



A Poroelastoplastic Model for Saturated Clays Incorporating the Modified Cam-Clay Model

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Setting of the model

Balance Laws

Constitutive Relationships

Thermodynamical Consistency

Field equations

Setting of the model

- Non-stationary isothermal saturated water flow in a deformable clay.
- The clay is composed of an *incompressible* solid matrix (index s) and a porous space completely filled by water (index w).
- The poroelastoplastic modified Cam-Clay model with non-linear elasticity is used for the solid skeleton.
- Negligible inertial effects.
- Lagrangian formulation.
- The small-strain assumption.
- Compressive-positive pressures, tensile-positive stresses.
- Based on [Cou04].

Balance Laws

Under the small-strain assumption:

$$\frac{\partial(\phi\rho_w)}{\partial t} + \text{div}(\rho_w\mathbf{q}_{rw}) = 0$$

t — the time

ρ_w — the water mass density

ϕ — the Lagrangian porosity (with respect to the initial configuration)

$\mathbf{q}_{rw} \equiv n(\mathbf{v}_w - \mathbf{v}_s)$ — the Darcy velocity

n — the Eulerian porosity (with respect to the deformed configuration)

\mathbf{v}_w — the water velocity \mathbf{v}_s — the skeleton velocity

Under the small-strain assumption:

$$\mathbf{div} \boldsymbol{\sigma} + ((1 - \phi_0)\rho_s^0 + \phi\rho_w)\mathbf{f} = \mathbf{0}$$

$\boldsymbol{\sigma}$ — the Cauchy stress tensor ϕ_0 — an initial Lagrangian porosity

ρ_s^0 — the initial matrix mass density \mathbf{f} — a body force density

Constitutive Relationships

By considering the water to be compressible:

$$\frac{d\rho_w}{\rho_w} = \frac{dp_w}{K_w}$$

d — the differential operator with respect to time

p_w — the water pressure K_w — the water bulk modulus

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Assuming K_w constant (over some range of pressures), one obtains by integration:

$$\rho_w = \rho_w^0 e^{(p_w - p_w^0)/K_w}$$

ρ_w^0, p_w^0 — initial values of the water density and pressure

Transport of water is described by:

$$\mathbf{q}_{rw} = \frac{\mathbf{k}}{\mu_w} (-\nabla p_w + \rho_w \mathbf{f})$$

\mathbf{k} — the (intrinsic) permeability tensor of the porous medium

μ_w — the dynamic viscosity of water

The solid grains forming the matrix generally undergo negligible volume changes and the matrix can be assumed to be *incompressible*. This means that the matrix volume remains unchanged during the deformation:

$$(1 - n) dV_t = (1 - n_0) dV_0$$

n_0 — the initial Eulerian porosity

dV_0 — an arbitrary infinitesimal volume in the initial configuration

dV_t — the corresponding infinitesimal volume in the deformed configuration

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Use of transport formulae gives in the framework of small strains:

$$\phi = \phi_0 + \varepsilon_v$$

$\varepsilon_v \equiv \text{tr} \boldsymbol{\varepsilon}$ — the volumetric strain

$\boldsymbol{\varepsilon} \equiv \frac{1}{2} (\nabla \mathbf{u} + (\nabla \mathbf{u})^\top)$ — the linear strain tensor

\mathbf{u} — the displacement vector of the skeleton

Poroplasticity is the ability of porous materials to undergo permanent strains. In the context of small strains, the strain tensor $\boldsymbol{\varepsilon}$ can be decomposed into a reversible part (elastic, superscript el) and an irreversible one (plastic, superscript p) as follows:

$$\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}^{el} + \boldsymbol{\varepsilon}^p$$

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$$\boldsymbol{\sigma}' \equiv \boldsymbol{\sigma} + p_w \mathbf{I} \text{ — Terzaghi's effective stress}$$

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We introduce the decompositions:

$$\boldsymbol{\sigma}' = \mathbf{s} - p' \mathbf{I}$$

$$p' \equiv -\frac{1}{3} \text{tr} \boldsymbol{\sigma}' \text{ — the effective pressure} \quad \mathbf{s} \text{ — the deviatoric stress tensor}$$

$$\boldsymbol{\varepsilon} = \boldsymbol{\varepsilon}_d + \frac{1}{3} \boldsymbol{\varepsilon}_v \mathbf{I}$$

$$\boldsymbol{\varepsilon}_d \text{ — the deviatoric strain tensor}$$

When the porous material is subjected to an axial pressure $-\sigma_1$ in one direction and a uniform pressure $-\sigma_2 = -\sigma_3$ in the orthogonal directions, and the material is *isotropic*, it suffices to consider:

$q \equiv -(\sigma_1 - \sigma_3)$ — the deviatoric stress

$\epsilon_q \equiv -\frac{2}{3}(\epsilon_1 - \epsilon_3)$ — the deviatoric strain

$\epsilon_1, \epsilon_3 (= \epsilon_2)$ — principal strains

and we shall take

$$\epsilon_v := -\epsilon_v$$

The following elastic behaviour of clays has been experimentally found:

$$d\epsilon_v^{el} = \kappa^* \frac{dp'}{p'} \quad d\epsilon_q^{el} = \frac{dq}{3\mu}$$

$$\kappa^* := \frac{\kappa}{1 + e_0} \quad e_0 = \frac{\phi_0}{1 - \phi_0} \text{ — an initial void ratio}$$

κ — an elastic stiffness parameter μ — the shear modulus

$$\left(K(p') := \frac{p'}{\kappa^*} \text{ — the } \textit{tangent} \text{ bulk modulus} \right)$$

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By integration:

$$\epsilon_v^{el} = \kappa^* \ln \frac{p'}{p'_0} \quad \epsilon_q^{el} = \frac{q - q_0}{3\mu}$$

p'_0, q_0 — initial values of p'_0 and q

and by inversion:

$$p' = p'_0 \exp\left(\frac{\epsilon_v^{el}}{\kappa^*}\right) \quad q = 3\mu\epsilon_q^{el} + q_0$$

$$f(p', q, p_{co}) = \left(p' - \frac{p_{co}}{2}\right)^2 + \frac{q^2}{M^2} - \left(\frac{p_{co}}{2}\right)^2$$

p_{co} — the effective consolidation pressure

M — a material parameter

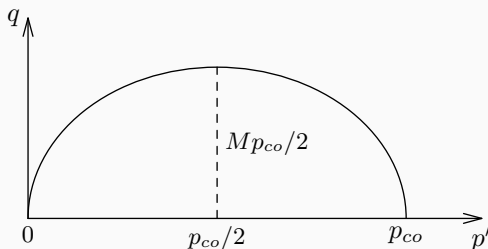


Figure 1: Yield surface $f = 0$.

$$d\epsilon_v^p = d\lambda \frac{\partial f}{\partial p'} = 2d\lambda \left(p' - \frac{p_{co}}{2} \right) \quad d\epsilon_q^p = d\lambda \frac{\partial f}{\partial q} = 2d\lambda \frac{q}{M^2}$$

where the plastic multiplier $d\lambda$ satisfies the complementarity conditions:

$$d\lambda \geq 0 \quad f \leq 0 \quad d\lambda \cdot f = 0$$

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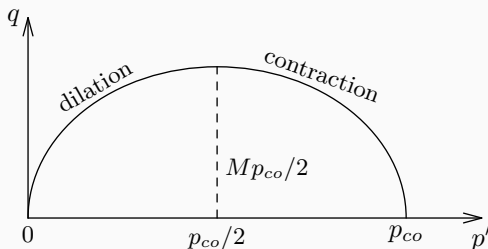


Figure 2: Yield surface.

The incremental law:

$$\frac{dp_{co}}{p_{co}} = \frac{1}{\lambda^* - \kappa^*} d\epsilon_v^p \quad \lambda^* := \frac{\lambda}{1 + e_0} \quad \kappa < \lambda \text{ — a parameter}$$

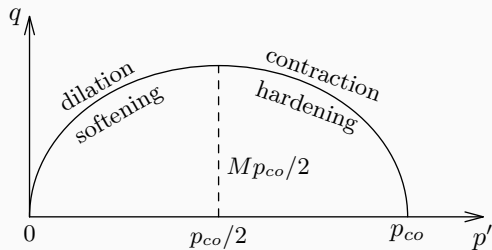


Figure 3: Yield surface.

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By integration:

$$p_{co} = p_{co}^0 \exp\left(\frac{\epsilon_v^p}{\lambda^* - \kappa^*}\right)$$

p_{co}^0 — a reference effective consolidation pressure

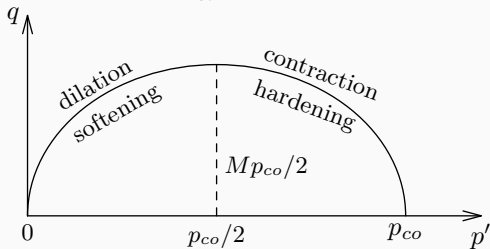


Figure 3: Yield surface.

Parameters		Initial (reference) values	
Water bulk modulus	K_w	Water pressure	p_w^0
Permeability (tensor)	\mathbf{k}	Water density	ρ_w^0
Dynamic viscosity of water	μ_w	Porosity (or void ratio)	ϕ_0 (e_0)
Elastic stiffness parameter	κ	Matrix density	ρ_s^0
Shear modulus	μ	Consolidation pressure	p_{co}^0
Shear strength	M	(Displacement	$\mathbf{u}_0 = \mathbf{0}$)
Plastic stiffness parameter	λ		

Thermodynamical Consistency

In the context of small isothermal strains, the non-negativeness of the dissipation associated with the skeleton saturated by water can be written as the following Clausius–Duhem inequality:

$$\boldsymbol{\sigma} : d\boldsymbol{\varepsilon} + p_w d\phi - d\Psi_s \geq 0$$

Ψ_s — the Helmholtz free energy of the skeleton

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By the incompressibility condition $d\phi = d\varepsilon_v$:

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and for an isotropic material under triaxial stress conditions:

$$p' d\varepsilon_v + q d\varepsilon_q - d\Psi_s \geq 0$$

Owing to the additive character of energy, the energy Ψ_s can be split into two parts:

- (i) the elastic energy F stored in the skeleton during reversible mechanical processes;
- (ii) the locked energy Z that is stored in the skeleton when irreversible (mechanical) processes take place:

$$\Psi_s = F(\epsilon_v^{el}, \epsilon_q^{el}) + Z(\chi)$$

χ — a hardening state variable

Inserting the energy decomposition into the dissipation condition, one gets:

$$\left(p' - \frac{\partial F}{\partial \epsilon_v^{el}}\right) d\epsilon_v^{el} + \left(q - \frac{\partial F}{\partial \epsilon_q^{el}}\right) d\epsilon_q^{el} + p' d\epsilon_v^p + q d\epsilon_q^p + \zeta d\chi \geq 0$$
$$\zeta \equiv -\frac{dZ}{d\chi} \text{ — the hardening force}$$

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From here:

$$p' = \frac{\partial F}{\partial \epsilon_v^{el}} \quad q = \frac{\partial F}{\partial \epsilon_q^{el}}$$
$$p' d\epsilon_v^p + q d\epsilon_q^p + \zeta d\chi \geq 0$$

Alternatively, by introducing the energy G by the following Legendre transformation:

$$G(p', q) = p' \epsilon_v^{el} + q \epsilon_q^{el} - F(\epsilon_v^{el}, \epsilon_q^{el})$$

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$$G(p', q) = p' \epsilon_v^{el} + q \epsilon_q^{el} - F(\epsilon_v^{el}, \epsilon_q^{el})$$

one obtains the state equations:

$$\epsilon_v^{el} = \frac{\partial G}{\partial p'} \quad \epsilon_q^{el} = \frac{\partial G}{\partial q}$$

The energy potential G:

$$G(p', q) = \kappa^* p' \left(\ln \frac{p'}{p'_0} - 1 \right) + \frac{(q - q_0)^2}{6\mu}$$

The energy potential F:

$$F(\epsilon_v^{el}, \epsilon_q^{el}) = \kappa^* p'_0 \exp\left(\frac{\epsilon_v^{el}}{\kappa^*}\right) + \frac{3}{2}\mu(\epsilon_q^{el})^2 + \epsilon_q^{el} q_0$$

We identify:

$\chi = \epsilon_v^p$ — the hardening variable $\zeta = -p_{co}$ — the hardening force

and we require:

$$p_{co} = \frac{dZ}{d\epsilon_v^p}$$

This is satisfied by taking:

$$Z(\epsilon_v^p) = (\lambda^* - \kappa^*) p_{co}^0 \exp\left(\frac{\epsilon_v^p}{\lambda^* - \kappa^*}\right)$$

It suffices to verify:

$$p' d\epsilon_v^p + q d\epsilon_q^p - p_{co} d\epsilon_v^p \geq 0$$

or by inserting the flow rule:

$$d\lambda \left[2p' \left(p' - \frac{p_{co}}{2} \right) + 2 \frac{q^2}{M^2} - 2p_{co} \left(p' - \frac{p_{co}}{2} \right) \right] \geq 0$$

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In virtue of the complementarity conditions either $d\lambda = 0$ or ($d\lambda > 0$ and $f = 0$). In the latter case, one arrives at:

$$2p' \left(p' - \frac{p_{co}}{2} \right) + 2 \frac{q^2}{M^2} - 2p_{co} \left(p' - \frac{p_{co}}{2} \right) = p_{co}(p_{co} - p')$$

Therefore one can conclude that the dissipated energy is non-negative over the whole range of admissible effective pressures p' ($p' \leq p_{co}$).

One can express the deviatoric strain ϵ_q and the deviatoric stress q from triaxial stress conditions as functions of the deviatoric tensors ϵ_d and \mathbf{s} :

$$\epsilon_q^2 = \frac{2}{3} \epsilon_d : \epsilon_d \quad \epsilon_q q = \epsilon_d : \mathbf{s} \quad q^2 = \frac{3}{2} \mathbf{s} : \mathbf{s}$$

This leads to:

$$F(\epsilon_v^{el}, \epsilon_d^{el}) = \kappa^* p'_0 \exp\left(\frac{\epsilon_v^{el}}{\kappa^*}\right) + \mu \epsilon_d^{el} : \epsilon_d^{el} + \epsilon_d^{el} : \mathbf{s}_0$$
$$f(p', \mathbf{s}, p_{co}) = \left(p' - \frac{p_{co}}{2}\right)^2 + \frac{2}{3M^2} \mathbf{s} : \mathbf{s} - \left(\frac{p_{co}}{2}\right)^2$$

and

$$\mathbf{s} = \frac{\partial F}{\partial \epsilon_d^{el}} = 2\mu \epsilon_d^{el} + \mathbf{s}_0$$
$$d\epsilon_d^p = d\lambda \frac{\partial f}{\partial \mathbf{s}} = \frac{d\lambda}{3M^2} \mathbf{s}$$

Field equations

One obtains:

$$\frac{\partial(\phi\rho_w)}{\partial t} = \rho_w \frac{\partial\phi}{\partial t} + \phi \frac{\partial\rho_w}{\partial t} = \rho_w \frac{\partial\varepsilon_v}{\partial t} + \frac{\phi\rho_w}{K_w} \frac{\partial p_w}{\partial t}$$
$$\operatorname{div}(\rho_w \mathbf{q}_{rw}) = \operatorname{div}\left(\rho_w \frac{\mathbf{k}}{\mu_w} (-\nabla p_w + \rho_w \mathbf{f})\right)$$

and the water mass balance equation provides:

$$\rho_w \frac{\partial\varepsilon_v}{\partial t} + \frac{\phi\rho_w}{K_w} \frac{\partial p_w}{\partial t} = -\operatorname{div}\left(\rho_w \frac{\mathbf{k}}{\mu_w} (-\nabla p_w + \rho_w \mathbf{f})\right)$$

By taking:

$$\boldsymbol{\sigma} = \boldsymbol{\sigma}' - p_w \mathbf{1} = \mathbf{s} - p' \mathbf{1} - p_w \mathbf{1}$$

and invoking the stress–strain relationship, one obtains:

$$-\frac{\partial p'}{\partial \varepsilon_v^{el}} \nabla \varepsilon_v^{el} + 2\mu \mathbf{div} \boldsymbol{\varepsilon}_d^{el} - \nabla p_w + ((1 - \phi_0)\rho_s^0 + \phi\rho_w) \mathbf{f} = \mathbf{0}$$



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John Wiley & Sons, 2004.

<https://doi.org/10.1002/0470092718>.