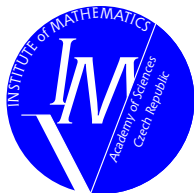


Local error indicators and guaranteed upper bounds

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February 9, 2011, SIGA 2011, Institute of Thermomechanics, Praha



Motivation – adaptive algorithm

1. **Initialize:** Construct the initial mesh \mathcal{T}_h .
2. **Solve:** Find u_h on \mathcal{T}_h .
3. **Error indicators:** Compute η_K for all $K \in \mathcal{T}_h$.
4. **Error estimator:** $\eta^2 = \sum_{K \in \mathcal{T}_h} \eta_K^2$.
5. **Stopping criterion:** If $\eta \leq \text{TOL} \Rightarrow \text{STOP}$.
6. **Mark:** If $\eta_K \geq \Theta \max_{K \in \mathcal{T}_h} \eta_K \Rightarrow \text{mark } K$. $0 < \Theta < 1$
7. **Refine:** Refine marked elements and build the new mesh \mathcal{T}_h .
8. GO TO 2.

Remark: Guaranteed upper bound: $\|u - u_h\| \leq \eta \leq \text{TOL}$



Primal Problem

Strong form.:
$$\begin{aligned} -\Delta u &= f & \text{in } \Omega \subset \mathbb{R}^d \\ u &= 0 & \text{on } \partial\Omega \end{aligned}$$

Weak form.: $u \in V : \mathcal{B}(u, v) = \mathcal{F}(v) \quad \forall v \in V$

Notation:

▶ $V = H_0^1(\Omega)$

▶ $\mathcal{B}(u, v) = (\nabla u, \nabla v) \quad (\mathbf{p}, \mathbf{q}) = \int_{\Omega} \mathbf{p} \cdot \mathbf{q} \, dx$

▶ $\mathcal{F}(v) = (f, v) \quad (f, v) = \int_{\Omega} f v \, dx$

▶ $\|v\|^2 = \mathcal{B}(v, v)$

Derivation of the estimate

Divergence theorem: $v \in H^1(\Omega)$ $\mathbf{y} \in \mathbf{H}(\text{div}, \Omega)$

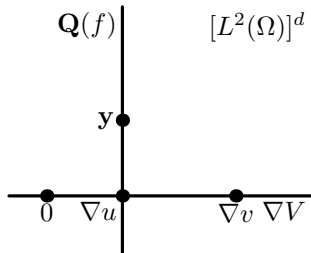
$$\int_{\Omega} v \operatorname{div} \mathbf{y} \, dx + \int_{\Omega} \mathbf{y} \cdot \nabla v \, dx - \int_{\partial\Omega} v \mathbf{y} \cdot \mathbf{n} \, dx = 0$$

$$\mathbf{Q}(f) = \{\mathbf{y} \in \mathbf{H}(\text{div}, \Omega) : (\mathbf{y}, \nabla v) = (f, v) \quad \forall v \in V\}$$

Orthogonality:

$$\int_{\Omega} (\nabla u - \mathbf{y}) \cdot \nabla v \, dx = 0$$

$$\forall v \in V, \forall \mathbf{y} \in \mathbf{Q}(f)$$





Derivation of the estimate

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$$\int_{\Omega} v \operatorname{div} \mathbf{y} \, dx + \int_{\Omega} \mathbf{y} \cdot \nabla v \, dx - \int_{\partial\Omega} v \mathbf{y} \cdot \mathbf{n} \, dx = 0$$

$$v \in V, \quad \mathbf{y} \in \mathbf{Q}(f) = \{ \mathbf{y} \in \mathbf{H}(\text{div}, \Omega) : (\mathbf{y}, \nabla v) = (f, v) \quad \forall v \in V \}$$

$$\begin{aligned} \mathcal{B}(u - u_h, v) &= (f, v) - (\nabla u_h, \nabla v) + (v, \operatorname{div} \mathbf{y}) + (\mathbf{y}, \nabla v) \\ &= (f + \operatorname{div} \mathbf{y}, v) + (\mathbf{y} - \nabla u_h, \nabla v) \\ &= (\mathbf{y} - \nabla u_h, \nabla v) \\ &\leq \|\mathbf{y} - \nabla u_h\|_0 \|\nabla v\|_0 \end{aligned}$$

$$\|u - u_h\| \leq \|\mathbf{y} - \nabla u_h\|_0 \quad \forall u_h \in V$$



The estimator

Definition: $\eta(u_h, \mathbf{y}_h) = \|\mathbf{y}_h - \nabla u_h\|_0$

Theorem: $\|u - u_h\| \leq \eta(u_h, \mathbf{y}_h) \quad \forall u_h \in V \quad \forall \mathbf{y}_h \in \mathbf{Q}(f)$



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Complementary problem:

(A) Find $\mathbf{y} \in \mathbf{Q}(f) : \eta(u_h, \mathbf{y}) \leq \eta(u_h, \mathbf{w}) \quad \forall \mathbf{w} \in \mathbf{Q}(f)$

(B) Find $\mathbf{y} \in \mathbf{Q}(f) : \frac{1}{2} \|\mathbf{y}\|_0^2 \leq \frac{1}{2} \|\mathbf{w}\|_0^2 \quad \forall \mathbf{w} \in \mathbf{Q}(f)$

(C) Find $\mathbf{y} \in \mathbf{Q}(f) : (\mathbf{y}, \mathbf{w}^0) = 0 \quad \forall \mathbf{w}^0 \in \mathbf{Q}(0)$



The estimator

Definition: $\eta(u_h, \mathbf{y}_h) = \|\mathbf{y}_h - \nabla u_h\|_0$

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(C) Find $\mathbf{y} \in \mathbf{Q}(f) : (\mathbf{y}, \mathbf{w}^0) = 0 \quad \forall \mathbf{w}^0 \in \mathbf{Q}(0)$

Lemma 1: (A) \Leftrightarrow (B) \Leftrightarrow (C)

Lemma 2: $\mathbf{y} = \nabla u \in \mathbf{Q}(f)$ is the unique solution of (A)–(C)

Lemma 3: $\eta^2(u, \mathbf{y}_h) + \eta^2(u_h, \mathbf{y}) = \eta^2(u_h, \mathbf{y}_h) \quad \forall u_h \in V, \mathbf{y}_h \in \mathbf{Q}(f)$
 $\|\mathbf{y}_h - \mathbf{y}\|_0^2 + \|\nabla u - \nabla u_h\|_0^2 = \|\mathbf{y}_h - \nabla u_h\|_0^2$

Method of hypercircle

Theorem: If

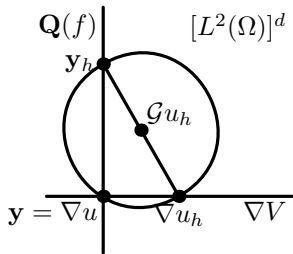
- ▶ $u \in V$ is primal solution
- ▶ $u_h \in V$, $\mathbf{y}_h \in \mathbf{Q}(f)$ arbitrary
- ▶ $\mathcal{G}u_h = (\mathbf{y}_h + \nabla u_h)/2$

Then

$$\|\nabla u - \mathcal{G}u_h\|_0 = \frac{1}{2}\eta(u_h, \mathbf{y}_h).$$

Proof:

$$\begin{aligned} 4 \|\nabla u - \mathcal{G}u_h\|_0^2 &= \|\nabla u - \mathbf{y}_h + \nabla u - \nabla u_h\|_0^2 \\ &= \|\nabla u - \mathbf{y}_h\|_0^2 + \|\nabla u - \nabla u_h\|_0^2 = \|\nabla u_h - \mathbf{y}_h\|_0^2 \end{aligned}$$



Handelling $\mathbf{Q}(f)$, $d = 2$, Ω simply connected



$$\bar{\mathbf{q}}(x_1, x_2) = - \left(\int_0^{x_1} f(s, x_2) ds, 0 \right)^T \Rightarrow -\operatorname{div} \bar{\mathbf{q}} = f$$

$$\mathbf{Q}(0) = \operatorname{curl} H^1(\Omega), \quad \operatorname{curl} = (\partial_2, -\partial_1)^T$$

$$\mathbf{Q}(f) = \bar{\mathbf{q}} + \mathbf{Q}(0) = \bar{\mathbf{q}} + \operatorname{curl} H^1(\Omega)$$

$$\text{(Comp)} \quad \mathbf{y} = \bar{\mathbf{q}} + \operatorname{curl} z \in \mathbf{Q}(f) : (\mathbf{y}, \mathbf{w}^0) = 0 \quad \forall \mathbf{w}^0 \in \mathbf{Q}(0)$$

$$\text{(Comp)} \quad z \in H^1(\Omega) : \underbrace{(\operatorname{curl} z, \operatorname{curl} v)}_{(\nabla z, \nabla v)} = -(\bar{\mathbf{q}}, \operatorname{curl} v) \quad \forall v \in H^1(\Omega)$$

Numerical example



Primal problem

$$\begin{aligned} -u'' + \kappa^2 u &= f \\ u(0) &= u(1) = 0 \end{aligned}$$

Complementary problem

$$\begin{aligned} -y'' + \kappa^2 y &= f' \quad \text{in } (0, 1) \\ y'(0) &= -f(0) \quad y'(1) = -f(1) \end{aligned}$$

$$f = 1, \quad \kappa = \text{const.}$$

$$u = \frac{1}{\kappa^2} \left(1 - \frac{\sinh \kappa(1-x) + \sinh \kappa x}{\sinh \kappa} \right), \quad y = u'$$



Numerical example

Primal problem

$$\begin{aligned} -u'' + \kappa^2 u &= f \\ u(0) = u(1) &= 0 \end{aligned}$$

Complementary problem

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FEM mesh

$$0 = x_0 < x_1 < \dots < x_M = 1 \quad K_i = [x_{i-1}, x_i], \quad i = 1, 2, \dots, M$$

Primal FEM

$$V_h = \{v_h \in H_0^1(0, 1) : v_h|_{K_i} \in P^1(K_i) \quad \forall K_i\}$$

$$u_h \in V_h : (u'_h, v'_h) + (\kappa^2 u_h, v_h) = (f, v_h) \quad \forall v_h \in V_h$$

Complementary FEM

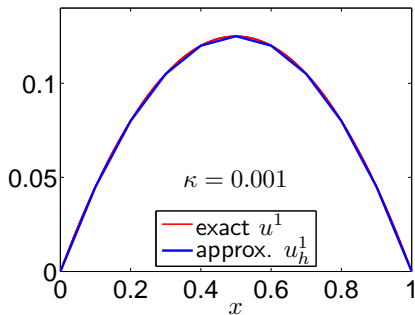
$$W_h = \{w_h \in H^1(0, 1) : w_h|_{K_i} \in P^1(K_i) \quad \forall K_i\}$$

$$y_h \in W_h : (y'_h, w'_h) + (\kappa^2 y_h, w_h) = -(f, w'_h) \quad \forall w_h \in W_h$$

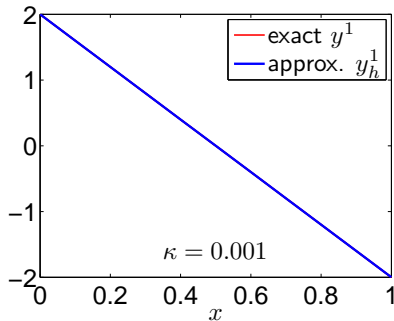
Primal and complementary solutions



Primal solution



Complementary sol.



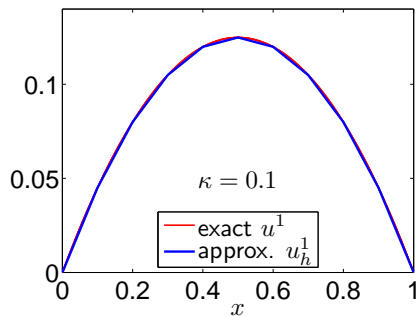
$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 9.486\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 9.440\% \quad \frac{\eta}{\|u\|} = 9.440\% \quad l_{eff} = 1.000$$

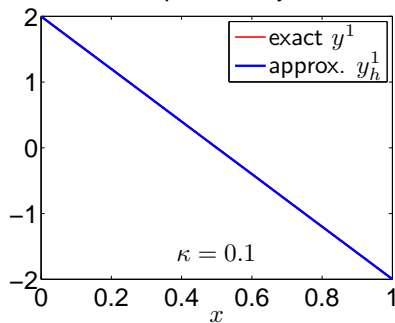
Primal and complementary solutions



Primal solution



Complementary sol.



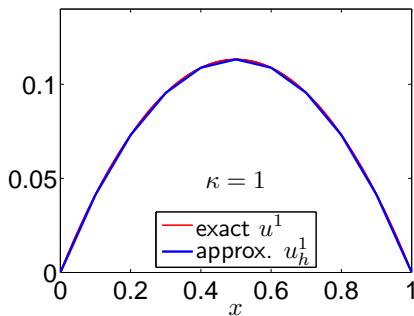
$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 9.486\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 9.436\% \quad \frac{\eta}{\|u\|} = 9.439\% \quad l_{eff} = 1.0003$$

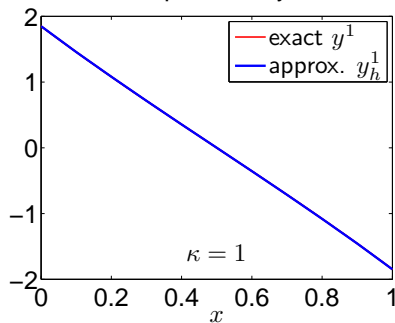
Primal and complementary solutions



Primal solution



Complementary sol.



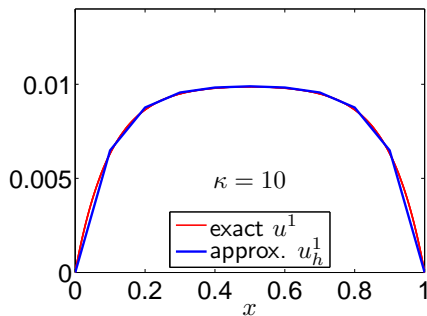
$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 9.530\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 9.158\% \quad \frac{\eta}{\|u\|} = 9.487\% \quad l_{eff} = 1.036$$

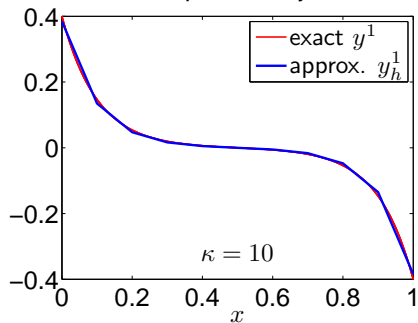
Primal and complementary solutions



Primal solution



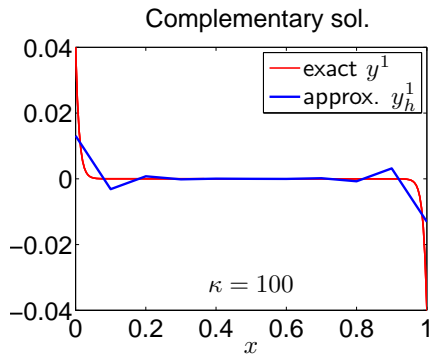
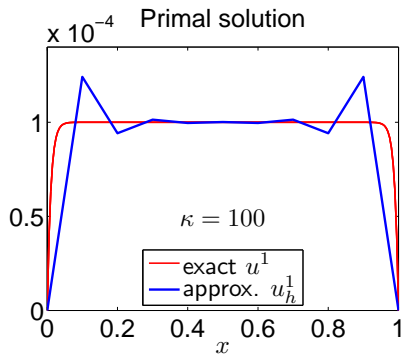
Complementary sol.



$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 13.45\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 9.617\% \quad \frac{\eta}{\|u\|} = 13.39\% \quad l_{eff} = 1.392$$

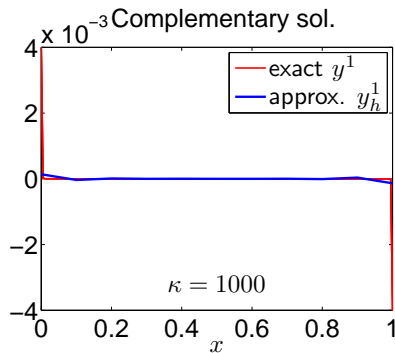
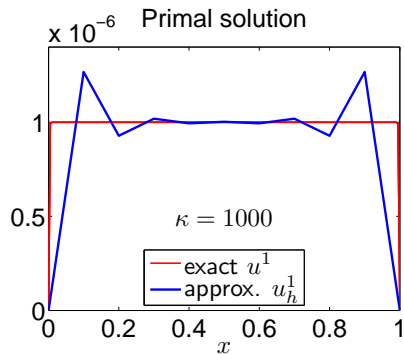
Primal and complementary solutions



$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 22.26\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 15.48\% \quad \frac{\eta}{\|u\|} = 21.99\% \quad l_{eff} = 1.420$$

Primal and complementary solutions



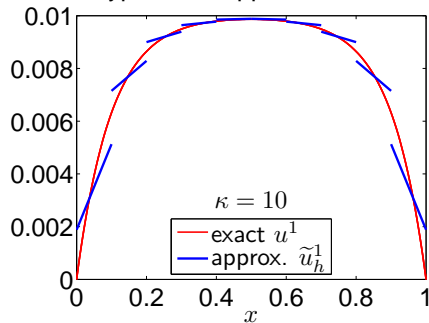
$$\frac{\|u - u_h\|}{\|u_h\|} \leq \frac{\eta}{\|u_h\|} = 22.23\%$$

$$\frac{\|u - u_h\|}{\|u\|} = 19.86\% \quad \frac{\eta}{\|u\|} = 21.90\% \quad l_{eff} = 1.103$$

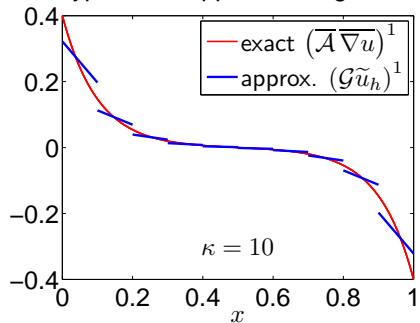
Method of hypercircle



Hypercircle approx. of values



Hypercircle approx. of cogradient



$$\frac{\| [u - \tilde{u}_h, \overline{\nabla} u - \mathcal{G} \tilde{u}_h] \|_{hc}}{\| u_h \|} = \frac{1}{2} \frac{\eta}{\| u_h \|} = 6.72 \%$$



- ▶ General elliptic problem (nonsymmetric)
- ▶ Elasticity
- ▶ Stokes problem (incompressible viscous fluids)
- ▶ Variational inequalities
- ▶ Nonlinear problems (special)
- ▶ Differential equations of higher order
- ▶ Equations with curl
- ▶ Linear evolutionary problems
- ▶ Optimal control

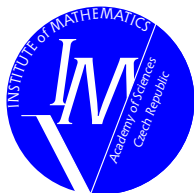
$$\|u - u_h\| \leq \eta(u_h, \mathbf{y}_h)$$

- ▶ Guaranteed upper bounds
- ▶ Optimal \mathbf{y} solves a complementary problem
- ▶ Postprocessing of ∇u_h
 - ⇒ fast algorithms for \mathbf{y}_h (many open problems)
- ▶ $u_h \in V$ arbitrary
 - ⇒ including algebraic errors, quadrature errors, human errors
 - ⇒ any conforming numerical method
 - including Splines and IsoGeometric Analysis

Thank you for your attention

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