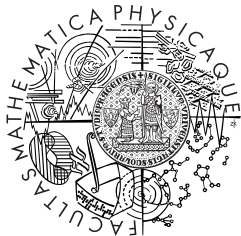


# Discrete maximum principles

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## Setting:

- ▶ linear elliptic second-order PDE
- ▶ finite element method (FEM)
  - ▶ linear (lowest-order)
  - ▶ higher-order
- ▶ discrete maximum principles (DMP)

## Goals:

- ▶ General theory of DMP
- ▶ Unified survey of known results
- ▶ New results (higher-order FEM)



- [A1] A. Hannukainen, S. Korotov, and T. Vejchodský: *J. Comput. Appl. Math.* **226** (2009), 275–287. **IF 0.943**
- [A2] S. Korotov and T. Vejchodský: In: *Numerical mathematics and advanced applications ENUMATH 2009*, Springer, Berlin, 2010, pp. 533–541.
- [A3] T. Vejchodský and P. Šolín: *Math. Comp.* **76** (2007), 1833–1846. **IF 1.230**
- [A4] T. Vejchodský and P. Šolín: *Adv. Appl. Math. Mech.* **1** (2009), 201–214.
- [A5] T. Vejchodský and P. Šolín: *J. Numer. Math.* **15** (2007), 233–243. **IF 0.586**
- [A6] T. Vejchodský: *Appl. Numer. Math.* **60** (2010), 486–500. **IF 1.279**
- [A7] T. Vejchodský: In: *Numerical mathematics and advanced applications ENUMATH 2009*, Springer, Berlin, 2010, pp. 901–909.
- [A8] P. Šolín and T. Vejchodský: *J. Comput. Appl. Math.* **209** (2007), 54–65. **IF 0.943**



# Introduction

Example 1:  $-u'' = f$  in  $(0, 2)$ ,  $u(0) = u(2) = 0$

Conservation of nonnegativity:  $f \geq 0 \Rightarrow u \geq 0$



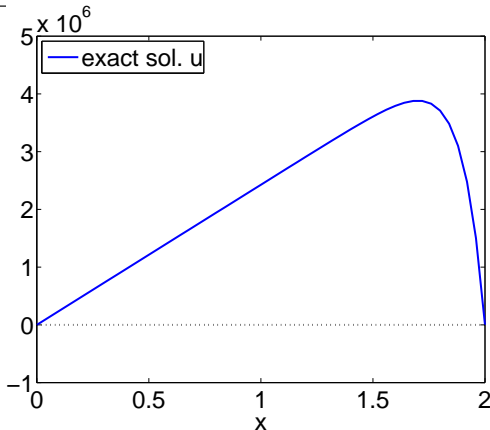
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►  $u = \frac{2 + (e^{20} - 1)x - 2e^{10x}}{200}$

►  $f = e^{10x}$





# Introduction

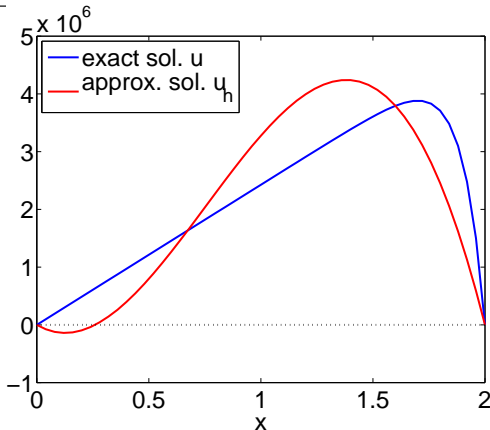
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►  $f = e^{10x}$

►  $u_h \in \mathbb{P}_0^3(0, 2)$





# Introduction

Example 2:  $-\Delta u = f$  in  $\Omega = (0, 4) \times (0, 2)$ ,  $u = 0$  on  $\partial\Omega$

Conservation of nonnegativity:  $f \geq 0 \Rightarrow u \geq 0$

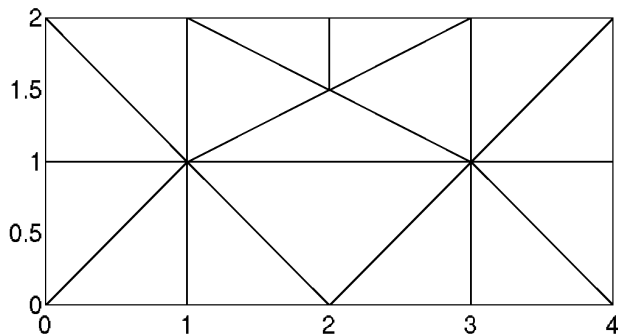
# Introduction



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$$f(x_1, x_2) = \begin{cases} 1 & \text{for } x_1 < 1 \\ 0 & \text{for } x_1 \geq 1 \end{cases} \quad u_h \text{ by linear FEM}$$



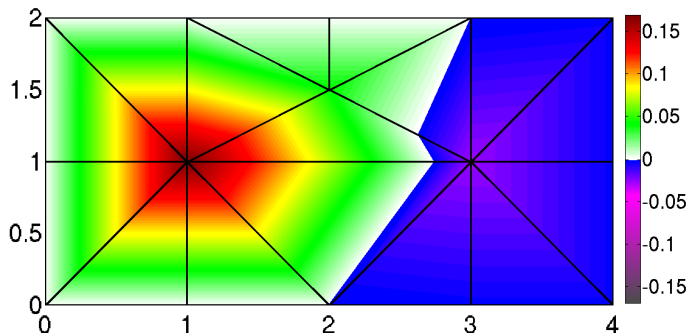


# Introduction

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Negative values 10 $\times$  magnified.

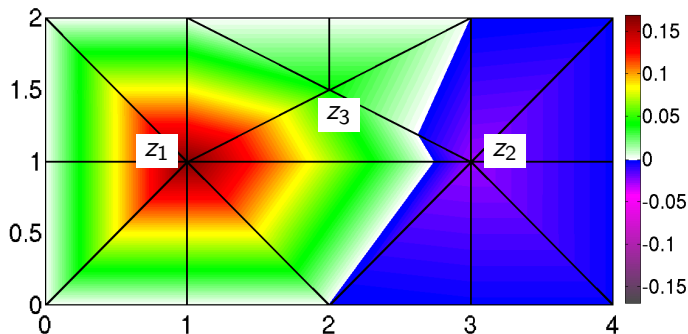
Brandts, Korotov, Křížek, Šolc, SIAM Review 51 (2009), 317–335

# Introduction



Example 2:

$$Az = b \Leftrightarrow \overbrace{\begin{pmatrix} + & - & + \\ - & + & + \\ + & + & + \end{pmatrix}}^{A^{-1}} \overbrace{\begin{pmatrix} + \\ 0 \\ 0 \end{pmatrix}}^b = \overbrace{\begin{pmatrix} + \\ - \\ + \end{pmatrix}}^z$$



Negative values 10× magnified.

Brandts, Korotov, Křížek, Šolc, SIAM Review 51 (2009), 317–335

# Model problem



$$\begin{aligned} -\operatorname{div}(\mathcal{A}\nabla u) + \mathbf{b} \cdot \nabla u + cu &= f && \text{in } \Omega \\ u &= g_D && \text{on } \Gamma_D \\ \alpha u + (\mathcal{A}\nabla u) \cdot \mathbf{n} &= g_N && \text{on } \Gamma_N \end{aligned}$$

Maximum Principle:

$$f \leq 0 \text{ and } g_N \leq 0 \quad \Rightarrow \quad \max_{\Omega} u \leq \max_{\Gamma_D} \max\{0, u\}$$

Minimum Principle:

$$f \geq 0 \text{ and } g_N \geq 0 \quad \Rightarrow \quad \min_{\Omega} u \geq \min_{\Gamma_D} \min\{0, u\}$$

Conservation of Nonnegativity:

$$f \geq 0, \quad g_D \geq 0, \text{ and } g_N \geq 0 \quad \Rightarrow \quad u \geq 0$$

Comparison Principle:

$$f \geq \tilde{f}, \quad g_D \geq \tilde{g}_D, \text{ and } g_N \geq \tilde{g}_N \quad \Rightarrow \quad u \geq \tilde{u}$$



Weak form.:  $u - \bar{g}_D \in V : a(u, v) = \mathcal{F}(v) \quad \forall v \in V$

FEM form.:  $u_h - \bar{g}_{D,h} \in V_h : a(u_h, v_h) = \mathcal{F}(v_h) \quad \forall v_h \in V_h$   
 $V_h \subset V, \dim V_h < \infty$

Discrete Maximum Principle (DMP):

$$f \leq 0 \text{ and } g_N \leq 0 \quad \Rightarrow \quad \max_{\Omega} u_h \leq \max_{\Gamma_D} \max\{0, u_h\}$$

Discrete Minimum Principle:

$$f \geq 0 \text{ and } g_N \geq 0 \quad \Rightarrow \quad \min_{\Omega} u_h \geq \min_{\Gamma_D} \min\{0, u_h\}$$

Discrete Conservation of Nonnegativity:

$$f \geq 0, g_{D,h} \geq 0, \text{ and } g_N \geq 0 \quad \Rightarrow \quad u_h \geq 0$$

Discrete Comparison Principle:

$$f \geq \tilde{f}, g_{D,h} \geq \tilde{g}_{D,h}, \text{ and } g_N \geq \tilde{g}_N \quad \Rightarrow \quad u_h \geq \tilde{u}_h$$



**Definition:**  $\mathbf{y} \in \Omega$ ,  $G_{h,\mathbf{y}} \in V_h$  :  $a(v_h, G_{h,\mathbf{y}}) = v_h(\mathbf{y}) \quad \forall v_h \in V_h$

**Notation:**  $G_h(\mathbf{x}, \mathbf{y}) = G_{h,\mathbf{y}}(\mathbf{x}) \quad \forall (\mathbf{x}, \mathbf{y}) \in \Omega^2$

**Theorem:** DMP  $\Leftrightarrow$

(i)  $G_h(\mathbf{x}, \mathbf{y}) \geq 0 \quad \forall (\mathbf{x}, \mathbf{y}) \in \Omega^2$

(ii)  $g_{D,h}(\mathbf{y}) - (\Pi_h^0 g_{D,h})(\mathbf{y}) \geq 0 \quad \forall g_{D,h} \in V_h^\partial, g_{D,h} \geq 0 \text{ in } \Omega, \mathbf{y} \in \Omega$

**Theorem:** For linear FEM:

(i)  $\Leftrightarrow A^{-1} \geq 0$

(ii)  $\Leftrightarrow -A^{-1}A^\partial \geq 0$



# Results for linear FEM

*Systematic overview of known results.*

$$-(\mathcal{A}u')' + bu' + cu = f \quad \text{in } \Omega = (a, b)$$

$$u(a) = g_D$$

$$\alpha u(b) + \mathcal{A}u'(b) = g_N$$

Original contributions:

- ▶ Complete characterization in 1D
- ▶ New general sufficient conditions for
  - ▶ simplicial FEM, arbitrary dimension
  - ▶ block FEM, arbitrary dimension [A2]
- ▶ Right triangular prismatic FEM [A1]

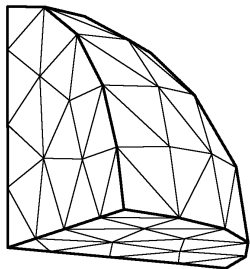
# Results for linear FEM

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$$\begin{aligned}
 -\operatorname{div}(\lambda \nabla u) + cu &= f && \text{in } \Omega \subset \mathbb{R}^d \\
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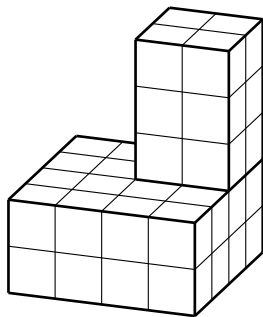
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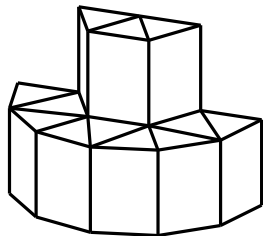
# Results for linear FEM

*Systematic overview of known results.*

$$\begin{aligned}
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 u &= 0 && \text{on } \partial\Omega
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Original contributions:

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- ▶ New general sufficient conditions for
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  - ▶ block FEM, arbitrary dimension [A2]
- ▶ **Right triangular prismatic FEM [A1]**



# Results for higher-order FEM



*Mostly original results.*

$$\begin{aligned} -(\mathcal{A}u')' &= f \quad \text{in } \Omega = (a, b) \\ u(a) &= g_D \\ \mathcal{A}u'(b) &= g_N \end{aligned}$$

- ▶ 1D diffusion equation [A3]–[A5]
- ▶ 1D diffusion-reaction equation [A6]
- ▶ 2D numerical tests – negative conclusions [A7]
- ▶ 1D weaker concept [A8]

# Results for higher-order FEM



*Mostly original results.*

$$\begin{aligned} -u'' + cu &= f \quad \text{in } \Omega = (a, b) \\ u(a) &= g_D \\ u'(b) &= g_N \end{aligned}$$

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# Results for higher-order FEM



*Mostly original results.*

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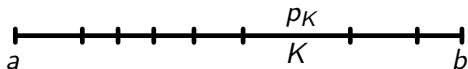


# 1D diffusion equation

Problem:  $-u'' = f$  in  $(a, b)$ ,  $u(a) = u(b) = 0$

FEM:  $u_{hp} \in V_{hp} = \{v_{hp} \in C_0[a, b] : v_{hp} \in \mathbb{P}^{p_K}(K), K \in \mathcal{T}_h\}$

Theorem:  $h_K \leq H_{\text{rel}}^*(p_K)(b-a) \forall K \in \mathcal{T}_h \Rightarrow u_{hp}$  satisfies DMP



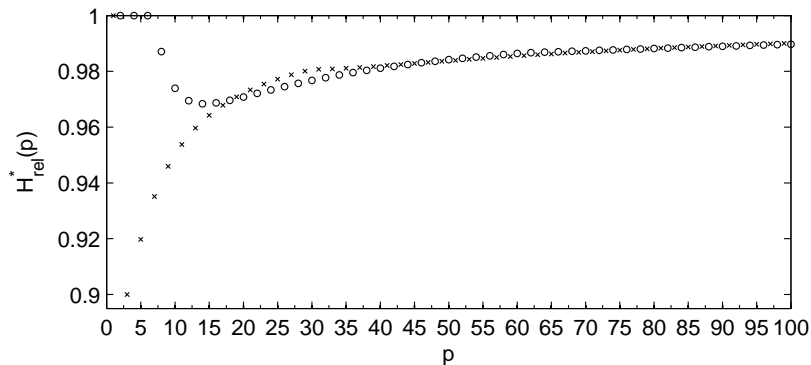


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# Conclusions



## Setting:

- ▶ linear elliptic second-order PDE
- ▶ finite element method (FEM)
  - ▶ linear
  - ▶ higher-order
- ▶ discrete maximum principles (DMP)

## Output:

- ▶ general theory
- ▶ unified presentation
- ▶ general overview of DMP results
- ▶ original contributions (higher-order FEM)
- ▶ 8 original papers

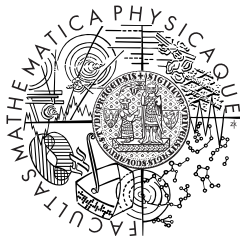


# Thank you for your attention

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## Parabolic problems

$$\begin{aligned}\frac{\partial u}{\partial t} - \operatorname{div}(\mathcal{A}\nabla u) + \mathbf{b} \cdot \nabla u + cu &= f && \text{in } \Omega \\ u &= g_D && \text{on } \Gamma_D \\ \alpha u + (\mathcal{A}\nabla u) \cdot \mathbf{n} &= g_N && \text{on } \Gamma_N \\ u(x, t) &= u_0(x) && \text{for } t = 0\end{aligned}$$

Conservation of Nonnegativity:

$$f \geq 0, \quad g_D \geq 0, \quad g_N \geq 0, \quad \text{and } u_0 \geq 0 \quad \Rightarrow \quad u \geq 0$$

## Parabolic problems

$$\begin{aligned}\frac{\partial u}{\partial t} - \Delta u &= 0 && \text{in } \Omega \\ u &= 0 && \text{on } \partial\Omega \\ u(x, t) &= u_0(x) && \text{for } t = 0\end{aligned}$$

Conservation of Nonnegativity:  $u_0 \geq 0 \Rightarrow u \geq 0$

Method of lines:

$$u_h(x, t) = \sum_{i=1}^N z_i(t) \varphi_j(x) \quad \Rightarrow \quad \begin{aligned} M\dot{\mathbf{z}}(t) + A\mathbf{z}(t) &= \mathbf{b} \\ \mathbf{z}(0) &= \mathbf{z}_0 \end{aligned}$$

- ▶ Semidiscretization: DMP fails on any mesh. [Vejchodský, 2004]
- ▶ Full-discretization: DMP satisfied for  $\Delta t > \tau$  [Faragó]
- ▶ Mass-lumping, FDM: DMP satisfied under the same conditions as in the elliptic case.