

# A posteriori error estimates in the finite element method

## A survey of techniques

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# Outline



- ▶ Poisson equation
- ▶ Finite element method
- ▶ A priori error estimates
- ▶ A posteriori error estimates
  - ▶ Explicit residual
  - ▶ Implicit residual
  - ▶ Hierarchic (residual)
  - ▶ Error majorants
  - ▶ Postprocessing
  - ▶ Quantity of interest
- ▶ Adaptivity
- ▶ Numerical example
- ▶ A new result

# Poisson problem

- ▶ Classical formulation: find  $u \in C^2(\Omega) \cap C(\bar{\Omega})$  :

$$-\Delta u = f \quad \text{in } \Omega \qquad u = 0 \quad \text{on } \partial\Omega$$

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- ▶ Weak formulation:  $V = H_0^1(\Omega)$

$$\begin{aligned} u \in V : \quad & \underbrace{\mathcal{B}(u, v)}_{\int_{\Omega} \nabla u \cdot \nabla v \, dx} = \underbrace{\mathcal{F}(v)}_{\int_{\Omega} fv \, dx} \quad \forall v \in V \end{aligned}$$

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- ▶ Galerkin method  $V_h \subset V \quad \dim V_h < \infty$

$$u_h \in V_h : \quad \mathcal{B}(u_h, v_h) = \mathcal{F}(v_h) \quad \forall v_h \in V_h \quad \Leftrightarrow \quad Ay = F$$

$$u_h(x) = \sum_{j=1}^N y_j \varphi_j(x) \quad \sum_{j=1}^N y_j \underbrace{\mathcal{B}(\varphi_j, \varphi_i)}_{A_{ij}} = \underbrace{\mathcal{F}(\varphi_i)}_{F_i}$$

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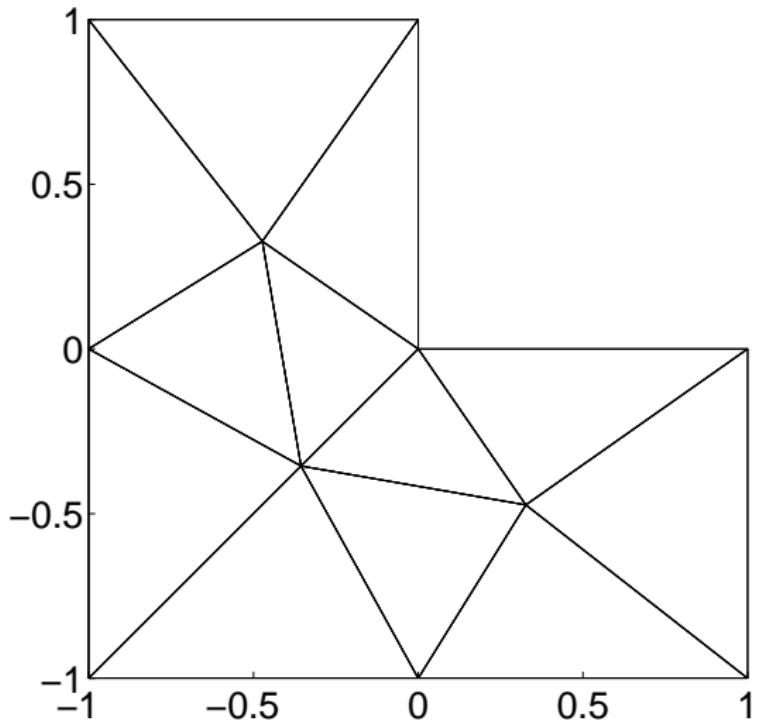
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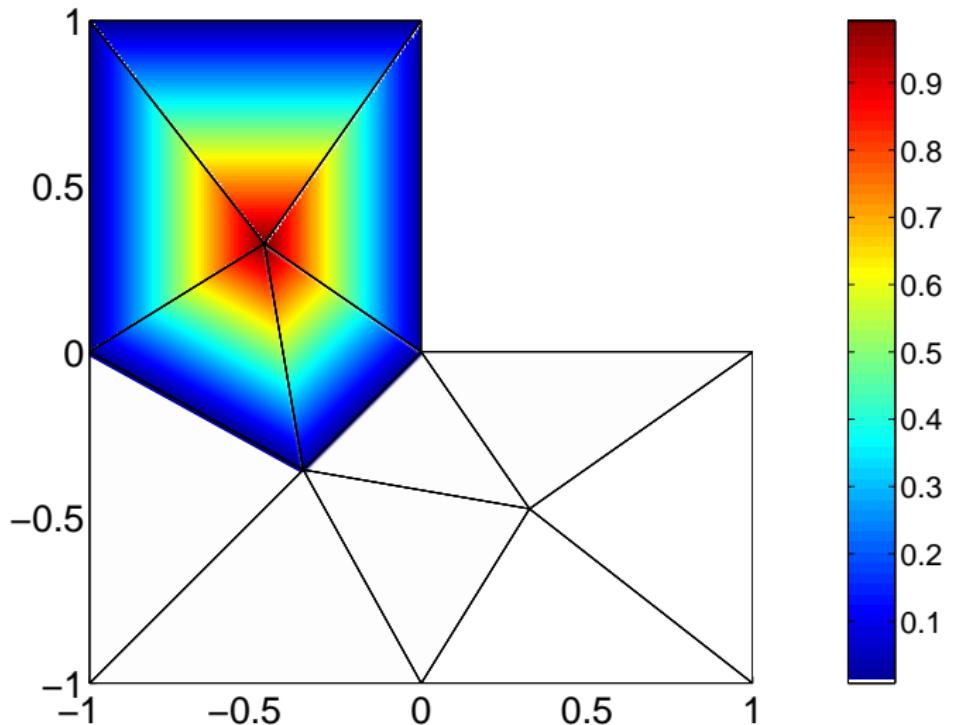
- ▶ FEM  $V_h = \{v_h \in V : v_h|_K \in P^1(K) \ \forall K \in \mathcal{T}_h\}$

$\varphi_1, \dots, \varphi_N \dots$  FEM basis functions  $\varphi_i(x_j) = \delta_{ij}$

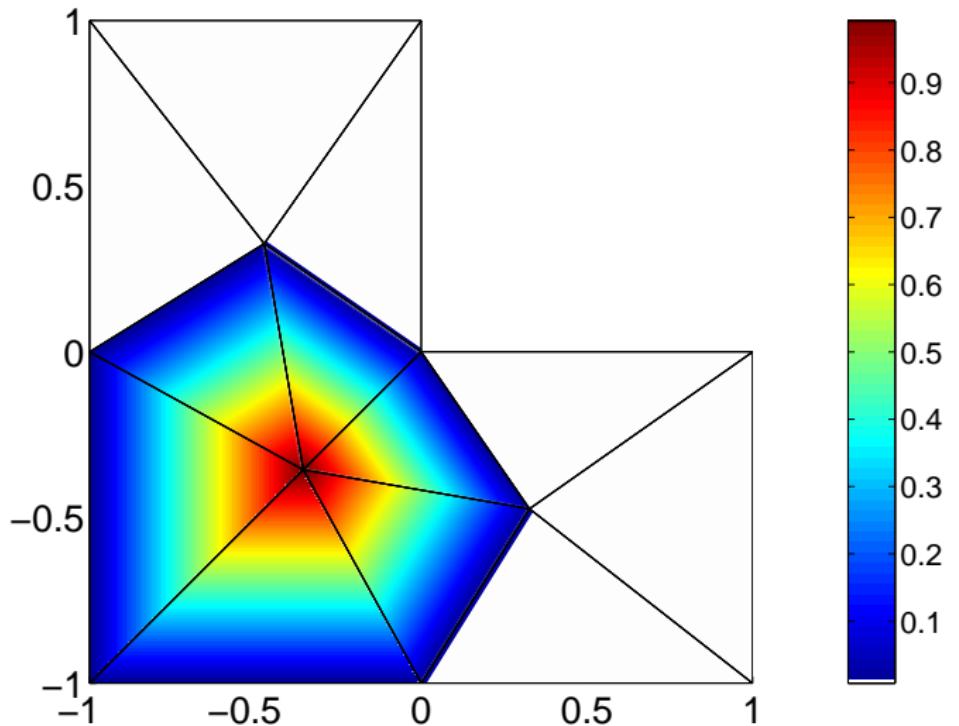
Mesh 1



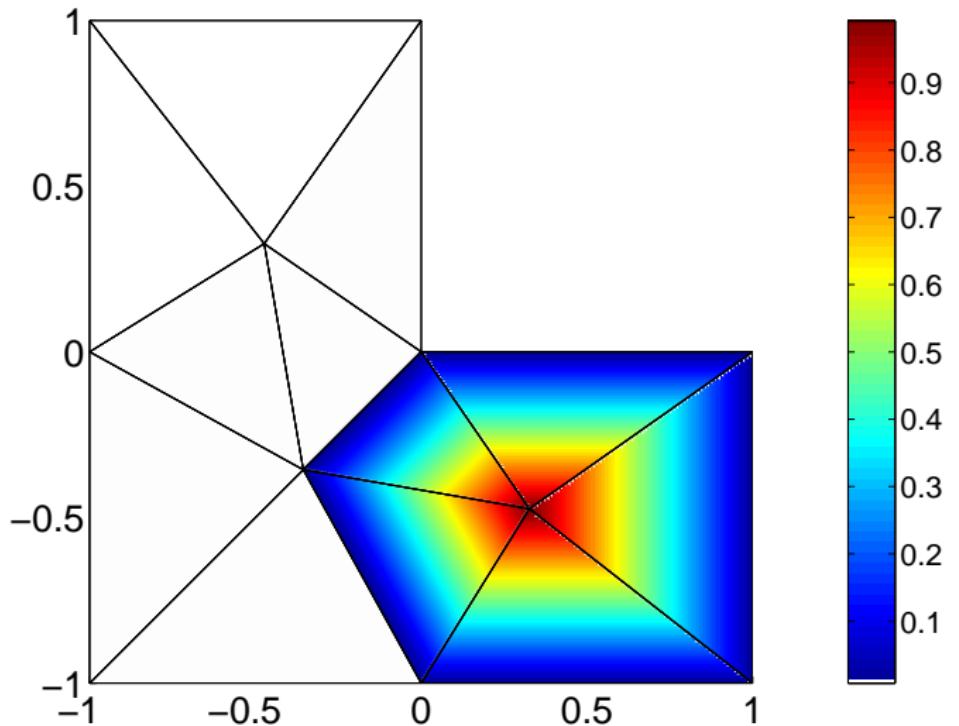
# FEM



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# A priori error estimates

- ▶ Discretization error:  $e = u - u_h$
- ▶ Energy norm:  $\|u\|^2 = \mathcal{B}(u, u) = \|u\|_{H^1(\Omega)}^2$
- ▶ Céa's lemma:  $\|e\| = \inf_{v_h \in V_h} \|u - v_h\| = \text{dist}(u, V_h)$
- ▶ Lagrange interpolation:  $\pi_h^{\text{Lag}} : C(\bar{\Omega}) \mapsto V_h$   
 $v \in H^2(\Omega) \cap C(\bar{\Omega}) \quad \Rightarrow \quad \|v - \pi_h^{\text{Lag}} v\|_{H^1(\Omega)} \leq C h |v|_{H^2(\Omega)}$
- ▶  $u \in H^2(\Omega) \cap C(\bar{\Omega}) \quad \Rightarrow \quad \|e\| \leq C h |u|_{H^2(\Omega)}$

# A posteriori error estimates

## Definition

- ▶  $\|e\| \approx \eta$  (or  $\|e\| \leq \eta$ , or  $\eta \leq \|e\|$ )
- ▶  $\eta = \eta(u_h, f, \Omega, \mathcal{T}_h, \dots)$

## Properties

- ▶ Local:  $\eta^2 = \sum_{K \in \mathcal{T}_h} \eta_K^2$
- ▶ Guaranteed upper (lower) bound:  $\|e\| \leq \eta$  ( $\eta \leq \|e\|$ )
- ▶ Asymptotic exactness:  $\lim_{h \rightarrow 0} \frac{\eta}{\|e\|} = 1$ ,  $I_{\text{eff}} = \frac{\eta}{\|e\|}$
- ▶ Efficient and reliable:  $C_1 \eta \leq \|e\| \leq C_2 \eta$
- ▶ Robust:  $C_1$  and  $C_2$  are independent from quantities like coefficients in the equation, mesh aspect ratio etc.

# Residual estimates

$$u \in V : \quad \mathcal{B}(u, v) = \mathcal{F}(v) \quad \forall v \in V$$

$$u_h \in V_h : \quad \mathcal{B}(u_h, v_h) = \mathcal{F}(v_h) \quad \forall v_h \in V_h$$

- ▶ Residual:  $\mathcal{R}(v) = \mathcal{F}(v) - \mathcal{B}(u_h, v) \quad \forall v \in V$
- ▶ Residual equation:  $e \in V : \quad \mathcal{B}(e, v) = \mathcal{R}(v) \quad \forall v \in V$   

$$\left[ \mathcal{B}(u, v) - \mathcal{B}(u_h, v) = \mathcal{F}(v) - \mathcal{B}(u_h, v) \quad \forall v \in V \right]$$
- ▶ Galerkin orthogonality:  $\mathcal{B}(e, v_h) = 0 \quad \forall v_h \in V_h$
- ▶  $\|e\| = \sup_{0 \neq v \in V} \frac{|\mathcal{B}(e, v)|}{\|v\|} = \sup_{0 \neq v \in V} \frac{|\mathcal{R}(v)|}{\|v\|} = \|\mathcal{R}\|_{V^*}$

# Explicit residual estimates

- ▶ Residual splitting:  $\mathcal{R}(v) = \sum_{K \in \mathcal{T}_h} \int_K r v \, dx + \sum_{\ell} \int_{\ell} J_{\ell} v \, ds$   
 $r = f + \Delta u_h \quad J_{\ell} = (\nabla u_h^+ - \nabla u_h^-) \cdot \nu_{\ell}$

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$$\begin{aligned}
 \mathcal{R}(v) &= \mathcal{F}(v) - \mathcal{B}(u_h, v) = \sum_{K \in \mathcal{T}_h} \left( \int_K fv \, dx - \int_K \nabla u_h \cdot \nabla v \, dx \right) \\
 &= \sum_{K \in \mathcal{T}_h} \left( \int_K fv \, dx + \int_K \Delta u_h v \, dx - \int_{\partial K} \nabla u_h \cdot \nu_K v \, ds \right) \\
 &= \sum_{K \in \mathcal{T}_h} \int_K rv \, dx + \sum_{\ell} \int_{\ell} (\nabla u_h^+ - \nabla u_h^-) \cdot \nu_{\ell} v \, ds
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 $r = f + \Delta u_h \quad J_{\ell} = (\nabla u_h^+ - \nabla u_h^-) \cdot \nu_{\ell}$
- ▶ Clément inter.:  $\pi_h^{\text{Cl}} : V \mapsto V_h \quad \|v - \pi_h^{\text{Cl}} v\|_{0,K} \leq C_1 |K|^{1/2} \|\nabla v\|_{0,\omega_K}$   
 $\|v - \pi_h^{\text{Cl}} v\|_{0,\ell} \leq C_2 |\ell|^{1/2} \|\nabla v\|_{0,\omega_{\ell}}$

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$$\begin{aligned}
 \|e\|^2 &= \mathcal{B}(e, e) = \mathcal{R}(e) = \mathcal{R}(e - \pi_h^{\text{Cl}} e) \\
 &= \sum_{K \in \mathcal{T}_h} \int_K r(e - \pi_h^{\text{Cl}} e) \, dx + \sum_{\ell} \int_{\ell} J_{\ell}(e - \pi_h^{\text{Cl}} e) \, ds \\
 &\leq \sum_{K \in \mathcal{T}_h} C_1 \|r\|_{0,K} |K|^{1/2} \|\nabla e\|_{0,\omega_K} + \sum_{\ell} C_2 \|J_{\ell}\|_{0,\ell} |\ell|^{1/2} \|\nabla e\|_{0,\omega_{\ell}} \\
 &\leq C_3 \left( \sum_{K \in \mathcal{T}_h} |K| \|r\|_{0,K}^2 + \sum_{\ell} |\ell| \|J_{\ell}\|_{0,\ell}^2 \right) + \varepsilon \|e\|^2
 \end{aligned}$$

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$$\|e\|^2 \leq C_4 \underbrace{\left( \sum_{K \in \mathcal{T}_h} |K| \|r\|_{0,K}^2 + \sum_{\ell} |\ell| \|J_{\ell}\|_{0,\ell}^2 \right)}_{(\eta^{\text{expl}})^2}$$

# Implicit residual estimates – Dirichlet

- ▶ Local Dirichlet problems:

$$e_K^{\text{Dir}} \in H_0^1(K) : \quad \mathcal{B}(e_K^{\text{Dir}}, v) = \mathcal{R}(v) \quad \forall v \in H_0^1(K)$$

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- ▶ Approximate local problems:  $V_{0,h}(K) \subset H_0^1(K)$

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- ▶  $e^{\text{Dir}}|_K = e_K^{\text{Dir}} \quad \forall K \in \mathcal{T}_h; \quad V_0 = \{v \in V : v|_K \in H_0^1(K)\} \subset V$

- ▶  $e_h^{\text{Dir}}|_K = e_{K,h}^{\text{Dir}} \quad \forall K \in \mathcal{T}_h; \quad V_{0,h} = \{v \in V : v|_K \in V_{0,h}(K)\} \subset V_0$

- ▶ **Theorem:**  $\|e_h^{\text{Dir}}\| \leq \|e^{\text{Dir}}\| \leq \|e\|$

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- **Theorem:**  $\|e_h^{\text{Dir}}\| \leq \|e^{\text{Dir}}\| \leq \|e\|$

Proof:

- $e^{\text{Dir}} \in V_0 \quad v \in V_0$

$$\mathcal{B}(e - e^{\text{Dir}}, v) = \mathcal{R}(v) - \mathcal{R}(v) = 0$$

$$\Rightarrow \quad \mathcal{B}(e, e^{\text{Dir}}) = \|e^{\text{Dir}}\|^2$$

$$\begin{aligned} \Rightarrow \quad \|e - e^{\text{Dir}}\|^2 &= \|e\|^2 - 2\mathcal{B}(e, e^{\text{Dir}}) + \|e^{\text{Dir}}\|^2 \\ &= \|e\|^2 - \|e^{\text{Dir}}\|^2 \end{aligned}$$

- $\mathcal{B}(e^{\text{Dir}} - e_h^{\text{Dir}}, v_h) = \mathcal{R}(v_h) - \mathcal{R}(v_h) = 0 \quad \forall v_h \in V_{0,h}$

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- **Theorem:**  $\|e_h^{\text{Dir}}\| \leq \|e^{\text{Dir}}\| \leq \|e\|$

- $\eta_K^{\text{Dir}} = \|e_{K,h}^{\text{Dir}}\|_K \quad (\eta^{\text{Dir}})^2 = \sum_{K \in \mathcal{T}_h} (\eta_K^{\text{Dir}})^2$

# Implicit residual estimates – Neumann

- $e_K^{\text{Neu}} \in H_E^1(K) = \{v \in H^1(K) : v = 0 \text{ on } \partial K \cap \partial\Omega\}$ :

$$\mathcal{B}_K(e_K^{\text{Neu}}, v) = \int_K fv \, dx - \mathcal{B}_K(u_h, v) + \int_{\partial K} g_K v \, ds \quad \forall v \in H_E^1(K)$$

$$\mathcal{B}_K(u, v) = \int_K \nabla u \cdot \nabla v \, dx$$

$$-\Delta(e_K^{\text{Neu}} + u_h) = f \quad \text{in } K$$

$$\nabla(e_K^{\text{Neu}} + u_h) \cdot \nu_K = g_K \quad \text{on } \partial K \setminus \partial\Omega$$

$$e_K^{\text{Neu}} + u_h = 0 \quad \text{on } \partial K \cap \partial\Omega$$

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- $g_K|_\ell \in P^1(\ell)$ ,  $\ell \subset \partial K$ ,  $K \in \mathcal{T}_h$ ,     $g_K \approx \nabla u|_K \cdot \nu_K$  on  $\partial K$
- $g_K|_\ell + g_{K^*}|_\ell = 0$  for  $\ell = \partial K \cap \partial K^*$

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► Theorem:  $\|e\|^2 \leq \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K^2$        $\|v\|_K^2 = \mathcal{B}_K(v, v)$

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- **Theorem:**  $\|e\|^2 \leq \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K^2 \quad \|v\|_K^2 = \mathcal{B}_K(v, v)$

Proof:  $v \in V$

$$\begin{aligned} \mathcal{B}(e, v) &= \mathcal{R}(v) = \sum_{K \in \mathcal{T}_h} \left( \int_K fv \, dx - \mathcal{B}_K(u_h, v) + \int_{\partial K} g_K v \, ds \right) \\ &= \sum_{K \in \mathcal{T}_h} \mathcal{B}_K(e_K^{\text{Neu}}, v) \leq \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K \|v\|_K \leq \left( \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K^2 \right)^{\frac{1}{2}} \|v\| \end{aligned}$$

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- $g_K|_\ell + g_{K^*}|_\ell = 0$  for  $\ell = \partial K \cap \partial K^*$
- **Theorem:**  $\|e\|^2 \leq \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K^2 \quad \|v\|_K^2 = \mathcal{B}_K(v, v)$
- **Remark:** Approximate Neumann problems:  
 $e_{K,h}^{\text{Neu}} \in V_h^{\text{Neu}} \subset H_E^1(K) \Rightarrow \sum_{K \in \mathcal{T}_h} \|e_{K,h}^{\text{Neu}}\|_K^2 \leq \sum_{K \in \mathcal{T}_h} \|e_K^{\text{Neu}}\|_K^2$
- $\eta_K^{\text{Neu}} = \|e_{K,h}^{\text{Neu}}\|_K \quad (\eta^{\text{Neu}})^2 = \sum_{K \in \mathcal{T}_h} (\eta_K^{\text{Neu}})^2$

In general:  $\|e\| \not\leq \eta^{\text{Neu}}$

# Hierarchic (residual) estimates

- ▶  $\widehat{V}_h = V_h \oplus Y_h \quad Y_h \subset V \quad V_h \cap Y_h = \{0\}$
- ▶  $\widehat{u}_h \in \widehat{V}_h : \quad \mathcal{B}(\widehat{u}_h, \widehat{v}_h) = \mathcal{F}(\widehat{v}_h) \quad \forall \widehat{v}_h \in \widehat{V}_h$

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- ▶  $\|e\| \approx \|\widehat{u}_h - u_h\| \equiv \|\widehat{e}_h\|$
- ▶  $\overline{e}_h \in Y_h : \quad \mathcal{B}(\overline{e}_h, y_h) = \mathcal{R}(y_h) \quad \forall y_h \in Y_h$
- ▶  $\|e\| \approx \|\overline{e}_h\| \equiv \eta^{\text{Hie}}$

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- ▶  $\widehat{u}_h \in \widehat{V}_h : \quad \mathcal{B}(\widehat{u}_h, \widehat{v}_h) = \mathcal{F}(\widehat{v}_h) \quad \forall \widehat{v}_h \in \widehat{V}_h$
- ▶  $\|e\| \approx \|\widehat{u}_h - u_h\| \equiv \|\widehat{e}_h\|$
- ▶  $\overline{e}_h \in Y_h : \quad \mathcal{B}(\overline{e}_h, y_h) = \mathcal{R}(y_h) \quad \forall y_h \in Y_h$
- ▶  $\|e\| \approx \|\overline{e}_h\| \equiv \eta^{\text{Hie}}$
- ▶ Saturation assumption:  
 $\exists \beta < 1: \quad \|u - \widehat{u}_h\| \leq \beta \|u - u_h\|$
- ▶ Strenghtened Cauchy-Schwarz inequality:  
 $\exists \gamma < 1: \quad |\mathcal{B}(v_h, y_h)| \leq \gamma \|v_h\| \|y_h\| \quad \forall v_h \in V_h, y_h \in Y_h$
- ▶  $\|\overline{e}_h\| \leq \|\widehat{e}_h\| \leq \|e\| \leq \frac{1}{(1 - \beta^2)^{\frac{1}{2}}} \|\widehat{e}_h\| \leq \frac{1}{(1 - \beta^2)^{\frac{1}{2}}(1 - \gamma^2)^{\frac{1}{2}}} \|\overline{e}_h\|$

# Error majorants

- ▶ Friedrichs inequality:  $\|v\|_{0,\Omega} \leq C_\Omega \|\nabla v\|_{0,\Omega} \quad \forall v \in V = H_0^1(\Omega)$
- ▶  $\|e\| \leq C_\Omega \|f + \operatorname{div} \mathbf{y}\|_{0,\Omega} + \|\mathbf{y} - \nabla u_h\|_{0,\Omega} \quad \forall \mathbf{y} \in \mathbf{H}(\operatorname{div}, \Omega)$

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Proof:

$$v \in V \quad \mathbf{y} \in \mathbf{H}(\operatorname{div}, \Omega)$$

$$\begin{aligned} \mathcal{B}(e, v) &= \mathcal{R}(v) + \int_{\Omega} \mathbf{y} \cdot \nabla v \, dx + \int_{\Omega} \operatorname{div} \mathbf{y} v \, dx + \int_{\partial\Omega} \mathbf{y} \cdot \nu v \, ds \\ &= \int_{\Omega} (f + \operatorname{div} \mathbf{y}) v \, dx + \int_{\Omega} (\mathbf{y} - \nabla u_h) \cdot \nabla v \, dx \\ &\leq \|f + \operatorname{div} \mathbf{y}\|_{0,\Omega} \|v\|_{0,\Omega} + \|\mathbf{y} - \nabla u_h\|_{0,\Omega} \|\nabla v\|_{0,\Omega} \\ &\leq \left( C_\Omega \|f + \operatorname{div} \mathbf{y}\|_{0,\Omega} + \|\mathbf{y} - \nabla u_h\|_{0,\Omega} \right) \|\nabla v\|_{0,\Omega} \\ &\leq \frac{1}{2} \left( C_\Omega \|f + \operatorname{div} \mathbf{y}\|_{0,\Omega} + \|\mathbf{y} - \nabla u_h\|_{0,\Omega} \right)^2 + \frac{1}{2} \|\nabla v\|_{0,\Omega}^2 \end{aligned}$$

# Postprocessing

- ▶ Recovered gradient:  $\nabla u_h \mapsto \mathcal{G}(u_h)$
- ▶  $\|e\| \approx \eta^{\text{post}} = \|\mathcal{G}(u_h) - \nabla u_h\|_{0,\Omega}$

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- ▶ Superconvergence:  $\|\nabla u - \mathcal{G}(u_h)\|_{0,\Omega} \leq C_1 h^{1+\epsilon}$
- ▶ Assumption:  $\|e\| \geq C_2 h$
- ▶ Theorem:  $\lim_{h \rightarrow 0} \frac{\eta^{\text{post}}}{\|e\|} = 1$

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Proof:

$$\frac{\eta^{\text{post}}}{\|e\|} \leq \frac{\|\nabla u - \nabla u_h\|_0}{\|e\|} + \frac{\|\nabla u - \mathcal{G}(u_h)\|_0}{\|e\|} \leq 1 + \frac{C_1 h^{1+\epsilon}}{C_2 h} \rightarrow 1$$

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# Quantity of interest

- ▶ Quantity of interest:  $\Phi \in V^*$
- ▶ Adjoint problem:  $z \in V : \quad \mathcal{B}(v, z) = \Phi(v) \quad \forall v \in V$
- ▶ Approx. adjoint prob.:  $z_h \in V_h : \quad \mathcal{B}(v_h, z_h) = \Phi(v_h) \quad \forall v_h \in V_h$
- ▶ Error representation formula:

$$\Phi(e) = \mathcal{B}(e, z) = \mathcal{R}(z) = \mathcal{R}(z - z_h) = \mathcal{B}(u - u_h, z - z_h)$$

$$\begin{aligned} |\Phi(e)| &\leq \|u - u_h\| \|z - z_h\| \\ &\leq \eta^{\text{pri}} \eta^{\text{adj}} \end{aligned}$$

# Adaptive algorithm

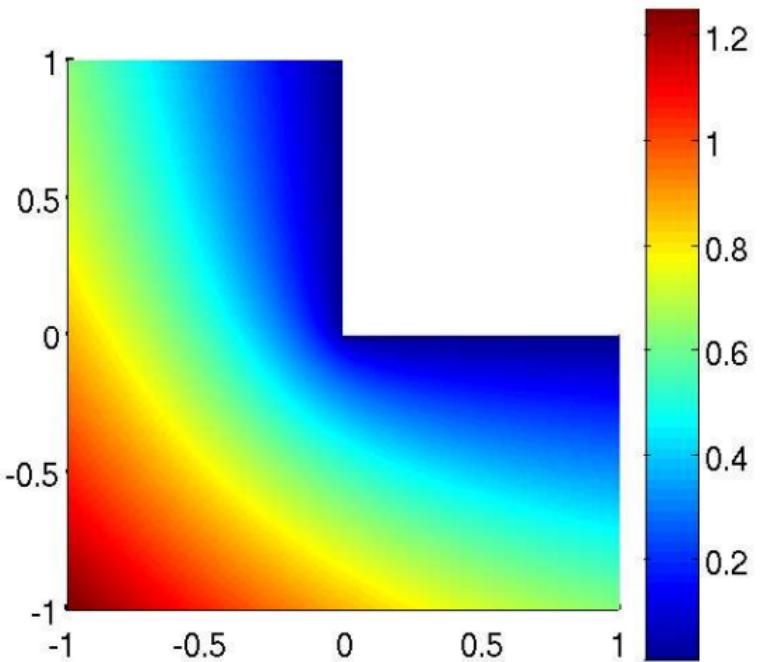
1. Construct the initial mesh  $\mathcal{T}_h$ .
2. Find  $u_h$  on  $\mathcal{T}_h$ .
3. Compute  $\eta_K$  for all  $K \in \mathcal{T}_h$ .
4. If  $\sum_{K \in \mathcal{T}_h} \eta_K^2 \leq \text{TOL}^2 \Rightarrow \text{STOP.}$
5. If  $\eta_K \geq \Theta \eta_{K,\max} \Rightarrow \text{mark } K.$        $0 < \Theta < 1$
6. Refine marked elements and build the new mesh  $\mathcal{T}_h$ .
7. GO TO 2.

# Example

$$-\Delta u = 0 \quad \text{in } \Omega$$

$$u = g_D \quad \text{on } \partial\Omega$$

$$u = r^{\frac{2}{3}} \sin \frac{2\theta - \pi}{3}$$

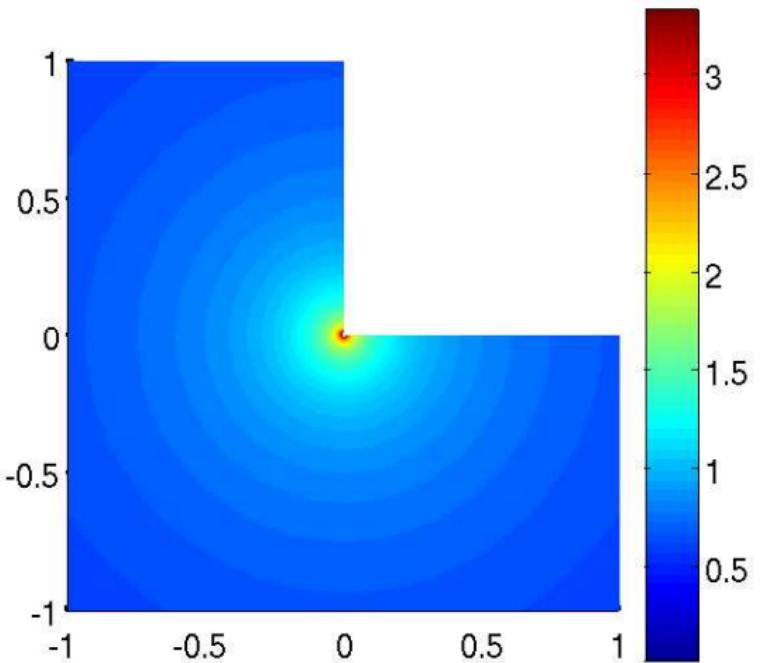


# Example

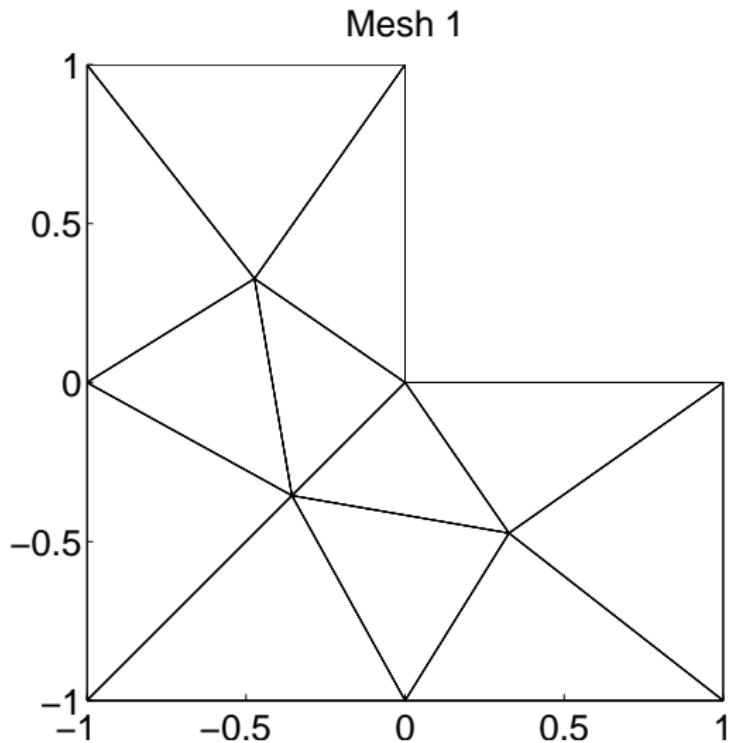
$$-\Delta u = 0 \quad \text{in } \Omega$$

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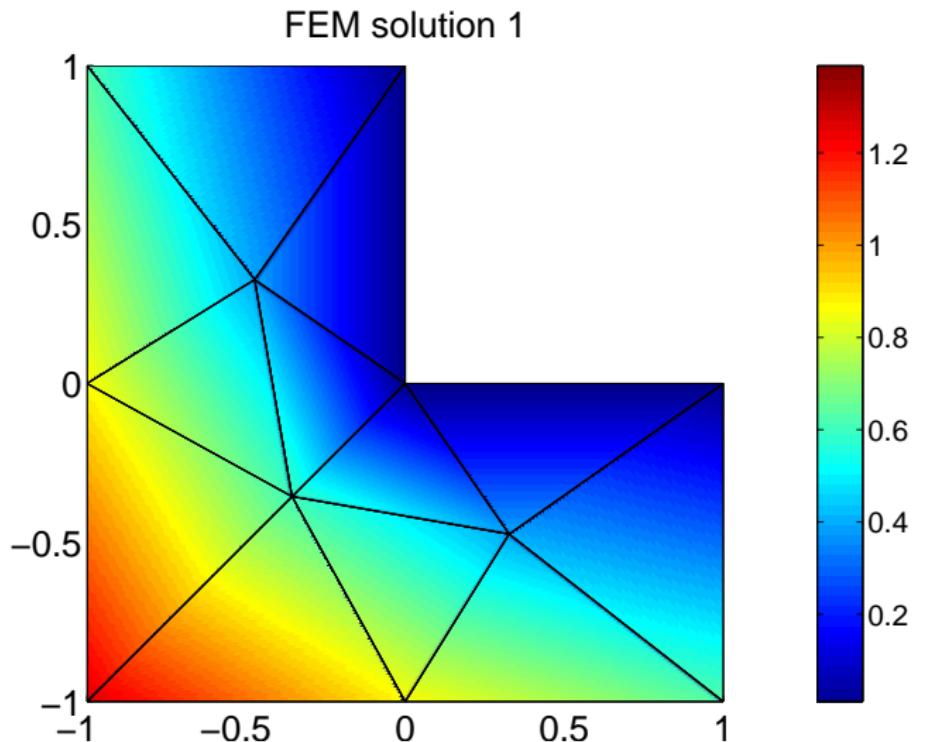
$$u = r^{\frac{2}{3}} \sin \frac{2\theta - \pi}{3}$$



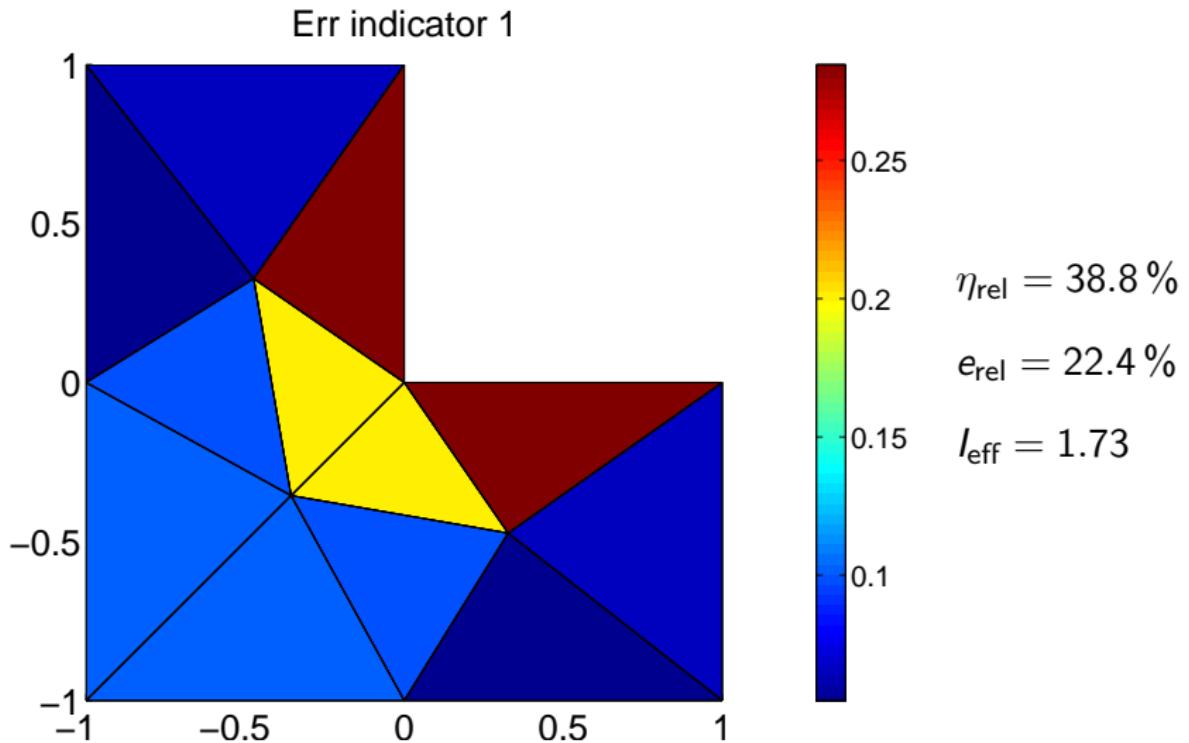
# Adaptive algorithm



# Adaptive algorithm

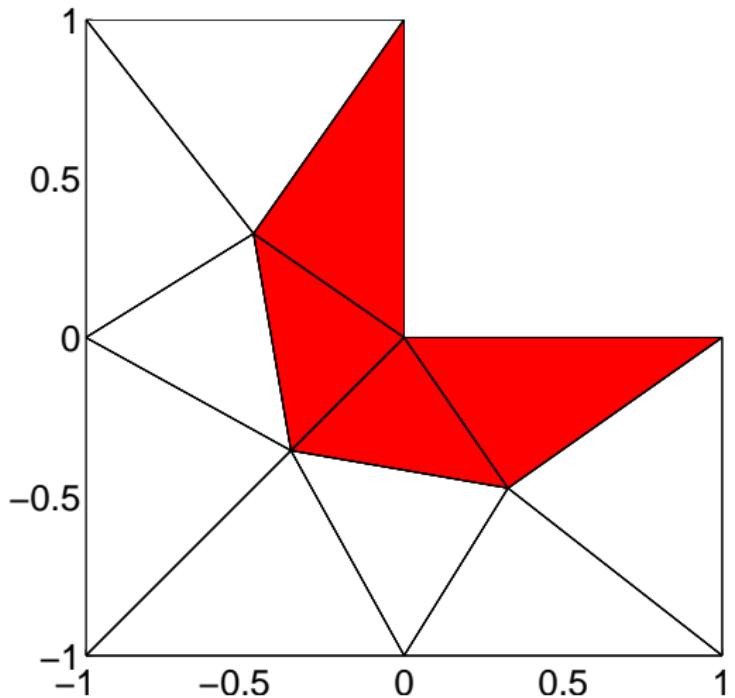


# Adaptive algorithm

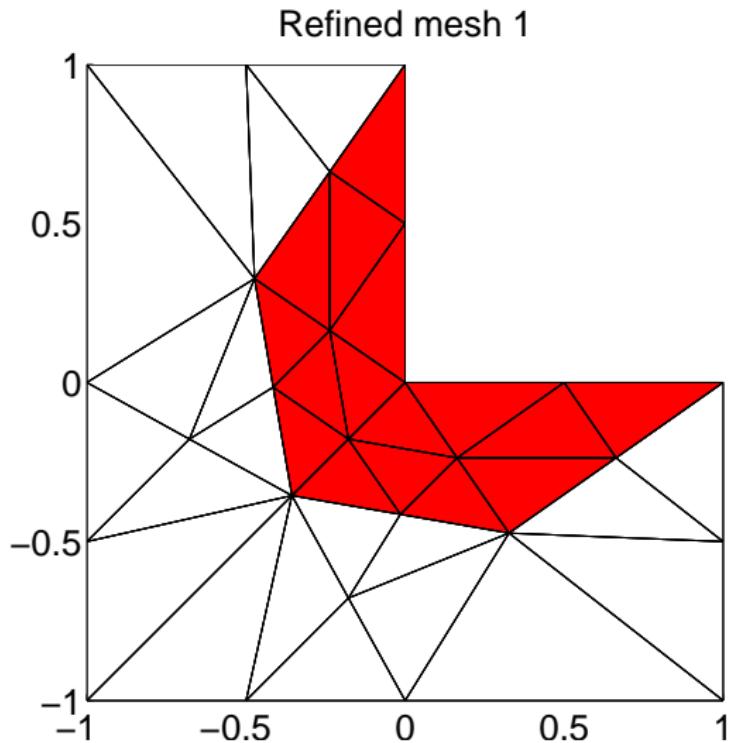


# Adaptive algorithm

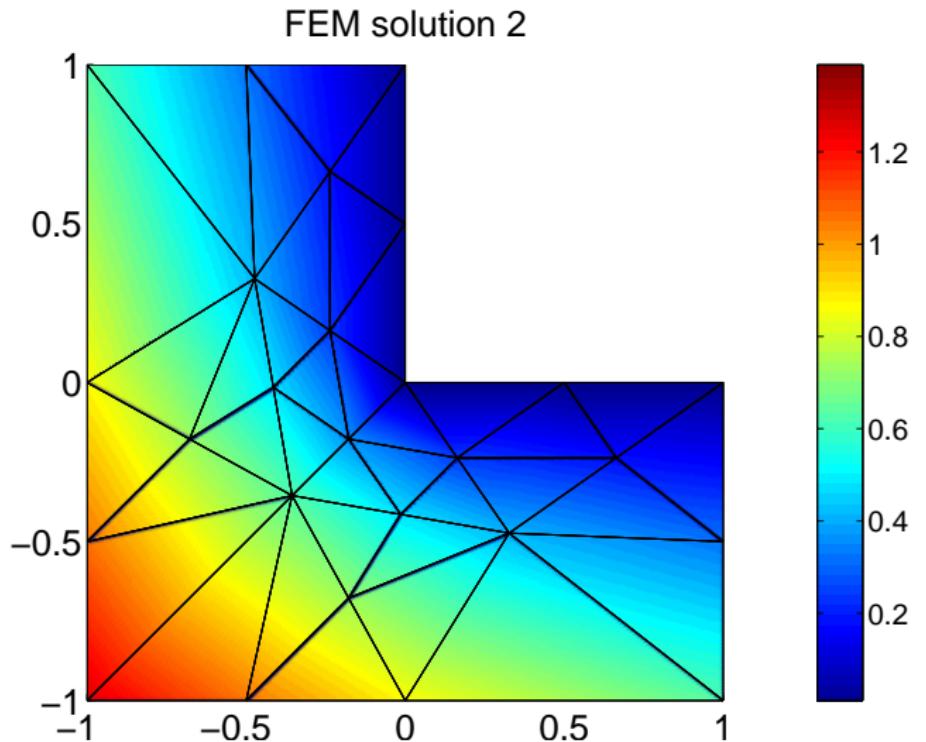
Marked elements 1



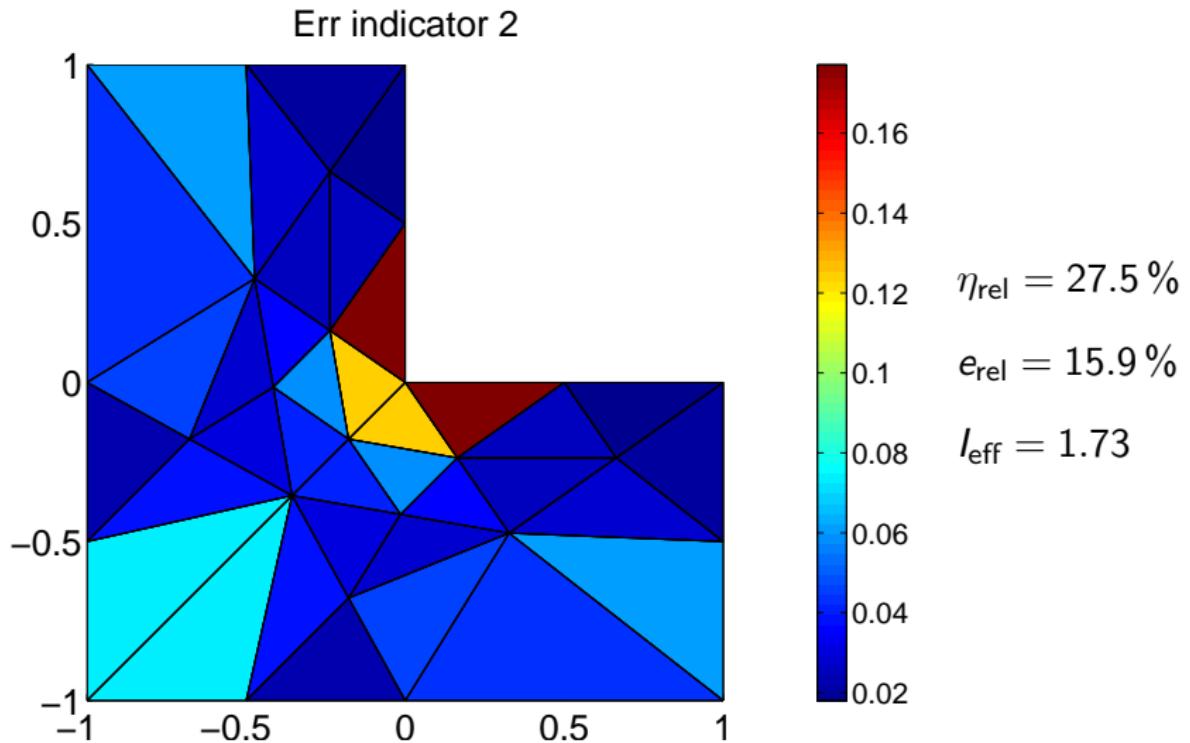
# Adaptive algorithm



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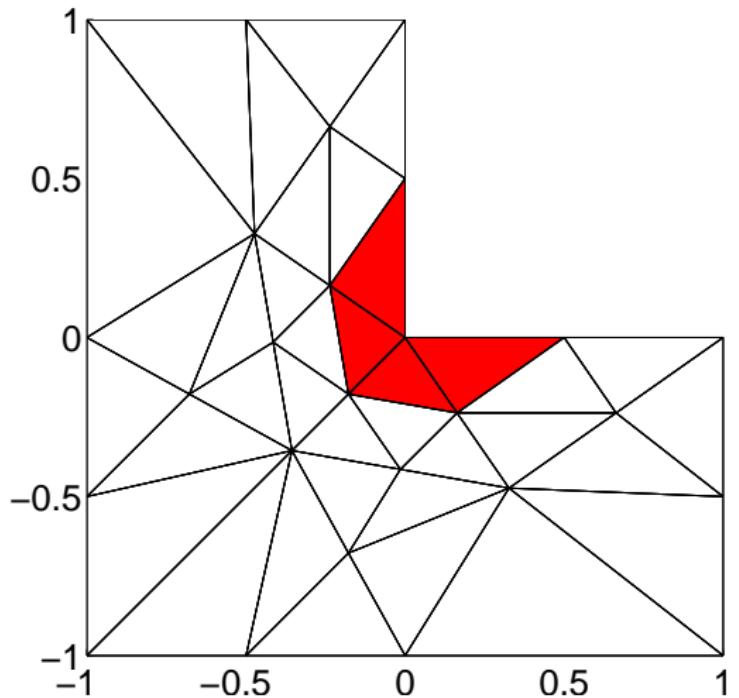


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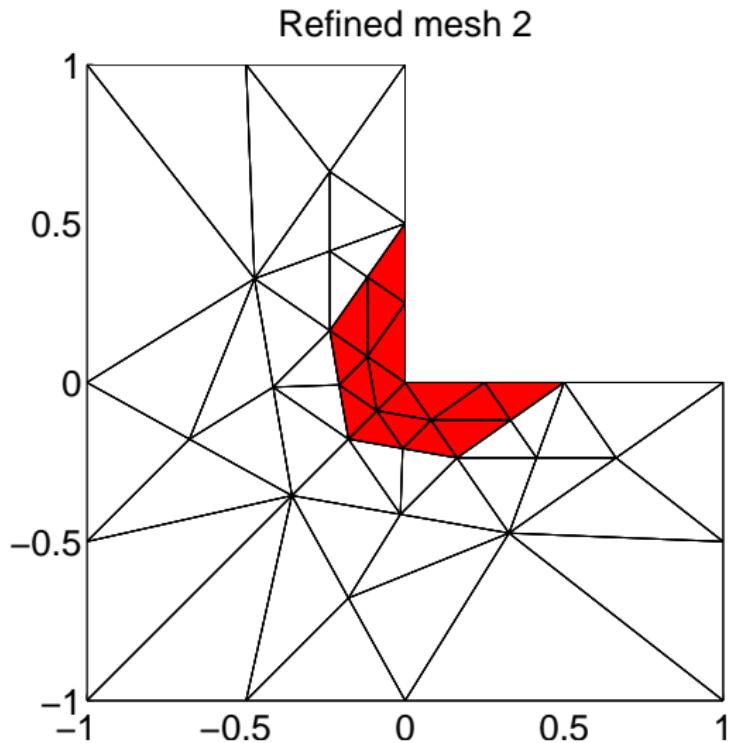


# Adaptive algorithm

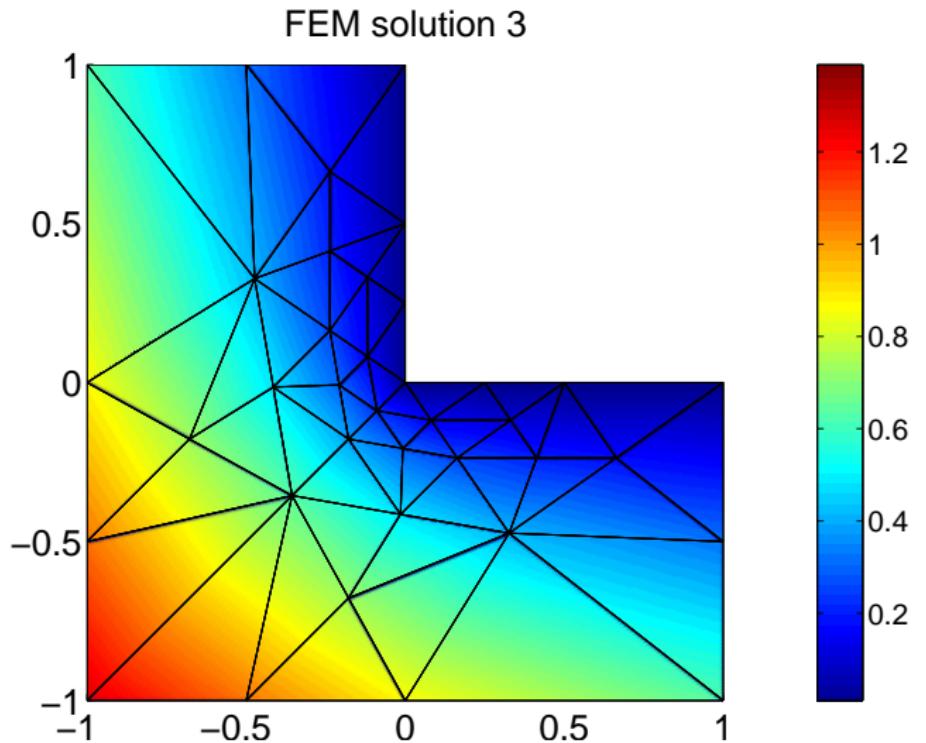
Marked elements 2



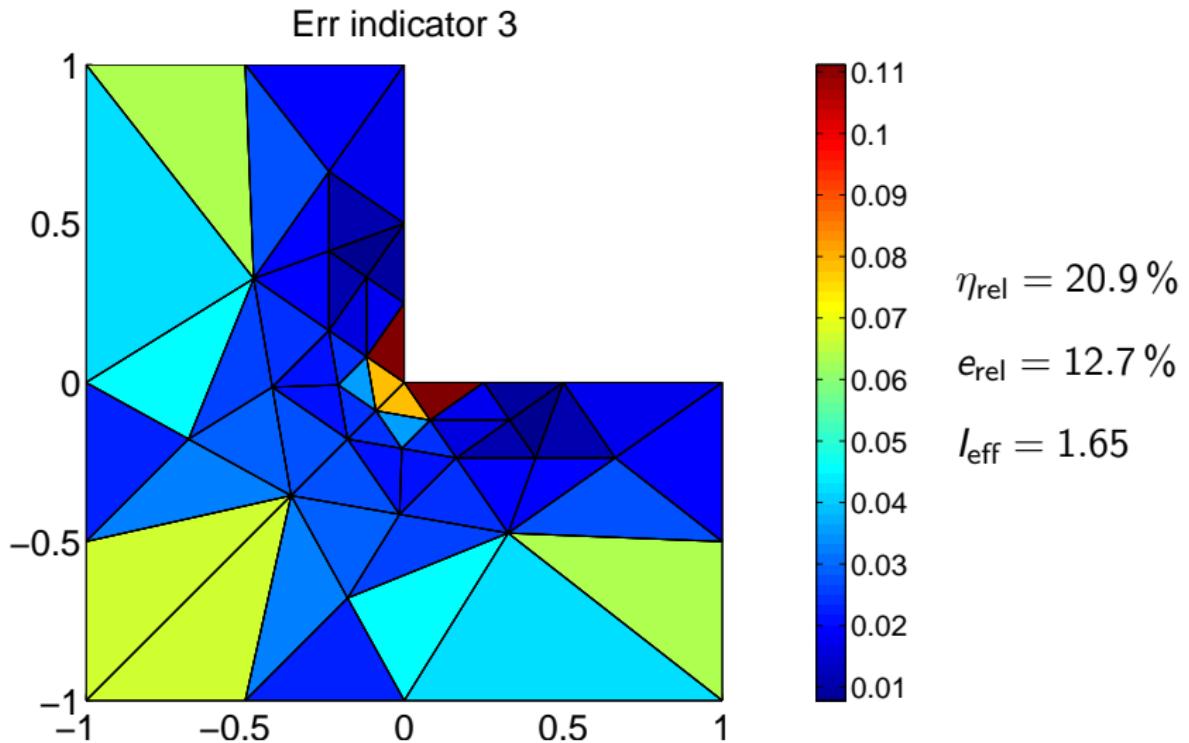
# Adaptive algorithm



# Adaptive algorithm

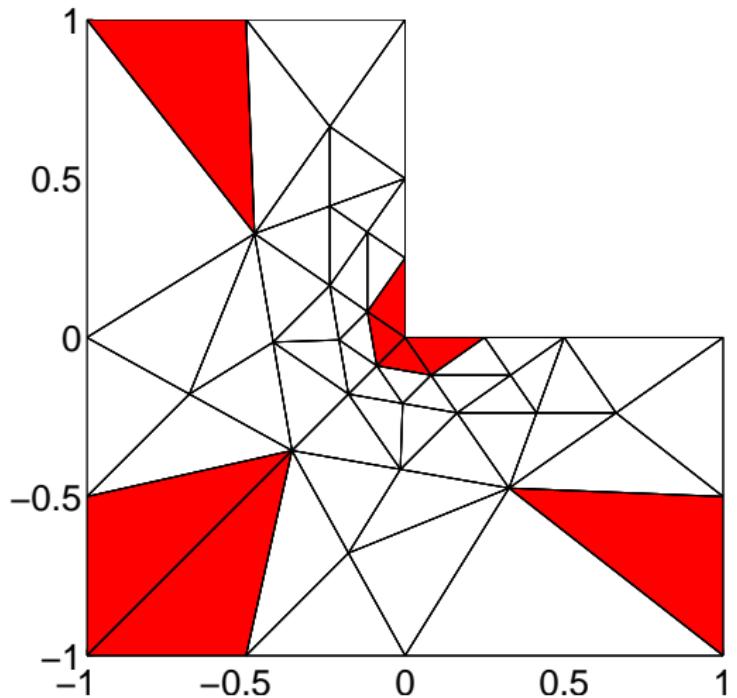


# Adaptive algorithm



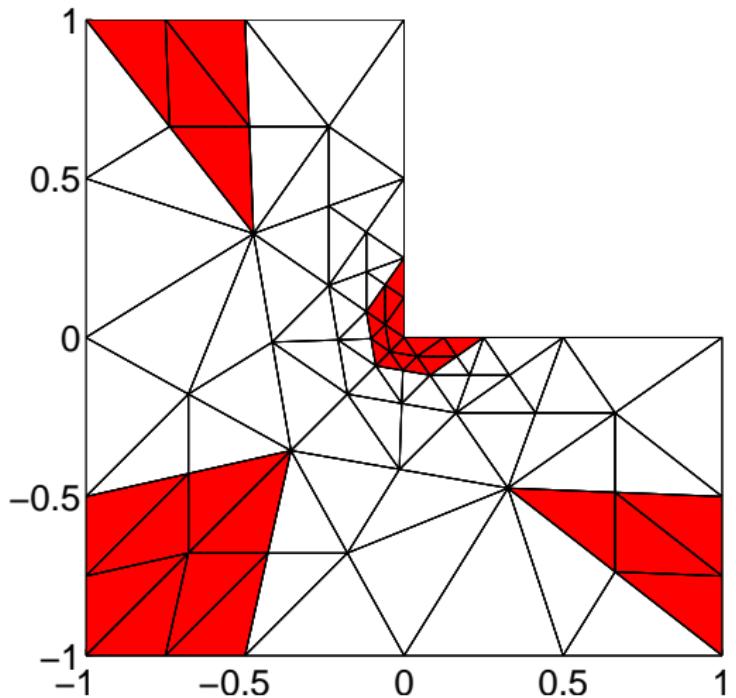
# Adaptive algorithm

Marked elements 3

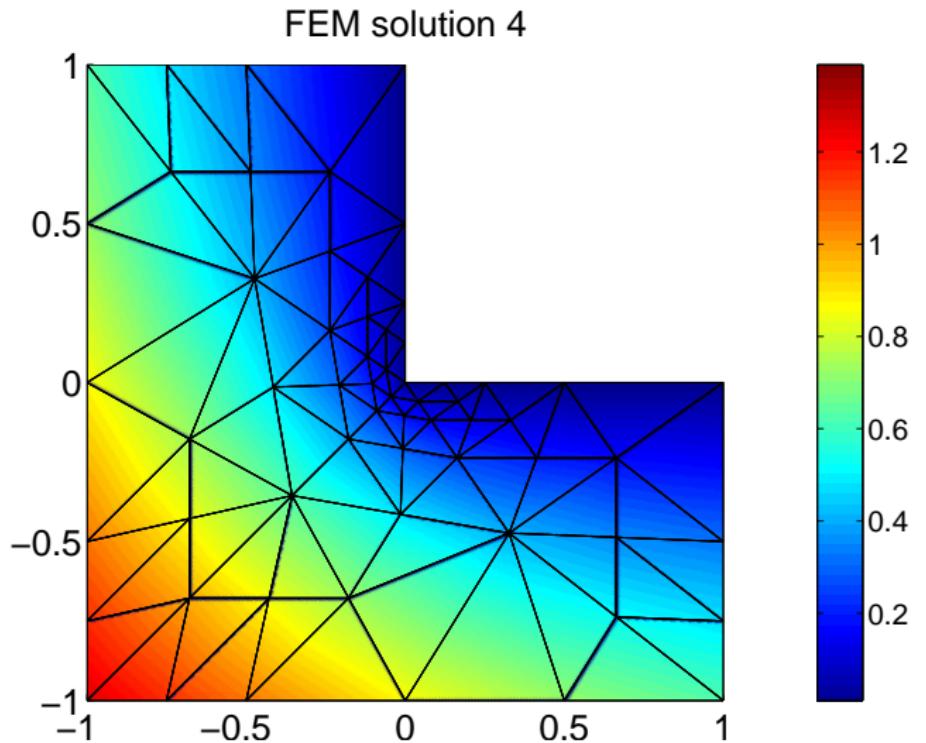


# Adaptive algorithm

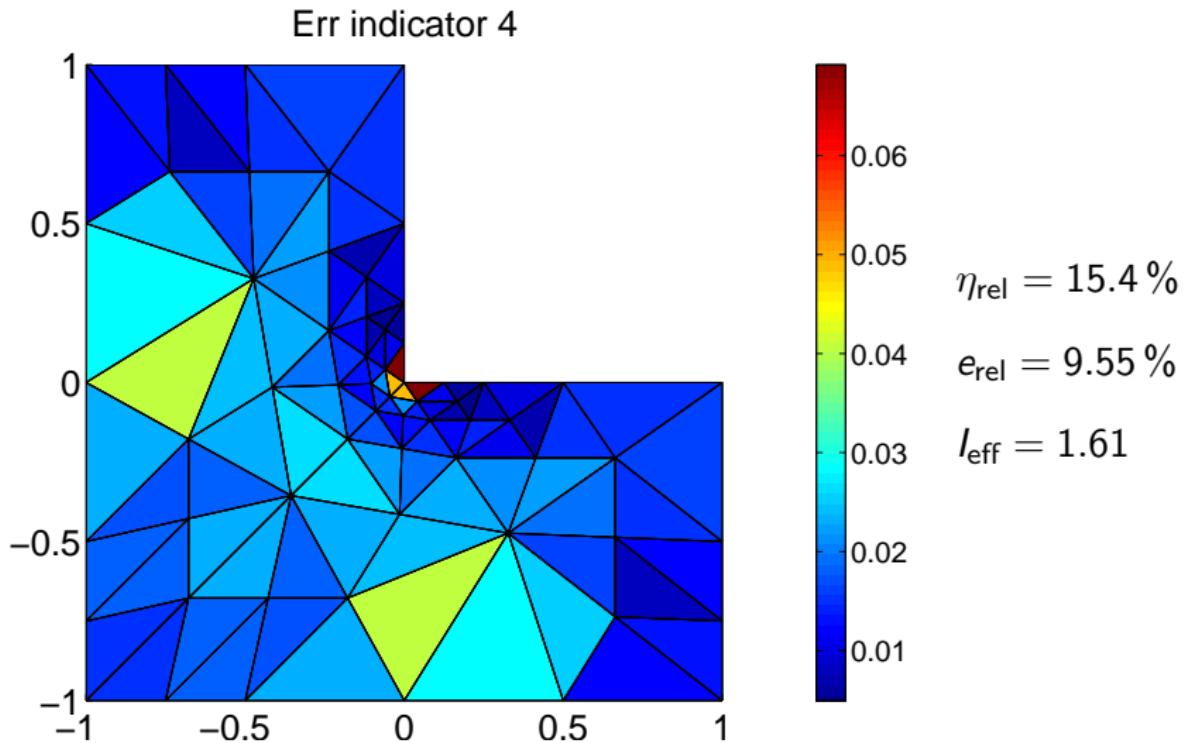
Refined mesh 3



# Adaptive algorithm

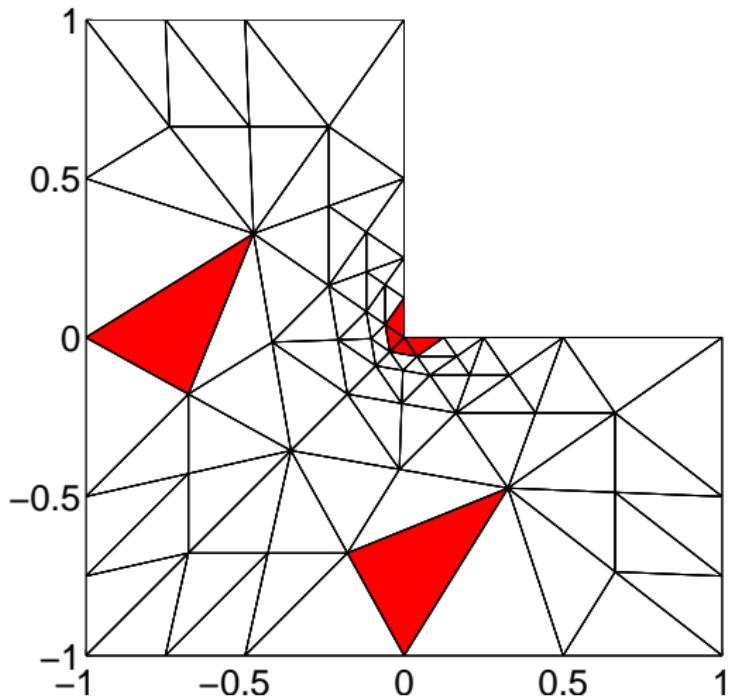


# Adaptive algorithm



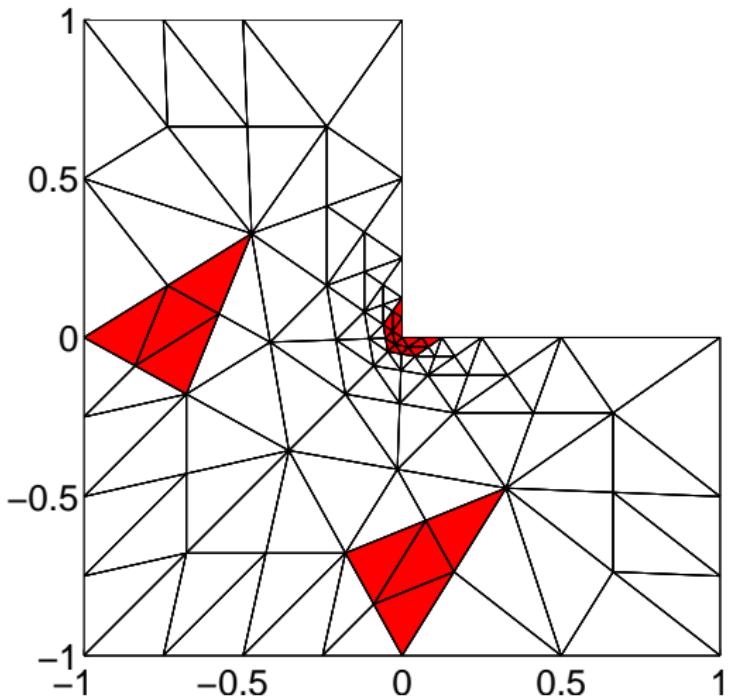
# Adaptive algorithm

Marked elements 4

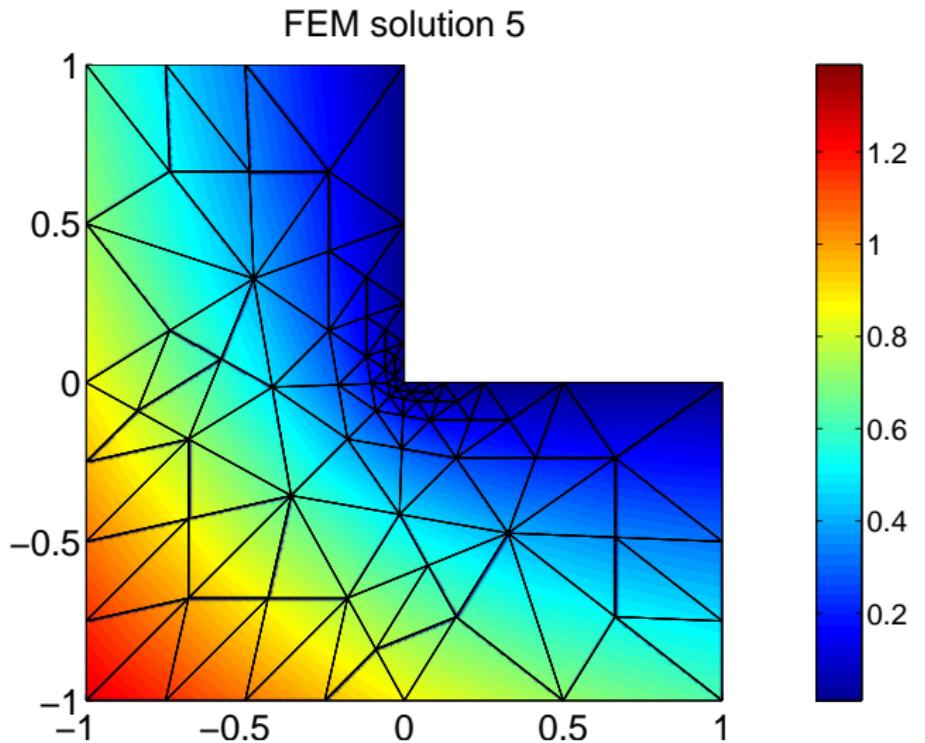


# Adaptive algorithm

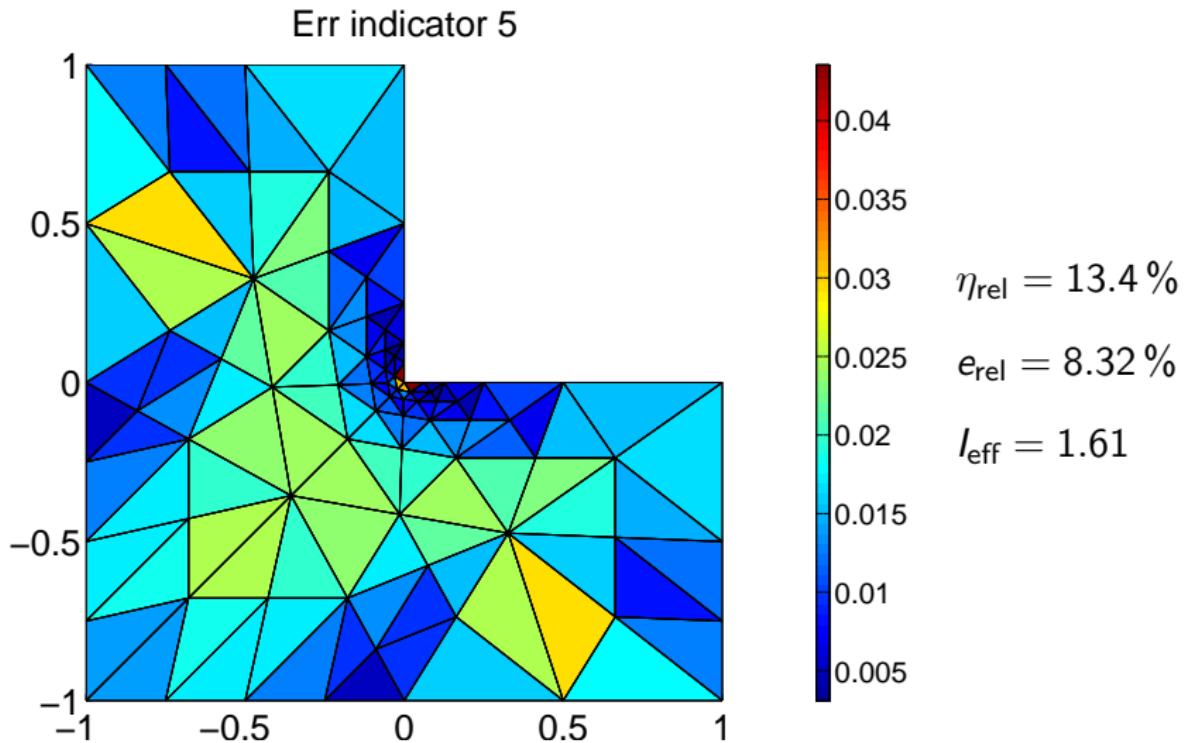
Refined mesh 4



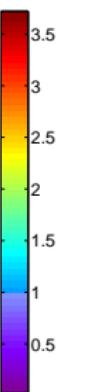
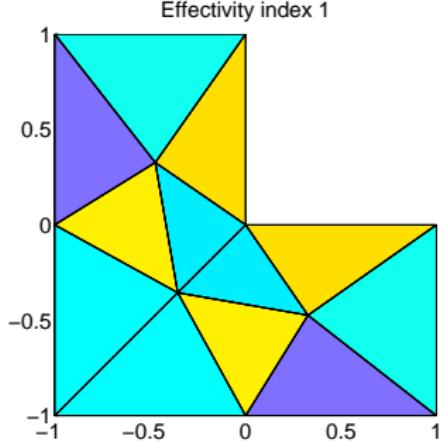
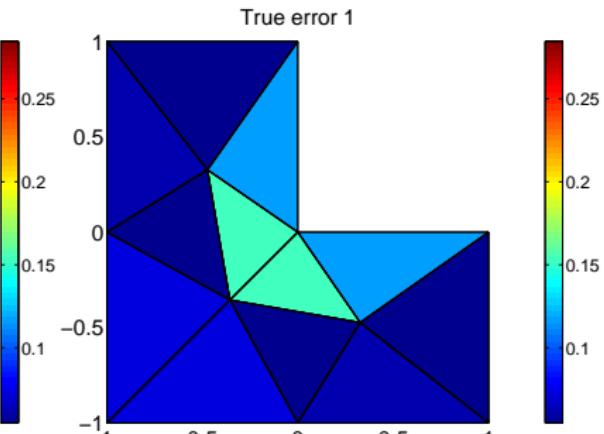
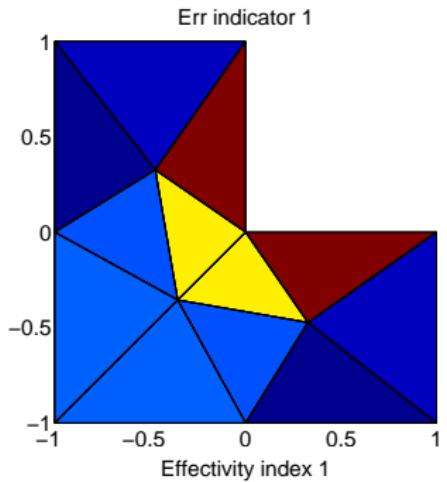
# Adaptive algorithm



# Adaptive algorithm

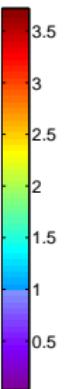
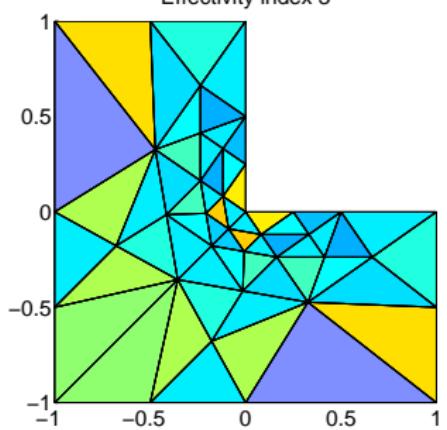
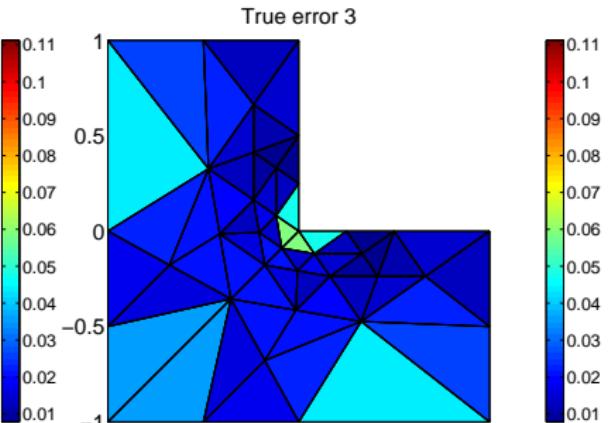
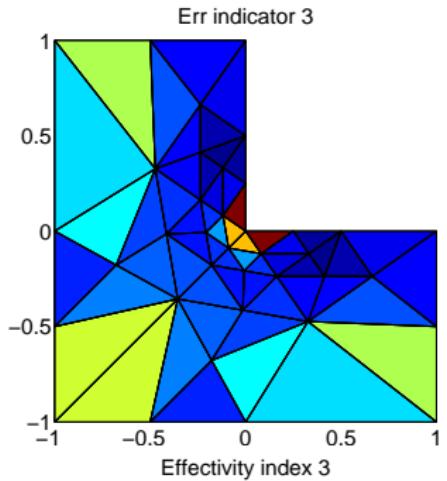


# Effectivity index



$$I_{\text{eff}} = \frac{\eta}{\|e\|} = 1.73$$

# Effectivity index



$$I_{\text{eff}} = \frac{\eta}{\|e\|} = 1.65$$

# Estimator by M. Ainsworth and T. Vejchodský

$$\begin{aligned} -\Delta u + \kappa^2 u &= f && \text{in } \Omega \subset \mathbb{R}^2 \\ u &= 0 && \text{on } \partial\Omega \end{aligned}$$

$$\|e\|^2 \leq \sum_{K \in \mathcal{T}_h} \underbrace{\left( \left\| \frac{1}{\kappa} (r + \operatorname{div} \boldsymbol{\sigma}_K) \right\|_{0,K}^2 + \|\boldsymbol{\sigma}_K\|_{0,K}^2 \right)}_{\eta_K^2}$$

- ▶  $r = f + \Delta u_h - \kappa^2 u_h$
- ▶  $\boldsymbol{\sigma}_K \in \mathbf{H}(\operatorname{div}, K)$
- ▶  $\boldsymbol{\sigma}_K \cdot \boldsymbol{n}_K = g_K - \frac{\partial u_h}{\partial n_K} \quad \text{on } \partial K$
- ▶  $g_K \approx \frac{\partial u}{\partial n_K} \quad \text{on } \partial K$

Thank you for your attention

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