A(x)} = \frac{p(x, t)}{A(x)} \qquad \text{for any solution } p(x, t),$$

c) $\hat{\omega}$ can be expanded in ϵ : $\hat{\omega}(x, y, \partial_x) = 1 + \sum_{j=1}^{\infty} \epsilon^j \hat{\omega}_j(x, y, \partial_x)$

d) the backward mapped $\rho(x,y,t)=\hat{\omega}(x,y,\partial_x)\big[p(x,t)/A(x)\big]$ solves the diffusion equation

$$\sum_{j=0}^{\infty} \epsilon^{j+1} \left(\frac{\partial}{\partial t} - \frac{\partial^2}{\partial x^2} - \frac{1}{\epsilon} \frac{\partial^2}{\partial y^2} \right) \hat{\omega}_j(x, y, \partial_x) \frac{p(x, t)}{A(x)} = 0$$

with Neumann BC at y = 0 and A(x).

$$\frac{\partial p(x,t)}{\partial t} = \hat{Q}(x,\partial_x)p(x,t) = \frac{\partial}{\partial x} \Big[\frac{\partial}{\partial x} A(x) - A'(x)\hat{\omega}(x,A(x),\partial_x) \Big] \frac{p(x,t)}{A(x)}$$
$$= \frac{\partial}{\partial x} A(x) \Big(1 - \epsilon \hat{Z}(x,\partial_x) \Big) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)} ,$$
where also \hat{Z} can be expanded in ϵ : $\epsilon \hat{Z}(x,\partial_x) = \sum_{j=1}^{\infty} \epsilon^j \hat{Z}_j(x,\partial_x) .$

Recurrence relations:

$$\frac{\partial^2}{\partial y^2} \,\hat{\omega}_{j+1}(x, y, \partial_x) = -\frac{\partial^2}{\partial x^2} \,\hat{\omega}_j(x, y, \partial_x) \\ -\sum_{k=0}^j \hat{\omega}_{j-k}(x, y, \partial_x) \frac{1}{A(x)} \,\frac{\partial}{\partial x} A(x) \hat{Z}_k(x, \partial_x) \frac{\partial}{\partial x}$$

and
$$\hat{Z}_j(x,\partial_x)\frac{\partial}{\partial x} = \frac{A'(x)}{A(x)} \hat{\omega}_j(x,A(x),\partial_x)$$
 for $j > 0$.

- we start from $\hat{\omega}_0(x, y, \partial_x) = 1$ and $\hat{Z}_0(x, \partial_x) = -1$ (valid for FJ)

- use BC and the inverse relation for fixing the integration constants at double integration of $\partial_y^2 \hat{\omega}_{j+1}(x, y, \partial_x)$

Resultant expansions of $\hat{\omega}(x, y, \partial_x)$ and $\hat{Z}(x, \partial_x)$:

$$\hat{\omega}(x, y, \partial_x) = 1 + \epsilon \left(3y^2 - A'^2(x) \right) \frac{A'(x)}{6A(x)} \frac{\partial}{\partial x} + \dots$$

 and

$$\begin{aligned} \frac{\partial p(x,t)}{\partial t} &= \frac{\partial}{\partial x} A \bigg[1 - \frac{\epsilon}{3} A'^2 - \frac{\epsilon^2}{45} A' \Big(2A \big(AA' \big)' \frac{\partial}{\partial x} + AA'A'' + A^2 A^{(3)} - 7A'^3 \Big) + \dots \bigg] \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)} \end{aligned}$$

Instead of the function D(x), we get an **operator** containing $\partial/\partial x$.

Stationary flow: D(x) can be expressed using \hat{Z} .

Any form of the equation for $\partial_t p(x,t)$ represents 1D mass conservation law.

$$J(x,t) = -A(x)D(x)\frac{\partial}{\partial x}\frac{p(x,t)}{A(x)}; \quad J(x,t) = A(x)\left(1 - \epsilon \hat{Z}(x,\partial_x)\right)\frac{\partial}{\partial x}\frac{p(x,t)}{A(x)}$$

In the stationary state: J(x,t)=J constant; - any stationary solution p(x) has to keep

$$\frac{\partial}{\partial x} \frac{p(x)}{A(x)} = \frac{-J}{A(x)D(x)}$$

Final relation:

$$\frac{1}{D(x)} = A(x) \left[1 - \epsilon \hat{Z}(x, \partial_x) \right]^{-1} \frac{1}{A(x)}$$

enables us to generate D(x) as an expansion in ϵ .

$$D(x) = 1 - \frac{\epsilon}{3} A'^2 + \frac{\epsilon^2}{45} \left(9A'^4 + AA'^2 A'' - A^2 A' A^{(3)} \right) - \frac{\epsilon^3}{945} \left(135A'^6 + 45AA'^4 A'' - 58A^2 A'^2 A''^2 - 41A^2 A'^3 A^{(3)} - 12A^3 A' A'' A^{(3)} + 8A^3 A'^2 A^{(4)} + 2A^4 A' A^{(5)} \right) \dots$$

"Linear" approximation:

$$D(x) \simeq 1 - \frac{\epsilon}{3} A'^2 + \frac{\epsilon^2}{5} A'^4 - \dots + \frac{(-\epsilon)^j}{2j+1} A'^{2j} + \dots = \frac{\arctan(\sqrt{\epsilon}A')}{\sqrt{\epsilon}A'}$$

3D symmetric channels : $D(x) \simeq \frac{1}{\sqrt{1 + \epsilon R'^2(x)}}$; R(x) is the radius

$\sqrt{\epsilon}$ as a scaling parameter of the transverse lengths

If we rescale $\sqrt{\epsilon}y \to y$, $\sqrt{\epsilon}A(x) \to A(x)$ and $\rho \to \sqrt{\epsilon}\rho$ the diffusion becomes isotropic:

$$\frac{\partial}{\partial t} \frac{\rho(x, y, t)}{\sqrt{\epsilon}} = \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial (\sqrt{\epsilon}y)^2}\right) \frac{\rho(x, y, t)}{\sqrt{\epsilon}} ;$$

the upper boundary condition:

$$\frac{\partial \rho(x, y, t)}{\sqrt{\epsilon} \ \partial(\sqrt{\epsilon}y)} = \sqrt{\epsilon} A'(x) \frac{\partial \rho(x, y, t)}{\sqrt{\epsilon} \ \partial x} \Big|_{\sqrt{\epsilon}y = \sqrt{\epsilon}A(x)} .$$

 \Rightarrow a narrow channel with isotropic diffusion is equivalent to a wide domain with $D_y \gg D_x$.

Variational approach



Q: Can we express the 2D density $\rho(x, y, t)$ as a function of only one spatial (curvilinear) variable z = z(x, y)?

Variational mapping: we start from the functional $F[\rho, \bar{\rho}]$

$$F = \int_{t_0}^{t_1} dt \int_{x_L}^{x_R} dx \int_0^{A(x)} dy \left(\frac{1}{2} \left(\dot{\rho}\bar{\rho} - \dot{\bar{\rho}}\rho\right) + \partial_x \bar{\rho} \ \partial_x \rho + \frac{1}{\epsilon} \partial_y \bar{\rho} \ \partial_y \rho\right)$$

Stationary condition $\delta F = 0$ gives the diffusion and "*anti* diffusion" equation for the density $\rho = \rho(x, y, t)$ and its complementary $\bar{\rho} = \bar{\rho}(x, y, t)$:

$$\dot{
ho} = \partial_x^2
ho + rac{1}{\epsilon} \partial_y^2
ho ~~;~~ -\dot{ar{
ho}} = \partial_x^2 ar{
ho} + rac{1}{\epsilon} \partial_y^2 ar{
ho}$$

Next step: switching from (x, y) to (z, y) in F

$$F = \int_{t_0}^{t_1} dt \int_{z_L}^{z_R} dz \int_0^{A(x_z)} dy \frac{\partial x}{\partial z} \left[\frac{1}{2} \left(\dot{\rho} \bar{\rho} - \dot{\bar{\rho}} \rho \right) + \left(\left(\frac{\partial z}{\partial x} \right)^2 + \frac{1}{\epsilon} \left(\frac{\partial z}{\partial y} \right)^2 \right) \partial_z \bar{\rho} \, \partial_z \rho \right]$$

$$x = x(z, y) \text{ is inverse to } z = z(x, y) \text{ and } x_z = x(z, A(x_z)).$$

Integration over y – along constant z = z(x, y):

$$F_1[\rho(z,t),\bar{\rho}(z,t)] = \int_{t_0}^{t_1} dt \int_{z_L}^{z_R} dz \left[\frac{1}{2} \alpha(z) \left(\dot{\rho} \bar{\rho} - \dot{\bar{\rho}} \rho \right) + \kappa(z) \, \partial_z \bar{\rho} \, \partial_z \rho \right] ;$$



$$\frac{\partial \rho}{\partial t} = \frac{1}{\alpha(z)} \frac{\partial}{\partial z} \kappa(z) \frac{\partial}{\partial z} \rho \quad ; \qquad -\frac{\partial \bar{\rho}}{\partial t} = \frac{1}{\alpha(z)} \frac{\partial}{\partial z} \kappa(z) \frac{\partial}{\partial z} \bar{\rho}$$

A problem: there is no condition for the transformation z = z(x, y)

- at the stationary $\rho, \bar{\rho}, \ F[\rho, \bar{\rho}] = 0$ for any z = z(x, y).

Simple Ansatz:

$$z = z(x, y) = \sum_{j=0}^{\infty} \epsilon^j y^{2j} z_j(x)$$

– the boundary conditions for hoig(z(x,y),tig) have to be satisfied

$$\frac{\partial \rho}{\partial z} \frac{\partial z}{\partial y} = 0 \Big|_{y=0} \quad ; \quad \frac{1}{\epsilon} \frac{\partial \rho}{\partial z} \frac{\partial z}{\partial y} = A'(x) \left. \frac{\partial \rho}{\partial z} \left. \frac{\partial z}{\partial x} \right|_{y=A(x)} ;$$

hence

$$z_j(x) = \frac{1}{2j} \frac{A'(x)}{A(x)} \, z'_{j-1}(x) \; ;$$

 $z_0(x)$ can be chosen to make the Ansatz summable.

Test example - hyperboloidal cone



Oblate spheroidal coordinates:

$$x = a\xi\eta, \quad r^2 = a^2(1+\xi^2)(1-\eta^2)$$

 $\begin{array}{l} \xi \ - \ {\rm longitudinal\ coordinate;} \quad \xi > 0 \\ \eta \ - \ {\rm curved\ transverse\ coordinate,} \\ {\rm hard\ walls\ at\ } \eta = \eta_0; \quad 0 < \eta_0 < 1 \\ {\rm the\ points\ } \eta_0 < \eta < 1 \ {\rm are\ inside\ the\ cone} \end{array}$

Boundary conditions:

- $\xi = 0$ absorbing boundary; $\rho(0, \eta) = 0$
- in infinity, $\rho(\xi \to \infty, \eta) \to \rho_0 = const.$

Q: What is the stationary flux J through the bottleneck $(x = \xi = 0)$?



... several questions:

- how to find the optimal transformation z = z(x, y) ?
- how reliable is the "linear" formula for D(x) ?
- can we sum more terms in the ϵ expansion of D(x) ?



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Stationary curvilinear coordinates

The mapped equation :

$$\frac{\partial p(x,t)}{\partial t} = \frac{\partial}{\partial x} A(x) D(x) \frac{\partial}{\partial x} \frac{p(x,t)}{A(x)}$$

Its stationary solution :

$$\frac{p(x)}{A(x)} = \rho_0 - J \int \frac{dx'}{A(x')D(x')}$$

D(x) is fixed by using $\hat{Z}(x,\partial_x)$ and $\hat{\omega}(x,y,\partial_x)$ is known, hence

$$\rho(x,y) = \hat{\omega}(x,y,\partial_x) \frac{p(x)}{A(x)} = \rho_0 + J \sum_{j=0}^{\infty} \sum_{k=0}^{j} \epsilon^j y^{2k} z_{j,k}(x) = \rho_0 + J z(x,y) ;$$

$$z_{0,0}(x) = \int \frac{dx}{A(x)} , \quad z_{1,0}(x) = \frac{1}{3} \int \frac{A'^2}{A} dx - \frac{A'}{6} , \quad z_{1,1}(x) = \frac{A'}{2A^2} , \dots$$

Correspondence to electrostatics

Conversely, the stationary ρ solves $\Delta \rho(x, y) = 0$ plus Neumann BC at y = 0, A(x), so D(x) can be calculated directly from

$$-J = A(x)D(x)\frac{\partial}{\partial x}\left[\frac{1}{A(x)}\int_{0}^{A(x)}\rho(x,y)dy\right]$$

for exactly solvable geometries in electrostatics.

Q: Why do we need D(x) if we have already the 2D solution $\rho(x, y)$?

- A: Originally, we intended to use the mapped equation for description of **non stationary processes**.
 - the simplified mapped equation (with D(x)) is capable to describe only quasi-stationary processes.

Linear cone:



Fixing
$$c:$$
 $J = -\int_0^{A(x)} \partial_x \rho(x, y) dy \Rightarrow \rho(x, y) = \rho_0 - \frac{J \ln r}{\arctan \gamma}$

$$D(x) = -\frac{J}{\gamma x} \left(\frac{\partial}{\partial x} \left[\frac{1}{\gamma x} \int_0^{\gamma x} \rho(x, y) dy \right] \right)^{-1} = \frac{\arctan \gamma}{\gamma}$$

 $r = \sqrt{x^2 + y^2}$ – correct curvilinear coordinate for the variational mapping.



$$\rho(x,y) = \rho_0 - \frac{J}{2\arctan\gamma} \ln\left[(x-a_0)^2 + y^2\right]; \qquad \gamma = A'(x) \text{ is constant}$$

$$D(x) = \frac{-J}{\gamma(x-a_0)} \left(\frac{\partial}{\partial x} \left[\frac{1}{\gamma(x-a_0)} \int_0^{\gamma(x-a_0)} \rho(x,y) dy \right] \right)^{-1} = \frac{\arctan A'(x)}{A'(x)}$$

Circular approximation:

A(x) is approximated by a circle, given by 3 parameters: radius R_0 , and the shifts x_0 , y_0 ;

- the circle fits A(x), A'(x) and A''(x) at $x = \overline{x}$.



$$\rho(x,y) = \rho_0 - \frac{J}{2\arctan[-w/y_0]} \ln \frac{(w+x-x_0)^2 + y^2}{(w-x+x_0)^2 + y^2} ,$$

where $w = \sqrt{R_0^2 - y_0^2}$ and arctan of real argument $\in (0, \pi)$.

$$D(x) = \frac{AA''}{A'(1 + A'^2 + AA'') \arctan(A') / \arctan(\gamma) + AA'' - A'^2(1 + A'^2)},$$

where
$$\gamma = \frac{\sqrt{(1 + A'^2)^3 - (1 + A'^2 + AA'')^2}}{1 + A'^2 + AA''}$$

If A is rescaled by $\sqrt{\epsilon}$, its Taylor expansion is

$$D(x) = 1 - \frac{\epsilon}{3} A'^2 + \frac{\epsilon^2}{45} A'^2 (9A'^2 + AA'') - \frac{\epsilon^3}{945} A'^2 (135A'^4 + 45AA'^2A'' + 5A^2A''^2) + \dots$$

Finite channels

- the mapping procedure supposes that the function A(x) is analytic
- the mapping generates a unique stationary curvilinear system
- if the function A(x) defined for $x \in (x_L, x_R)$ is extended by its mirrors $A(x_{L,R} + x) = A(x_{L,R} x)$ and it remains analytic, the mapping works





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Hierarchy of approximations of the mapping

- Zwanzig-Mori: keeps all information; the transients are hidden in the memory
- non stationary mapping: projects out the transients, the mapped process is again Markovian, governed by the generalized **FJ equation** modified by a correction operator $1 \hat{Z}(x, \partial_x)$
- stationary mapping: fixes a unique curvilinear coordinate system; the operator $1 \hat{Z}(x, \partial_x)$ becomes a function D(x).
- **next approximations** of D(x). The exact stationary function is replaced by a function D(x) corresponding to **some exactly solvable model**, which approximates the true boundary.

Can be this mapping extended to other dynamics?

forced diffusion; diffusion in an external field . . . is OK ballistic motion - ? quantum mechanics - ?

One has to resolve ...

- ... what are the transients?
- ... what is the small parameter ϵ ?
- ... what is an equivalent of the Fick-Jacobs equation?
- ... what plays the role of the equilibrium in non-dissipative processes?

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