

Computing guaranteed upper bounds of the approximation error

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Outline



- ▶ A posteriori error estimates
- ▶ Primal problem: $-\mathcal{L}\mathbf{u} = f \quad \text{in } \Omega \quad + \quad \text{b.c.}$
- ▶ Complementary problem: $-\mathcal{L}^*\mathbf{y} = f \quad \text{in } \Omega \quad + \quad \text{b.c.}$
- ▶ Error estimate: $\|\mathbf{u} - \mathbf{u}_h\| \leq \eta(\mathbf{u}_h, \mathbf{y}_h) \quad \forall \mathbf{u}_h \in \mathbf{V} \quad \forall \mathbf{y}_h \in \mathbf{W}$
- ▶ Numerical examples
- ▶ Conclusions

A posteriori error estimates

- ▶ GOAL: Solve the problem **with prescribed accuracy**.

A posteriori error estimates



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- ▶ Adaptive algorithm
 1. **Initialize:** Construct the initial mesh \mathcal{T}_h .
 2. **Solve:** Find \mathbf{u}_h on \mathcal{T}_h .
 3. **Estimate error:** Compute η_K for all $K \in \mathcal{T}_h$. $\eta^2 = \sum_{K \in \mathcal{T}_h} \eta_K^2$.
 4. **Stopping criterion:** If $\eta \leq \text{TOL}$ \Rightarrow STOP.
 5. **Mark:** If $\eta_K \geq \Theta \max_{K \in \mathcal{T}_h} \eta_K$ \Rightarrow mark K . $0 < \Theta < 1$
 6. **Refine:** Refine marked elements and build the new mesh \mathcal{T}_h .
 7. GO TO 2.

A posteriori error estimates

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 7. GO TO 2.
- ▶ Guaranteed upper bound: $\|\mathbf{u} - \mathbf{u}_h\| \leq \eta \leq \text{TOL}$
- ▶ Verification

Primal Problem



$$\Omega \subset \mathbb{R}^d$$

$$-\operatorname{div}\left(\mathcal{A}^{11} \nabla u^1\right) \cdots-\operatorname{div}\left(\mathcal{A}^{1 N} \nabla u^N\right)+c^{11} u^1 \cdots+c^{1 N} u^N=f^1$$

$$-\operatorname{div}\left(\mathcal{A}^{21} \nabla u^1\right) \cdots-\operatorname{div}\left(\mathcal{A}^{2 N} \nabla u^N\right)+c^{21} u^1 \cdots+c^{2 N} u^N=f^2$$

⋮

$$-\operatorname{div}\left(\mathcal{A}^{N 1} \nabla u^1\right) \cdots-\operatorname{div}\left(\mathcal{A}^{N N} \nabla u^N\right)+c^{N 1} u^1 \cdots+c^{N N} u^N=f^N$$

$$u^1=u^2=\cdots=u^N=0 \quad \text { on } \partial \Omega$$

Primal Problem



$$\begin{aligned} -\operatorname{\mathbf{div}}(\overline{\mathcal{A}} \nabla u) + C \mathbf{u} &= \mathbf{f} && \text{in } \Omega \\ \mathbf{u} &= \mathbf{0} && \text{on } \partial\Omega \end{aligned}$$

$$\begin{aligned} \mathbf{u} &= \begin{pmatrix} u^1 \\ \vdots \\ u^N \end{pmatrix} & \nabla \mathbf{u} &= \begin{pmatrix} \nabla u^1 \\ \vdots \\ \nabla u^N \end{pmatrix} & \bar{\mathbf{y}} &= \begin{pmatrix} \mathbf{y}^1 \\ \vdots \\ \mathbf{y}^N \end{pmatrix} & \operatorname{\mathbf{div}} \bar{\mathbf{y}} &= \begin{pmatrix} \operatorname{div} \mathbf{y}^1 \\ \vdots \\ \operatorname{div} \mathbf{y}^N \end{pmatrix} \\ \overline{\mathcal{A}} &= \begin{pmatrix} \mathcal{A}^{11} & \cdots & \mathcal{A}^{1N} \\ \vdots & & \vdots \\ \mathcal{A}^{N1} & \cdots & \mathcal{A}^{NN} \end{pmatrix} & C &= \begin{pmatrix} c^{11} & \cdots & c^{1N} \\ \vdots & & \vdots \\ c^{N1} & \cdots & c^{NN} \end{pmatrix} & \mathbf{f} &= \begin{pmatrix} f^1 \\ \vdots \\ f^N \end{pmatrix} \end{aligned}$$

Assumptions: $\overline{\mathcal{A}} = \overline{\mathcal{A}}^{\frac{1}{2}} \overline{\mathcal{A}}^{\frac{1}{2}}$ is uniformly s.p.d. $C = K^T K$ is s.p.d.

Weak formulation

Strong form.:
$$\begin{aligned} -\operatorname{div}(\overline{\mathcal{A}} \nabla u) + C \mathbf{u} &= \mathbf{f} && \text{in } \Omega \\ \mathbf{u} &= \mathbf{0} && \text{on } \partial\Omega \end{aligned}$$

Weak form.: $\mathbf{u} \in \mathbf{V} : \quad \mathcal{B}(\mathbf{u}, \mathbf{v}) = \mathcal{F}(\mathbf{v}) \quad \forall \mathbf{v} \in \mathbf{V}$

Notation:

- ▶ $\mathbf{V} = [H_0^1(\Omega)]^N$
- ▶ $\mathcal{B}(\mathbf{u}, \mathbf{v}) = (\overline{\mathcal{A}} \nabla u, \nabla v) + (C \mathbf{u}, \mathbf{v}) \quad (\bar{\mathbf{p}}, \bar{\mathbf{q}}) = \int_{\Omega} \bar{\mathbf{p}} \cdot \bar{\mathbf{q}} \, dx$
- ▶ $\mathcal{F}(\mathbf{v}) = (\mathbf{f}, \mathbf{v})$
- ▶ $\|\mathbf{v}\|^2 = \mathcal{B}(\mathbf{v}, \mathbf{v})$

Derivation of the estimate

Divergence theorem: $v \in H^1(\Omega)$ $\mathbf{y} \in \mathbf{H}(\text{div}, \Omega)$

$$\int_{\Omega} v \operatorname{div} \mathbf{y} \, dx + \int_{\Omega} \mathbf{y} \cdot \nabla v \, dx - \int_{\partial\Omega} v \mathbf{y} \cdot \mathbf{n} \, dx = 0$$

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$$\begin{aligned}\mathcal{B}(\mathbf{u}, \mathbf{v}) &= \\ &= (\mathbf{f}, \mathbf{v})\end{aligned}$$

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$$\begin{aligned}\mathcal{B}(\mathbf{u} - \mathbf{u}_h, \mathbf{v}) &= \\ &= (\mathbf{f}, \mathbf{v}) - (\overline{\mathcal{A}} \overline{\nabla u_h}, \overline{\nabla v}) - (C \mathbf{u}_h, \mathbf{v})\end{aligned}$$

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Derivation of the estimate

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$$\begin{aligned}\mathcal{B}(\mathbf{u} - \mathbf{u}_h, \mathbf{v}) &= \\ &= (\mathbf{f}, \mathbf{v}) - (\overline{\mathcal{A}} \overline{\nabla u_h}, \overline{\nabla v}) - (C \mathbf{u}_h, \mathbf{v}) + (\operatorname{div} \bar{\mathbf{y}}, \mathbf{v}) + (\bar{\mathbf{y}}, \overline{\nabla v}) \\ &= \left(K^{-T} [\mathbf{f} - C \mathbf{u}_h + \operatorname{div} \bar{\mathbf{y}}], K \mathbf{v} \right) + \left(\overline{\mathcal{A}}^{-\frac{1}{2}} [\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}], \overline{\mathcal{A}}^{\frac{1}{2}} \overline{\nabla v} \right)\end{aligned}$$

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Derivation of the estimate

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$$\begin{aligned}
 \mathcal{B}(\mathbf{u} - \mathbf{u}_h, \mathbf{v}) &= \\
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 &= \left(K^{-T} [\mathbf{f} - C \mathbf{u}_h + \operatorname{div} \bar{\mathbf{y}}], K \mathbf{v} \right) + \left(\overline{\mathcal{A}}^{-\frac{1}{2}} [\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}], \overline{\mathcal{A}}^{\frac{1}{2}} \overline{\nabla v} \right) \\
 &\leq \left\| K^{-T} [\mathbf{f} - C \mathbf{u}_h + \operatorname{div} \bar{\mathbf{y}}] \right\|_0 \| K \mathbf{v} \|_0 + \left\| \overline{\mathcal{A}}^{-\frac{1}{2}} [\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}] \right\|_0 \left\| \overline{\mathcal{A}}^{\frac{1}{2}} \overline{\nabla v} \right\|_0 \\
 &\leq \underbrace{\left(\|\mathbf{f} - C \mathbf{u}_h + \operatorname{div} \bar{\mathbf{y}}\|_{C^{-1}}^2 + \|\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}\|_{\overline{\mathcal{A}}^{-1}}^2 \right)^{\frac{1}{2}}}_{\eta(\mathbf{u}_h, \bar{\mathbf{y}})} \|\mathbf{v}\|
 \end{aligned}$$

Derivation of the estimate

Divergence theorem: $v \in H^1(\Omega)$ $\mathbf{y} \in \mathbf{H}(\text{div}, \Omega)$

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 \mathcal{B}(\mathbf{u} - \mathbf{u}_h, \mathbf{v}) &= \\
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 &\leq \underbrace{\left(\|\mathbf{f} - C \mathbf{u}_h + \mathbf{div} \bar{\mathbf{y}}\|_{C^{-1}}^2 + \|\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}\|_{\overline{\mathcal{A}}^{-1}}^2 \right)^{\frac{1}{2}}}_{\eta(\mathbf{u}_h, \bar{\mathbf{y}})} \|\mathbf{v}\| \\
 \|\mathbf{u} - \mathbf{u}_h\| &\leq \eta(\mathbf{u}_h, \bar{\mathbf{y}}) \quad \forall \mathbf{u}_h \in \mathbf{V} \quad \forall \bar{\mathbf{y}} \in \mathbf{W} = [\mathbf{H}(\text{div}, \Omega)]^N
 \end{aligned}$$

The estimator

Definition: $\eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h) = \|\mathbf{f} - C\mathbf{u}_h + \mathbf{div}\bar{\mathbf{y}}\|_{C^{-1}}^2 + \|\bar{\mathbf{y}} - \overline{\mathcal{A}}\nabla u_h\|_{\overline{\mathcal{A}}^{-1}}^2$

Theorem: $\|\mathbf{u} - \mathbf{u}_h\| \leq \eta(\mathbf{u}_h, \bar{\mathbf{y}}_h) \quad \forall \mathbf{u}_h \in \mathbf{V} \quad \forall \bar{\mathbf{y}}_h \in \mathbf{W}$

Complementary problem:

(A) Find $\bar{\mathbf{y}} \in \mathbf{W}$: $\eta(\mathbf{u}_h, \bar{\mathbf{y}}) = \min_{\bar{\mathbf{w}} \in \mathbf{W}} \eta(\mathbf{u}_h, \bar{\mathbf{w}})$

(B) Find $\bar{\mathbf{y}} \in \mathbf{W}$: $\mathcal{B}^*(\bar{\mathbf{y}}, \bar{\mathbf{w}}) = \mathcal{F}^*(\bar{\mathbf{w}}) \quad \forall \bar{\mathbf{w}} \in \mathbf{W}$

- ▶ $\mathbf{W} = [\mathbf{H}(\text{div}, \Omega)]^N$

- ▶ $\mathcal{B}^*(\bar{\mathbf{y}}, \bar{\mathbf{w}}) = (C^{-1} \mathbf{div} \bar{\mathbf{y}}, \mathbf{div} \bar{\mathbf{w}}) + (\overline{\mathcal{A}}^{-1} \bar{\mathbf{y}}, \bar{\mathbf{w}})$

- ▶ $\mathcal{F}^*(\bar{\mathbf{w}}) = - (C^{-1} \mathbf{f}, \mathbf{div} \bar{\mathbf{w}})$

- ▶ $\|\bar{\mathbf{w}}\|_*^2 = \mathcal{B}^*(\bar{\mathbf{w}}, \bar{\mathbf{w}})$

The estimator

Definition: $\eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h) = \|\mathbf{f} - C\mathbf{u}_h + \operatorname{div} \bar{\mathbf{y}}\|_{C^{-1}}^2 + \|\bar{\mathbf{y}} - \overline{\mathcal{A}} \overline{\nabla u_h}\|_{\overline{\mathcal{A}}^{-1}}^2$

Theorem: $\|\mathbf{u} - \mathbf{u}_h\| \leq \eta(\mathbf{u}_h, \bar{\mathbf{y}}_h) \quad \forall \mathbf{u}_h \in \mathbf{V} \quad \forall \bar{\mathbf{y}}_h \in \mathbf{W}$

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(B) Find $\bar{\mathbf{y}} \in \mathbf{W}$: $\mathcal{B}^*(\bar{\mathbf{y}}, \bar{\mathbf{w}}) = \mathcal{F}^*(\bar{\mathbf{w}}) \quad \forall \bar{\mathbf{w}} \in \mathbf{W}$

Lemma 1: (A) \Leftrightarrow (B)

Lemma 2: $\bar{\mathbf{y}} = \overline{\mathcal{A}} \overline{\nabla \mathbf{u}}$ is the unique solution of (A)–(B)

Lemma 3: $\eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h) + \eta^2(\mathbf{u}, \bar{\mathbf{y}}_h) = \eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h) \quad \forall \mathbf{u}_h \in \mathbf{V}, \bar{\mathbf{y}}_h \in \mathbf{W}$
 $\|\mathbf{u} - \mathbf{u}_h\|^2 + \|\bar{\mathbf{y}}_h - \bar{\mathbf{y}}\|_*^2 = \eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h)$

Method of hypercircle

Theorem: If

- ▶ $\mathbf{u} \in \mathbf{V}$ is primal solution
- ▶ $\mathbf{u}_h \in \mathbf{V}$, $\bar{\mathbf{y}}_h \in \mathbf{W}$ arbitrary
- ▶ $\tilde{\mathbf{u}}_h = [C^{-1}(\mathbf{f} + \operatorname{div} \bar{\mathbf{y}}_h) + \mathbf{u}_h]/2$
- ▶ $\mathcal{G}\tilde{\mathbf{u}}_h = (\bar{\mathbf{y}}_h + \overline{\mathcal{A}\nabla u_h})/2$

Then

$$\left\| \overline{\nabla u} - \overline{\mathcal{A}}^{-1} \mathcal{G}\tilde{\mathbf{u}}_h \right\|_{\overline{\mathcal{A}}}^2 + \|\mathbf{u} - \tilde{\mathbf{u}}_h\|_C^2 = \frac{1}{4} \eta^2 (\mathbf{u}_h, \bar{\mathbf{y}}_h).$$

Other variants (good for C singular)

$$(1) \quad \eta^2(\mathbf{u}_h, \bar{\mathbf{y}}_h) = \|\mathbf{f} - C\mathbf{u}_h + \mathbf{div} \bar{\mathbf{y}}_h\|_{C^{-1}}^2 + \|\bar{\mathbf{y}}_h - \overline{\mathcal{A} \nabla u_h}\|_{\overline{\mathcal{A}}^{-1}}^2$$

$$(2) \quad \tilde{\eta}(\mathbf{u}_h, \tilde{\mathbf{y}}_h) = \|\tilde{\mathbf{y}}_h - \overline{\mathcal{A} \nabla u_h}\|_{\overline{\mathcal{A}}^{-1}} \quad \tilde{\mathbf{y}}_h \in \mathbf{Q}(\mathbf{f}, \mathbf{u}_h)$$

$$\mathbf{Q}(\mathbf{f}, \mathbf{u}_h) = \{\tilde{\mathbf{y}} \in \mathbf{W} : \mathbf{f} - C\mathbf{u}_h + \mathbf{div} \tilde{\mathbf{y}} = 0\}$$

$$(3) \quad \widehat{\eta}(\mathbf{u}_h, \widehat{\mathbf{y}}_h) = \frac{\gamma_F}{\lambda} \|\mathbf{f} - C\mathbf{u}_h + \mathbf{div} \widehat{\mathbf{y}}_h\|_0 + \|\widehat{\mathbf{y}}_h - \overline{\mathcal{A} \nabla u_h}\|_{\overline{\mathcal{A}}^{-1}}$$

Friedrichs ineq.: $\|\mathbf{v}\|_0 \leq \gamma_F \|\nabla \mathbf{v}\|_0 \quad \forall \mathbf{v} \in H_0^1(\Omega)$

Ellipticity: $(\overline{\mathcal{A} \mathbf{w}}, \overline{\mathbf{w}}) \geq \lambda^2 \|\overline{\mathbf{w}}\|_0^2 \quad \forall \overline{\mathbf{w}} \in \mathbf{W}$

Lemma: $\|\mathbf{u} - \mathbf{u}_h\| \leq \min \{\eta(\mathbf{u}_h, \bar{\mathbf{y}}_h), \tilde{\eta}(\mathbf{u}_h, \tilde{\mathbf{y}}_h), \widehat{\eta}(\mathbf{u}_h, \widehat{\mathbf{y}}_h)\}$

$\forall \mathbf{u}_h \in \mathbf{V} \quad \forall \bar{\mathbf{y}}_h \in \mathbf{W} \quad \forall \tilde{\mathbf{y}}_h \in \mathbf{Q}(\mathbf{f}, \mathbf{u}_h) \quad \forall \widehat{\mathbf{y}}_h \in \mathbf{W}$

Numerical example

Primal problem

$$-(\bar{\mathcal{A}}\mathbf{u}')' + C\mathbf{u} = \mathbf{f}$$

$$\mathbf{u}(0) = \mathbf{u}(1) = \mathbf{0}$$

$$\bar{\mathcal{A}} = \begin{pmatrix} 4 & 2 & -2 \\ 2 & 2 & 0 \\ -2 & 0 & 6 \end{pmatrix} \quad C = \kappa^2 \begin{pmatrix} 4 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 4 \end{pmatrix} \quad \mathbf{f} = \begin{pmatrix} 4 \\ 4 \\ 4 \end{pmatrix}$$

$$\mathbf{u} = \begin{pmatrix} u^1 \\ u^2 \\ u^3 \end{pmatrix} = \frac{1}{\kappa^2} \left(1 - \frac{\sinh \kappa(1-x) + \sinh \kappa x}{\sinh \kappa} \right) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

Numerical example

Primal problem

$$-(\bar{\mathcal{A}}\mathbf{u}')' + C\mathbf{u} = \mathbf{f}$$

$$\mathbf{u}(0) = \mathbf{u}(1) = \mathbf{0}$$

Complementary problem

$$-(C^{-1}\mathbf{y}')' + \bar{\mathcal{A}}^{-1}\mathbf{y} = (C^{-1}\mathbf{f})' \quad \text{in } (0, 1)$$

$$\mathbf{y}'(0) = -\mathbf{f}(0) \quad \mathbf{y}'(1) = -\mathbf{f}(1)$$

$$\bar{\mathcal{A}} = \begin{pmatrix} 4 & 2 & -2 \\ 2 & 2 & 0 \\ -2 & 0 & 6 \end{pmatrix} \quad C = \kappa^2 \begin{pmatrix} 4 & 1 & -1 \\ 1 & 2 & 1 \\ -1 & 1 & 4 \end{pmatrix} \quad \mathbf{f} = \begin{pmatrix} 4 \\ 4 \\ 4 \end{pmatrix}$$

$$\mathbf{u} = \begin{pmatrix} u^1 \\ u^2 \\ u^3 \end{pmatrix} = \frac{1}{\kappa^2} \left(1 - \frac{\sinh \kappa(1-x) + \sinh \kappa x}{\sinh \kappa} \right) \begin{pmatrix} 1 \\ 1 \\ 1 \end{pmatrix}$$

$$\mathbf{y} = \bar{\mathcal{A}}\mathbf{u}'$$

Numerical example

Primal problem

$$-\overline{(\mathcal{A}\mathbf{u}')}' + C\mathbf{u} = \mathbf{f}$$

$$\mathbf{u}(0) = \mathbf{u}(1) = \mathbf{0}$$

Complementary problem

$$-(C^{-1}\mathbf{y}')' + \overline{\mathcal{A}}^{-1}\mathbf{y} = (C^{-1}\mathbf{f})' \quad \text{in } (0, 1)$$

$$\mathbf{y}'(0) = -\mathbf{f}(0) \quad \mathbf{y}'(1) = -\mathbf{f}(1)$$

FEM mesh

$$0 = x_0 < x_1 < \dots < x_M = 1 \quad K_i = [x_{i-1}, x_i], \quad i = 1, 2, \dots, M$$

Primal FEM

$$\mathbf{V}_h = \{v_h \in H_0^1(0, 1) : v_h|_{K_i} \in P^1(K_i) \ \forall K_i\}^3$$

$$\mathbf{u}_h \in \mathbf{V}_h : \quad (\overline{\mathcal{A}}\mathbf{u}'_h, \mathbf{v}'_h) + (C\mathbf{u}_h, \mathbf{v}_h) = (\mathbf{f}, \mathbf{v}_h) \quad \forall \mathbf{v}_h \in \mathbf{V}_h$$

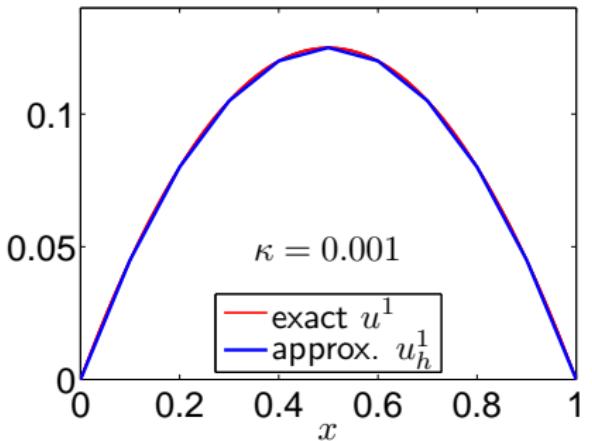
Complementary FEM

$$\mathbf{W}_h = \{w_h \in H^1(0, 1) : w_h|_{K_i} \in P^1(K_i) \ \forall K_i\}^3$$

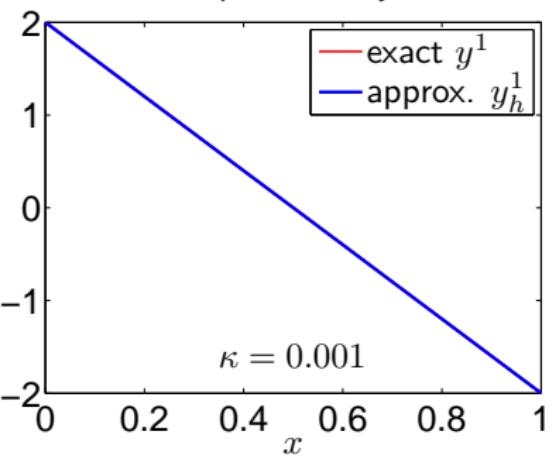
$$\mathbf{y}_h \in \mathbf{W}_h : \quad (C^{-1}\mathbf{y}'_h, \mathbf{w}'_h) + (\overline{\mathcal{A}}^{-1}\mathbf{y}_h, \mathbf{w}_h) = -(C^{-1}\mathbf{f}, \mathbf{w}'_h) \quad \forall \mathbf{w}_h \in \mathbf{W}_h$$

Primal and complementary solutions

Primal solution



Complementary sol.



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 9.486 \%$$

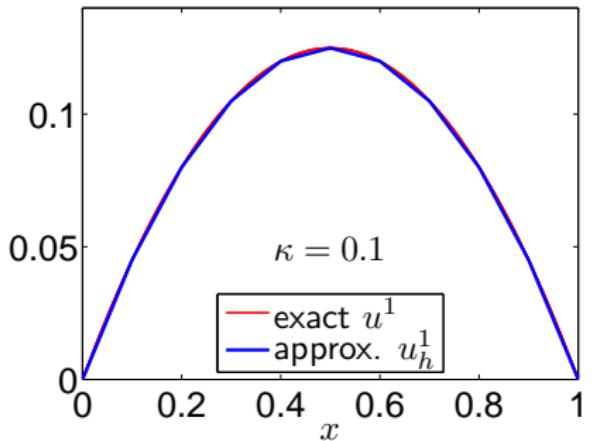
$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 9.440 \%$$

$$\frac{\eta}{\|\mathbf{u}\|} = 9.440 \%$$

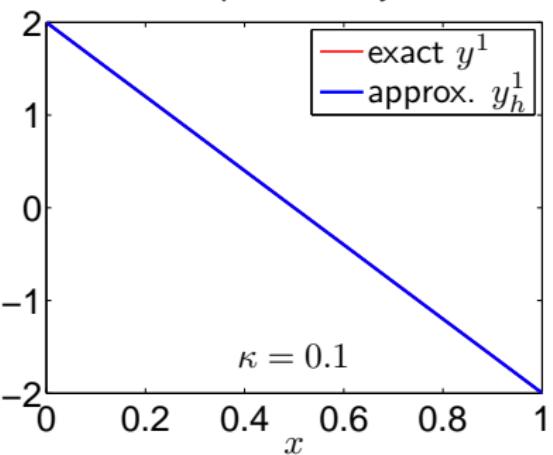
$$I_{eff} = 1.000$$

Primal and complementary solutions

Primal solution



Complementary sol.



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 9.486 \%$$

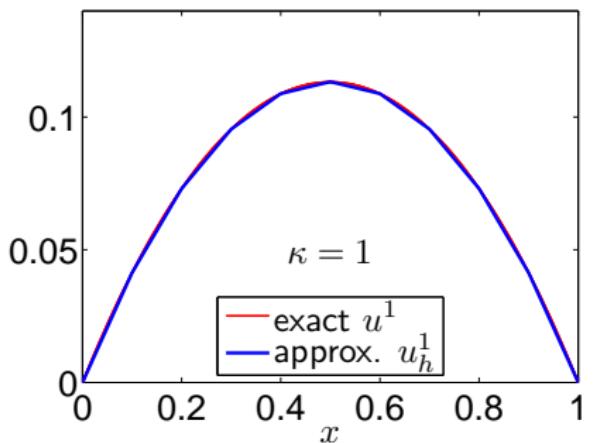
$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 9.436 \%$$

$$\frac{\eta}{\|\mathbf{u}\|} = 9.439 \%$$

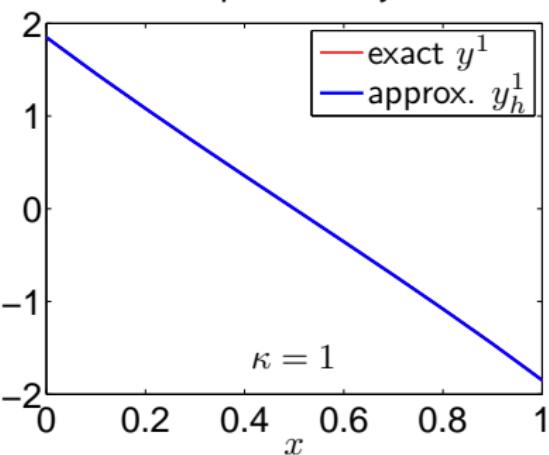
$$I_{\text{eff}} = 1.0003$$

Primal and complementary solutions

Primal solution



Complementary sol.



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 9.530 \%$$

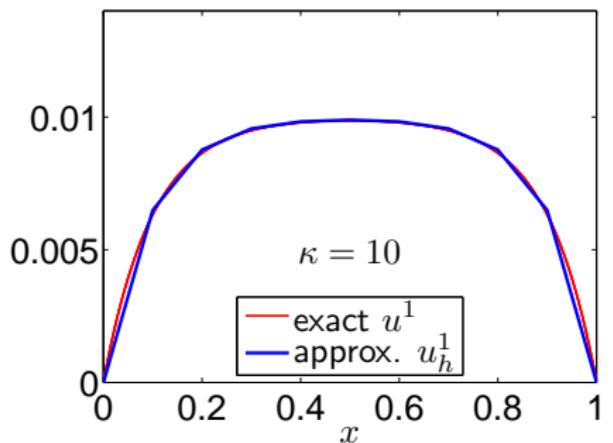
$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 9.158 \%$$

$$\frac{\eta}{\|\mathbf{u}\|} = 9.487 \%$$

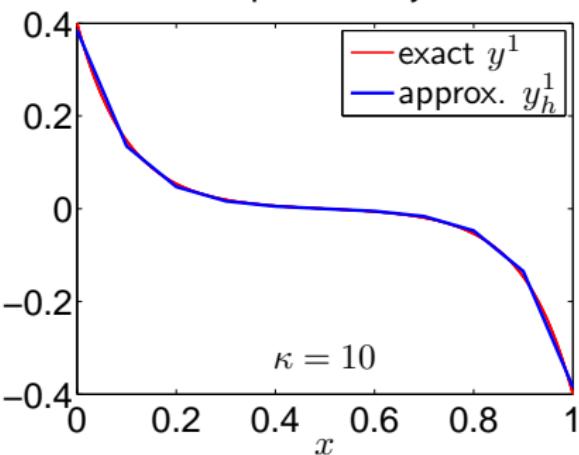
$$I_{\text{eff}} = 1.036$$

Primal and complementary solutions

Primal solution



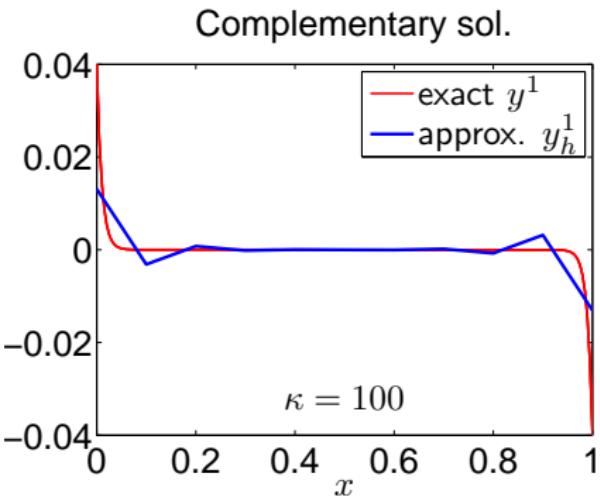
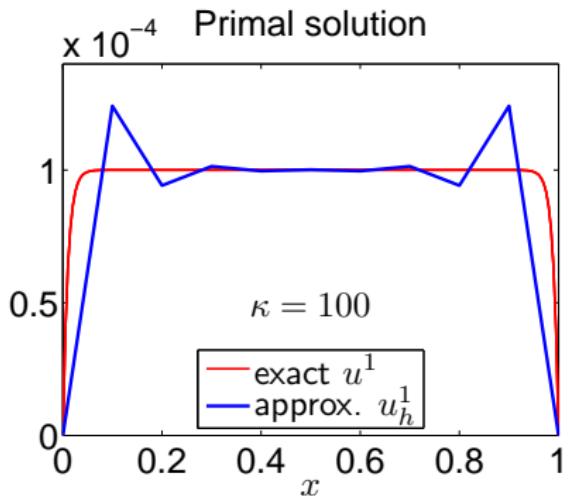
Complementary sol.



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 13.45\%$$

$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 9.617\% \quad \frac{\eta}{\|\mathbf{u}\|} = 13.39\% \quad I_{\text{eff}} = 1.392$$

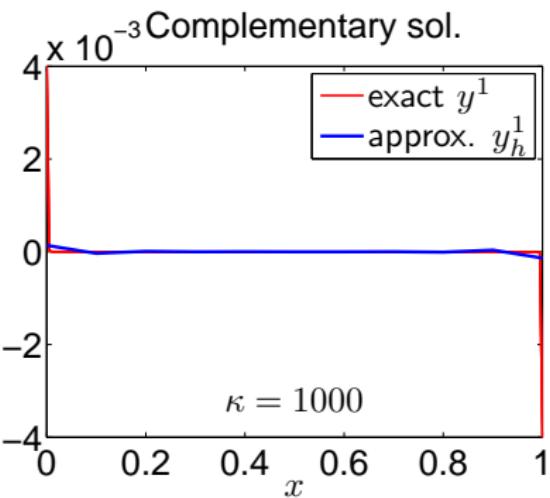
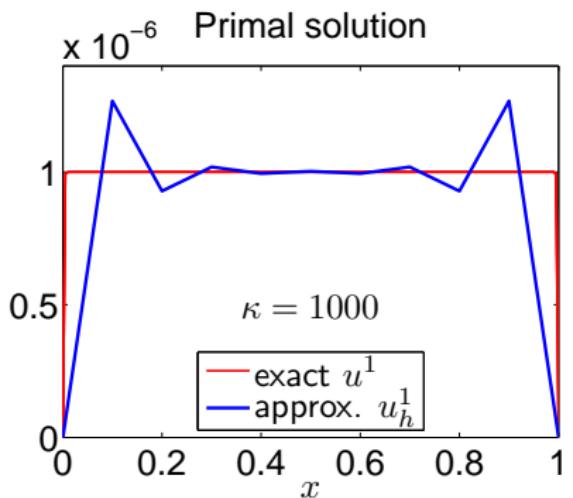
Primal and complementary solutions



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 22.26\%$$

$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 15.48\% \quad \frac{\eta}{\|\mathbf{u}\|} = 21.99\% \quad I_{\text{eff}} = 1.420$$

Primal and complementary solutions



$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}_h\|} \leq \frac{\eta}{\|\mathbf{u}_h\|} = 22.23\%$$

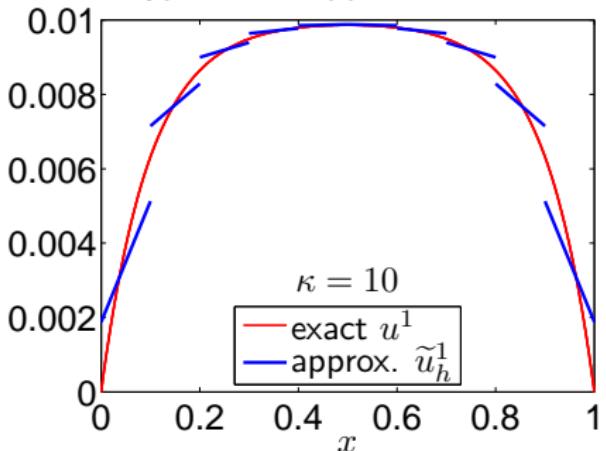
$$\frac{\|\mathbf{u} - \mathbf{u}_h\|}{\|\mathbf{u}\|} = 19.86\%$$

$$\frac{\eta}{\|\mathbf{u}\|} = 21.90\%$$

$$I_{eff} = 1.103$$

Method of hypercircle

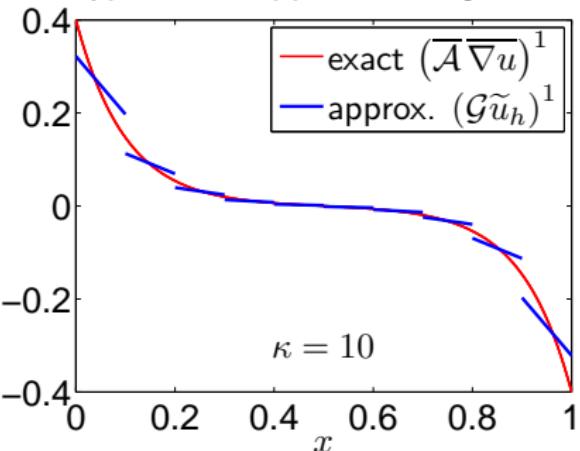
Hypercircle approx. of values



$\kappa = 10$

exact u^1
approx. \tilde{u}_h^1

Hypercircle approx. of cogradient



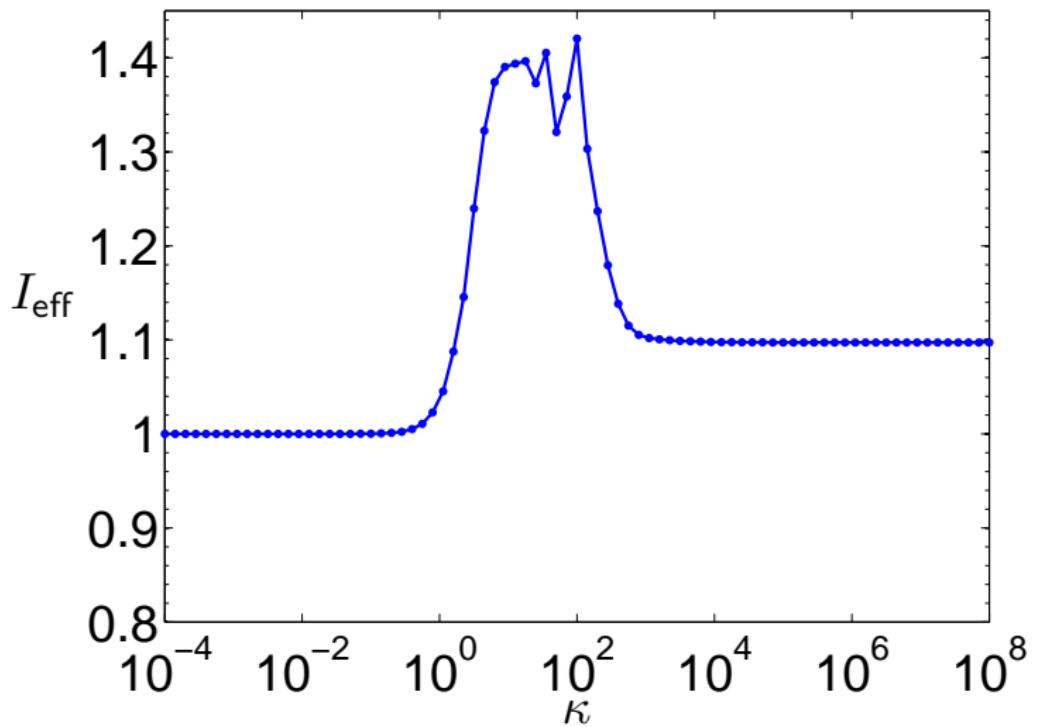
$\kappa = 10$

exact $(\bar{\mathcal{A}} \nabla u)^1$
approx. $(\tilde{\mathcal{G}} \tilde{u}_h)^1$

$$\frac{\|[\mathbf{u} - \tilde{\mathbf{u}}_h, \bar{\nabla} u - \mathcal{G}\tilde{\mathbf{u}}_h]\|_{hc}}{\|\mathbf{u}_h\|} = \frac{1}{2} \frac{\eta}{\|\mathbf{u}_h\|} = 6.72 \%$$

Effectivity index

Effectivity vs. κ



Conclusions



$$\|\mathbf{u} - \mathbf{u}_h\| \leq \eta(\mathbf{u}_h, \bar{\mathbf{y}}_h)$$

- ▶ Computable guaranteed upper bounds
- ▶ Optimal $\bar{\mathbf{y}}$ solves a complementary problem
- ▶ Postprocessing of $\bar{\mathcal{A}} \bar{\nabla} u_h$
⇒ fast algorithms for $\bar{\mathbf{y}}_h$ (many open problems)
- ▶ $\mathbf{u}_h \in \mathbf{V}$ arbitrary
⇒ including algebraic errors, human errors
- ▶ Exist generalizations to other classes of problems

Thank you for your attention

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