

LINEAR STIELTJES INTEGRAL EQUATIONS IN BANACH
SPACES II; OPERATOR VALUED SOLUTIONS

ŠTEFAN SCHWABIK, Praha

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Abstract. This paper is a continuation of [9]. In [9] results concerning equations of the form

$$x(t) = x(a) + \int_a^t d[A(s)]x(s) + f(t) - f(a)$$

were presented. The Kurzweil type Stieltjes integration in the setting of [6] for Banach space valued functions was used.

Here we consider operator valued solutions of the homogeneous problem

$$\Phi(t) = I + \int_d^t d[A(s)]\Phi(s)$$

as well as the variation-of-constants formula for the former equation.

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Assume that X is a Banach space and that $L(X)$ is the Banach space of all bounded linear operators $A: X \rightarrow X$ with the uniform operator topology. Defining the bilinear form $B: L(X) \times X \rightarrow X$ by $B(A, x) = Ax \in X$ for $A \in L(X)$ and $x \in X$, we obtain in a natural way the bilinear triple $\mathcal{B} = (L(X), X, X)$ (see [6]) because using the usual operator norm we have

$$\|B(A, x)\|_X \leq \|A\|_{L(X)}\|x\|_X.$$

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Similarly, if we define the bilinear form $B^*: L(X) \times L(X) \rightarrow L(X)$ by the relation $B^*(A, C) = AC \in L(X)$ for $A, C \in L(X)$ where AC is the composition of the linear operators A and C we get the bilinear triple $\mathcal{B}^* = (L(X), L(X), L(X))$ because we have

$$\|B^*(A, C)\|_{L(X)} \leq \|AC\|_{L(X)} \leq \|A\|_{L(X)}\|C\|_{L(X)}.$$

Assume that $[a, b] \subset \mathbb{R}$ is a bounded interval.

Given $A: [a, b] \rightarrow L(X)$, the function A is of *bounded variation on $[a, b]$* if

$$\text{var}_{[a,b]}(A) = \sup \left\{ \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} \right\} < \infty,$$

where the supremum is taken over all finite partitions

$$D: a = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = b$$

of the interval $[a, b]$. The set of all functions $A: [a, b] \rightarrow L(X)$ with $\text{var}_{[a,b]}(A) < \infty$ will be denoted by $BV([a, b]; L(X))$.

For $A: [a, b] \rightarrow L(X)$ and a partition D of the interval $[a, b]$ define

$$V_a^b(A, D) = \sup \left\{ \left\| \sum_{j=1}^k [A(\alpha_j) - A(\alpha_{j-1})]y_j \right\|_X \right\},$$

where the supremum is taken over all possible choices of $y_j \in X, j = 1, \dots, k$ with $\|y_j\| \leq 1$ and similarly

$$V_a^{*b}(A, D) = \sup \left\{ \left\| \sum_{j=1}^k [A(\alpha_j) - A(\alpha_{j-1})]C_j \right\|_{L(X)} \right\},$$

where the supremum is taken over all possible choices of $C_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1$.

Define

$$(\mathcal{B}) \text{var}_{[a,b]}(A) = \sup V_a^b(A, D)$$

and

$$(\mathcal{B}^*) \text{var}_{[a,b]}(A) = \sup V_a^{*b}(A, D)$$

where the supremum is taken over all finite partitions

$$D: a = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = b$$

of the interval $[a, b]$.

The function $A: [a, b] \rightarrow L(X)$ with $(\mathcal{B})\text{var}_{[a,b]}(A) < \infty$ is called a *function with bounded \mathcal{B} -variation on $[a, b]$* and similarly if $(\mathcal{B}^*)\text{var}_{[a,b]}(A) < \infty$ then A is of *bounded \mathcal{B}^* -variation on $[a, b]$* ([3]).

We denote by $(\mathcal{B})BV([a, b]; L(X))$ the set of all functions $A: [a, b] \rightarrow L(X)$ with $(\mathcal{B})\text{var}_{[a,b]}(A) < \infty$ and by $(\mathcal{B}^*)BV([a, b]; L(X))$ the set of all functions $A: [a, b] \rightarrow L(X)$ with $(\mathcal{B}^*)\text{var}_{[a,b]}(A) < \infty$.

In [9, Prop. 1.1 and 1.2] it is shown that

$$BV([a, b]; L(X)) \subset (\mathcal{B})BV([a, b]; L(X)) = (\mathcal{B}^*)BV([a, b]; L(X))$$

holds.

Given $x: [a, b] \rightarrow X$, the function x is called *regulated on $[a, b]$* if it has one-sided limits at every point of $[a, b]$, i.e. if for every $s \in [a, b)$ there is a value $x(s+) \in X$ such that

$$\lim_{t \rightarrow s+} \|x(t) - x(s+)\|_X = 0$$

and if for every $s \in (a, b]$ there is a value $x(s-) \in X$ such that

$$\lim_{t \rightarrow s-} \|x(t) - x(s-)\|_X = 0.$$

The set of all regulated functions $x: [a, b] \rightarrow X$ will be denoted by $G([a, b]; X)$ and similarly we denote the set of all regulated functions $A: [a, b] \rightarrow L(X)$ by $G([a, b]; L(X))$.

If $\mathcal{B} = (L(X), X, X)$ is the bilinear triple of Banach spaces mentioned above then a function $A: [a, b] \rightarrow L(X)$ is called *\mathcal{B} -regulated on $[a, b]$* if for every $y \in X$, $\|y\|_X \leq 1$, the function $Ay: [a, b] \rightarrow X$ given by $t \in [a, b] \mapsto A(t)y \in X$ for $t \in [a, b]$ is regulated, i.e. $Ay \in G([a, b]; X)$ for every $y \in X$, $\|y\|_X \leq 1$.

We denote by $(\mathcal{B})G([a, b]; L(X))$ the set of all \mathcal{B} -regulated functions $A: [a, b] \rightarrow L(X)$.

1. EQUATIONS WITH OPERATOR VALUED SOLUTIONS

For $[a, b] = [0, 1]$ we denote shortly

$$BV(L(X)) = BV([0, 1]; L(X)), (\mathcal{B})BV(L(X)) = (\mathcal{B})BV([0, 1]; L(X)),$$

$$G(L(X)) = G([0, 1]; L(X)) \text{ and } (\mathcal{B})G(L(X)) = (\mathcal{B})G([0, 1]; L(X)).$$

Assume that $A: [0, 1] \rightarrow L(X)$ satisfies

$$(1.1) \quad A \in (\mathcal{B})BV(L(X)) \cap (\mathcal{B})G(L(X))$$

and the following condition (E) (see [9]):

for every $d \in [0, 1]$ there are $0 < \varrho = \varrho(d) < 1$ and $\Delta = \Delta(d) > 0$ such that

$$(E+) \quad (\mathcal{B}) \operatorname{var}_{(d, d+\Delta] \cap [0, 1]}(A) < \varrho$$

and

$$(E-) \quad (\mathcal{B}) \operatorname{var}_{[d-\Delta, d) \cap [0, 1]}(A) < \varrho.$$

Taking the bilinear triple $\mathcal{B}^* = (L(X), L(X), L(X))$, by Proposition 1.1 in [9] we have

$$(\mathcal{B})BV(L(X)) = (\mathcal{B}^*)BV(L(X))$$

and

$$(\mathcal{B}) \operatorname{var}_{[a, b]}(A) = (\mathcal{B}^*) \operatorname{var}_{[a, b]}(A)$$

for every $[a, b] \subset [0, 1]$. Therefore condition (1.1) reads

$$(1.1) \quad A \in (\mathcal{B}^*)BV(L(X)) \cap (\mathcal{B})G(L(X)),$$

and in condition (E) the symbol \mathcal{B} can also be replaced by \mathcal{B}^* , i.e. condition (E) reads

for every $d \in [0, 1]$ there are $0 < \varrho = \varrho(d) < 1$ and $\Delta = \Delta(d) > 0$ such that

$$(E+) \quad (\mathcal{B}^*) \operatorname{var}_{(d, d+\Delta] \cap [0, 1]}(A) < \varrho$$

and

$$(E-) \quad (\mathcal{B}^*) \operatorname{var}_{[d-\Delta, d) \cap [0, 1]}(A) < \varrho.$$

Hence the results presented in Section 2 from [9] can be used for equations of the form

$$(1.2) \quad Y(t) = \tilde{Y} + \int_d^t d[A(s)]Y(s) + F(t) - F(d)$$

for every $t \in [0, 1]$ where $F \in G(L(X))$, $d \in [0, 1]$ and $\tilde{Y} \in L(X)$.

The operator valued function $Y: [\alpha, \beta] \rightarrow L(X)$ is called a solution of (1.2) on an interval $[\alpha, \beta] \subset [0, 1]$ if Y satisfies (1.2) for every $t \in [\alpha, \beta]$. If $d \in [\alpha, \beta]$ then of course we have $Y(d) = \tilde{Y}$ for this solution.

With regard to the above mentioned facts we obtain by a simple reformulation of Proposition 2.4 and Theorem 2.10 from [9] the following

1.1. Theorem. *Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.1) and condition (E). Then for every $d \in [0, 1]$, $\tilde{Y} \in X$, $F \in G(L(X))$ there is a $\Delta > 0$ such that for the interval $J_d = [d - \Delta, d + \Delta] \cap [0, 1]$ there is a unique function $Y \in G(J_d; L(X))$ such that*

$$Y(t) = \tilde{Y} + \int_d^t d[A(s)]Y(s) + F(t) - F(d), \quad t \in J_d,$$

i.e. $Y(t)$ is a local solution of the operator valued equation (1.2) on $J_d = [d - \Delta, d + \Delta] \cap [0, 1]$.

If

$$(1.3) \quad A \in (\mathcal{B})BV(L(X)) \cap G(L(X)),$$

condition (U):

$$(U+) \quad [I + \Delta^+ A(t)]^{-1} \in L(X) \text{ exists for every } t \in [0, 1]$$

and

$$(U-) \quad [I - \Delta^- A(t)]^{-1} \in L(X) \text{ exists for every } t \in (0, 1]$$

and (E) hold, then for every choice of $d \in [0, 1]$, $\tilde{Y} \in L(X)$, $F \in G([0, 1]; L(X))$ there exists a unique $Y \in G([0, 1]; X)$ which is a (global) solution of (1.2) on $[0, 1]$.

Let us consider the special case of the equation (1.2) with F a constant, i.e. the so called homogeneous equation

$$(1.4) \quad Y(t) = \tilde{Y} + \int_d^t d[A(s)]Y(s).$$

Theorem 1.1 applies to this equation and therefore there is a unique (global) solution to this equation and this operator valued solution is regulated provided $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

Together with (1.4) let us consider the equation

$$(1.5) \quad \Phi(t) = I + \int_d^t d[A(s)]\Phi(s)$$

where $I \in L(X)$ is the identity operator.

Clearly every solution $Y: [0, 1] \rightarrow L(X)$ of (1.4) can be written in the form

$$Y(t) = \Phi(t)\tilde{Y}, \quad t \in [0, 1].$$

Let us now consider the properties of the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5).

1.2. Lemma. *Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U). Then for the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5) we have*

$$\Phi \in (\mathcal{B})BV(L(X)) \cap G(L(X))$$

and there is a constant $K > 0$ such that $\|\Phi(t)\| \leq K$ for every $t \in [0, 1]$.

Proof. By Theorem 1.1 $\Phi \in G([0, 1]; L(X))$ and therefore there exists a $K > 0$ such that $\|\Phi(t)\| \leq K$ for every $t \in [0, 1]$. It remains to show that $\Phi \in (\mathcal{B})BV([0, 1]; L(X))$.

Assume that

$$D: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval $[0, 1]$.

For any $y_j \in X, j = 1, \dots, k$ with $\|y_j\| \leq 1$ we have

$$\left\| \sum_{j=1}^k [\Phi(\alpha_j) - \Phi(\alpha_{j-1})]y_j \right\|_X = \left\| \sum_{j=1}^k \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)]\Phi(s)y_j \right\|_X.$$

Define

$$\varphi(s) = \Phi(s)y_j \text{ for } s \in (\alpha_{j-1}, \alpha_j) \text{ and } \varphi(s) = 0 \text{ for } s = \alpha_j.$$

Evidently $\|\varphi(s)\| \leq K$.

Then by 1.18 from [9] we get

$$\begin{aligned} \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)]\Phi(s)y_j &= \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)]\varphi(s) \\ &+ [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j + [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j \end{aligned}$$

and

$$\begin{aligned}
& \left\| \sum_{j=1}^k \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)\Phi(s)y_j] \right\|_X = \left\| \sum_{j=1}^k \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)]\varphi(s) \right. \\
& \quad \left. + [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j + [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j \right\|_X \\
& = \left\| \int_0^1 d[A(s)]\varphi(s) + \sum_{j=1}^k [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right. \\
& \quad \left. + \sum_{j=1}^k [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j \right\|_X \leq \left\| \int_0^1 d[A(s)]\varphi(s) \right\|_X \\
& \quad + \left\| \sum_{j=1}^k [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right\|_X + \left\| \sum_{j=1}^k [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j \right\|_X.
\end{aligned}$$

For a given $\eta > 0$ let us choose a $\theta > 0$ such that

$$\|A(\alpha_{j-1} + \theta) - A(\alpha_{j-1}+)\|_{L(X)} < \frac{\eta}{k+1}$$

and

$$\|A(\alpha_j - \theta) - A(\alpha_j-)\|_{L(X)} < \frac{\eta}{k+1}$$

for all $j = 1, \dots, k$. Then

$$\begin{aligned}
& \left\| \sum_{j=1}^k [A(\alpha_{j-1}+) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right\|_X \\
& = \left\| \sum_{j=1}^k [A(\alpha_{j-1}+) - A(\alpha_{j-1} + \theta) + A(\alpha_{j-1} + \theta) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right\|_X \\
& \leq \left\| \sum_{j=1}^k [A(\alpha_{j-1}+) - A(\alpha_{j-1} + \theta)]\Phi(\alpha_{j-1})y_j \right\|_X \\
& \quad + \left\| \sum_{j=1}^k [A(\alpha_{j-1} + \theta) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right\|_X \\
& < \sum_{j=1}^k \frac{K\eta}{k+1} + \left\| \sum_{j=1}^k [A(\alpha_{j-1} + \theta) - A(\alpha_{j-1})]\Phi(\alpha_{j-1})y_j \right\|_X \\
& < K\eta + K(\mathcal{B}) \operatorname{var}_{[0,1]}(A)
\end{aligned}$$

and similarly also

$$\left\| \sum_{j=1}^k [A(\alpha_j) - A(\alpha_j-)]\Phi(\alpha_j)y_j \right\|_X < K\eta + K(\mathcal{B}) \operatorname{var}_{[0,1]}(A).$$

By 1.11 from [9] we have further

$$\left\| \int_0^1 d[A(s)]\varphi(s) \right\|_X \leq K(\mathcal{B}) \operatorname{var}_{[0,1]}(A)$$

and finally we obtain

$$\left\| \sum_{j=1}^k [\Phi(\alpha_j) - \Phi(\alpha_{j-1})]y_j \right\|_X = \left\| \sum_{j=1}^k \int_{\alpha_{j-1}}^{\alpha_j} d[A(s)]\Phi(s)y_j \right\|_X < 2K\eta + 3K(\mathcal{B}) \operatorname{var}_{[0,1]}(A).$$

Passing to the corresponding suprema we arrive easily at

$$(\mathcal{B}) \operatorname{var}_{[0,1]}(\Phi) \leq 3K(\mathcal{B}) \operatorname{var}_{[0,1]}(A) < \infty,$$

i.e. $\Phi \in (\mathcal{B})BV([0, 1]; L(X))$. □

1.3. Lemma. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

Then the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5) has an inverse $[\Phi(t)]^{-1} \in L(X)$ for every $t \in [0, 1]$.

Proof. For $t = d$ we have $\Phi(t) = \Phi(d) = I$ and the inverse $[\Phi(t)]^{-1}$ evidently exists for this value.

Assume that there is a point $t^* \in [0, 1]$ such that the inverse $[\Phi(t^*)]^{-1}$ does not exist. Then there exists $y \in X$ such that the equation

$$\Phi(t^*)z = y$$

has no solution in X . Assume that $\Psi: [0, 1] \rightarrow L(X)$ is a solution of the operator valued equation

$$\Psi(t) = I + \int_{t^*}^t d[A(s)]\Psi(s);$$

this solution exists and is uniquely determined by the second part of Theorem 1.1. Let us set $z = \Psi(d)y$. The function $x: [0, 1] \rightarrow X$ given by $x(t) = \Psi(t)y$ is a solution of the equation

$$x(t) = y + \int_{t^*}^t d[A(s)]x(s)$$

with $x(t^*) = y$ and $x(d) = \Psi(d)y$. On the other hand, $\varphi(t) = \Phi(t)z$ is a solution of

$$\varphi(t) = z + \int_d^t d[A(s)]\varphi(s)$$

where $\varphi(d) = z = \Psi(d)y = x(d)$ and

$$x(t) = x(d) + \int_d^t d[A(s)]x(s).$$

Hence by the uniqueness of a solution stated in Theorem 2.10 from [9] we have $x(t) = \varphi(t)$ for all $t \in [0, 1]$. Therefore

$$x(t^*) = y = \varphi(t^*) = \Phi(t^*)z = \Phi(t^*)\Psi(d)y,$$

i.e. $z = \Psi(d)y \in X$ is a solution of the equation $\Phi(t^*)z = y$. This contradicts the assumption and proves that the operator $\Phi(t) \in L(X)$ has an inverse for every $t \in [0, 1]$. \square

1.4. Lemma. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

Then the inverse $[\Phi(t)]^{-1} = \Phi^{-1}(t)$ to the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5) belongs to $G(L(X))$ and there is a constant $L > 0$ such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

for every $t \in [0, 1]$.

Proof. By Theorem 1.1 we have $\Phi \in G(L(X))$ and therefore the on-sided limits of this function exist at every point of $[0, 1]$. E. g., the limit $\lim_{r \rightarrow t+} \Phi(r)$ exists for every $t \in [0, 1)$ and by 1.18 from [9] we have

$$\begin{aligned} \lim_{r \rightarrow t+} \Phi(r) &= I + \lim_{r \rightarrow t+} \int_d^r d[A(s)]\Phi(s) = I + \int_d^t d[A(s)]\Phi(s) \\ &\quad + \lim_{r \rightarrow t+} \int_t^r d[A(s)]\Phi(s) = \Phi(t) + \lim_{r \rightarrow t+} \int_t^r d[A(s)]\Phi(s) \\ &= \Phi(t) + [A(t+) - A(t)]\Phi(t) = [I + \Delta^+ A(t)]\Phi(t). \end{aligned}$$

Hence $\Phi(t+) = [I + \Delta^+ A(t)]\Phi(t)$ and because $\Phi^{-1}(t)$ exists by Lemma 1.3 and the inverse $[I + \Delta^+ A(t)]^{-1}$ exists by (U+) from the assumption (U) the inverse $[\Phi(t+)]^{-1} = \Phi^{-1}(t+)$ also exists and we have the relation

$$[\Phi(t+)]^{-1} = \Phi^{-1}(t+) = \Phi^{-1}(t) \cdot [I + \Delta^+ A(t)]^{-1}, \quad t \in [0, 1).$$

Similarly we have also

$$\Phi^{-1}(t-) = \Phi^{-1}(t) \cdot [I - \Delta^- A(t)]^{-1}, \quad t \in (0, 1]$$

where $\Phi^{-1}(t-) = [\Phi(t-)]^{-1}$.

Using the continuity of the operation of taking an inverse (see [2], p. 624) we obtain

$$\lim_{r \rightarrow t+} \Phi^{-1}(r) = \Phi^{-1}(t+) \text{ for } t \in [0, 1]$$

and

$$\lim_{r \rightarrow t-} \Phi^{-1}(r) = \Phi^{-1}(t-) \text{ for } t \in (0, 1]$$

because $\lim_{r \rightarrow t+} \Phi(r) = \Phi(t+)$ for $t \in [0, 1)$ and $\lim_{r \rightarrow t-} \Phi(r) = \Phi(t-)$ for $t \in (0, 1]$.

Hence the operator valued function $\Phi^{-1}: [0, 1] \rightarrow L(X)$ belongs to the space $G(L(X))$ and it is therefore bounded, i.e. there is an $L \geq 0$ such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

for every $t \in [0, 1]$. □

1.5. Lemma. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

Assume that $d \in [0, 1]$ is fixed and that $\Phi: [0, 1] \rightarrow L(X)$ is the solution of (1.5). Then for every $t_0 \in [0, 1]$ and $\tilde{x} \in X$, the unique solution $x: [0, 1] \rightarrow X$ of the homogeneous equation

$$x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s)$$

is given by the relation

$$x(t) = \Phi(t)\Phi^{-1}(t_0)\tilde{x}, \quad t \in [0, 1].$$

Proof. The solution x exists and is unique by Theorem 2.11 in [9]. Using (1.1) we have

$$\begin{aligned} x(t) &= \Phi(t)\Phi^{-1}(t_0)\tilde{x} = \left[I + \int_d^t d[A(s)]\Phi(s) \right] \Phi^{-1}(t_0)\tilde{x} \\ &= \left[I + \int_d^{t_0} d[A(s)]\Phi(s) + \int_{t_0}^t d[A(s)]\Phi(s) \right] \Phi^{-1}(t_0)\tilde{x} \\ &= \Phi(t_0)\Phi^{-1}(t_0)\tilde{x} + \int_{t_0}^t d[A(s)]\Phi(s)\Phi^{-1}(t_0)\tilde{x} = \tilde{x} + \int_{t_0}^t d[A(s)]x(s) \end{aligned}$$

and the lemma is proved. □

2. VARIATION OF CONSTANTS

2.1. Lemma. *Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U). Let $\Phi: [0, 1] \rightarrow L(X)$ be the solution of (1.5) and assume that its inverse $\Phi^{-1}: [0, 1] \rightarrow L(X)$ given by Lemma 1.3 is such that $\Phi^{-1} \in (\mathcal{B})BV(L(X))$.*

Then for every $g \in G(X)$, $t \in [0, 1]$ the equality

$$(2.1) \quad \int_d^t d[A(r)]\Phi(r) \int_d^r d[\Phi^{-1}(s)]g(s) = \Phi(t) \int_d^t d[\Phi^{-1}(s)]g(s) + \int_d^t d[A(s)]g(s)$$

holds.

Proof. Since $g \in G(X)$ and $\Phi^{-1} \in (\mathcal{B})BV(L(X))$, the integrals on both sides of (2.1) exist by [6, Theorem 11] (see also [9, 1.12]).

To show that the equality (2.1) is valid for every regulated function $g: [0, 1] \rightarrow X$ it is sufficient to prove it for an arbitrary finite step function, because the finite step functions are dense in the space $G(X)$ (see [2]).

For a given $\alpha \in [0, 1]$, $c \in X$ and for $s \in [0, 1]$ we define

$$\psi_\alpha^+(s) = 0 \text{ if } s \leq \alpha, \quad \psi_\alpha^+(s) = c \text{ if } s > \alpha$$

and

$$\psi_\alpha^-(s) = 0 \text{ if } s < \alpha, \quad \psi_\alpha^-(s) = c \text{ if } s \geq \alpha.$$

It is a matter of routine to verify that every finite step function can be expressed in the form of a finite sum of functions of the type ψ_α^+ and ψ_α^- . Hence by the linearity of the integral it suffices to show that (2.1) holds for functions of this type.

Let us prove e.g. that (2.1) is satisfied for the function ψ_α^+ .

Assume that $\alpha < d$. Then

$$\int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) = [\Phi^{-1}(r) - \Phi^{-1}(d)]c \text{ if } r > \alpha$$

and

$$(2.2) \quad \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) = [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \text{ if } r \leq \alpha.$$

Hence for $t > \alpha$ we have

$$(2.3) \quad \begin{aligned} & \int_d^t d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \\ &= \int_d^t d[A(r)]\Phi(r)[\Phi^{-1}(r) - \Phi^{-1}(d)]c = \int_d^t d[A(r)][I - \Phi(r)\Phi^{-1}(d)]c \\ &= [A(t) - A(d)]c - [\Phi(t) - \Phi(d)]\Phi^{-1}(d)c = [A(t) - A(d)]c + c - \Phi(t)\Phi^{-1}(d)c. \end{aligned}$$

If $t \leq \alpha$ then

$$\begin{aligned} & \int_d^t d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) = - \int_t^d d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \\ & = - \left(\int_t^\alpha d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) + \int_\alpha^d d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \right) \end{aligned}$$

and

$$\begin{aligned} & \int_\alpha^d d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \\ & = [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \\ & \quad + \lim_{\delta \rightarrow 0+} \int_{\alpha+\delta}^d d[A(r)]\Phi(r)[\Phi^{-1}(r) - \Phi^{-1}(d)]c \\ & = [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \\ & \quad + \lim_{\delta \rightarrow 0+} \int_{\alpha+\delta}^d d[A(r)]c - \lim_{\delta \rightarrow 0+} \int_{\alpha+\delta}^d d[A(r)]\Phi(r)\Phi^{-1}(d)c \\ & = [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c + [A(d) - A(\alpha+)]c \\ & \quad - [\Phi(d) - \Phi(\alpha+)]\Phi^{-1}(d)c. \end{aligned}$$

Further we have

$$\int_t^\alpha d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) = [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c$$

and

$$\begin{aligned} & \int_d^t d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \\ & = - \{ [A(\alpha+) - A(\alpha)]\Phi(\alpha)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c + [A(d) - A(\alpha+)]c \\ & \quad - [\Phi(d) - \Phi(\alpha+)]\Phi^{-1}(d)c + [\Phi(\alpha) - \Phi(t)][\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \}. \end{aligned}$$

Since $[A(\alpha+) - A(\alpha)]\Phi(\alpha) = \Delta^+ A(\alpha)\Phi(\alpha) = \Phi(\alpha+) - \Phi(\alpha)$ we have

$$\begin{aligned} & \int_d^t d[A(r)]\Phi(r) \int_d^r d_s[\Phi^{-1}(s)]\psi_\alpha^+(s) \\ & = - \{ [\Phi(\alpha+) - \Phi(\alpha)][\Phi^{-1}(\alpha+) - \Phi^{-1}(d)] + [A(d) - A(\alpha+)] \\ (2.4) \quad & \quad - I + \Phi(\alpha+)\Phi^{-1}(d) + \Phi(\alpha)\Phi^{-1}(\alpha+) - \Phi(\alpha)\Phi^{-1}(d) \\ & \quad - \Phi(t)\Phi^{-1}(\alpha+) + \Phi(t)\Phi^{-1}(d) \} c \\ & = - \{ [A(d) - A(\alpha+)] - \Phi(t)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)] \} c \\ & = [A(\alpha+) - A(d)]c + \Phi(t)[\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \end{aligned}$$

for $t \leq \alpha$.

For the right hand side of (2.1) we use (2.2) for obtaining

$$\Phi(t) \int_d^t d[\Phi^{-1}(s)]\psi_\alpha^+(s) = \Phi(t)[\Phi^{-1}(t) - \Phi^{-1}(d)]c \text{ if } t > \alpha$$

and

$$(2.5) \quad \Phi(t) \int_d^t d[\Phi^{-1}(s)]\psi_\alpha^+(s) = [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c \text{ if } t \leq \alpha.$$

Now it is a matter of routine to show that

$$\int_d^t d[A(s)]\psi_\alpha^+(s) = [A(t) - A(d)]c \text{ if } t > \alpha$$

and

$$(2.6) \quad \int_d^t d[A(s)]\psi_\alpha^+(s) = [A(\alpha+) - A(d)]c \text{ if } t \leq \alpha.$$

Using (2.5) and (2.6) we obtain

$$\begin{aligned} \Phi(t) \int_d^t d[\Phi^{-1}(s)]\psi_\alpha^+(s) + \int_d^t d[A(s)]\psi_\alpha^+(s) \\ = -\Phi(t)[\Phi^{-1}(t) - \Phi^{-1}(d)]c + [A(t) - A(d)]c \text{ if } t > \alpha \end{aligned}$$

and

$$\begin{aligned} \Phi(t) \int_d^t d[\Phi^{-1}(s)]\psi_\alpha^+(s) + \int_d^t d[A(s)]\psi_\alpha^+(s) \\ = [\Phi^{-1}(\alpha+) - \Phi^{-1}(d)]c + [A(\alpha+) - A(d)]c \text{ if } t \leq \alpha. \end{aligned}$$

Looking at (2.3) and (2.4) we can see immediately that the equality (2.1) holds for the function ψ_α^+ if $\alpha < d$.

For $\alpha \geq d$ as well as for the case of the function ψ_α^- the result can be proved similarly. The computations are straightforward but slightly tedious. \square

Let us assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

Let us consider the equation

$$(2.7) \quad x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s) + f(t) - f(t_0).$$

By [9, Theorem 2.10] we obtain that
for every choice of $t_0 \in [0, 1]$, $\tilde{x} \in X$, $f \in G(X)$ there exists $x \in G(X)$ such that

$$x(t) = \tilde{x} + \int_{t_0}^t d[A(s)]x(s) + f(t) - f(t_0)$$

for every $t \in [0, 1]$.

This solution of (2.7) is determined uniquely.

2.2. Theorem. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U). Let $\Phi: [0, 1] \rightarrow L(X)$ be the solution of (1.5) and assume that its inverse $\Phi^{-1}: [0, 1] \rightarrow L(X)$ given by Lemma 1.3 is such that $\Phi^{-1} \in (\mathcal{B})BV(L(X))$.

Then for every $t_0 \in [0, 1]$, $\tilde{x} \in X$ and $f \in G(X)$ the formula

$$(2.8) \quad x(t) = \Phi(t)\Phi^{-1}(t_0)\tilde{x} + f(t) - f(t_0) - \Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)](f(s) - f(t_0)),$$

$t \in [0, 1]$, represents a solution of (2.7).

Proof. Using (2.8) we have for $t \in [0, 1]$

$$\begin{aligned} & \int_{t_0}^t d[A(r)]x(r) \\ &= \int_{t_0}^t d[A(r)] \left\{ \Phi(r)\Phi^{-1}(t_0)\tilde{x} + f(r) - f(t_0) - \Phi(r) \int_{t_0}^r d[\Phi^{-1}(s)](f(s) - f(t_0)) \right\} \\ &= \int_{t_0}^t d[A(r)]\Phi(r)\Phi^{-1}(t_0)\tilde{x} + \int_{t_0}^t d[A(r)](f(r) - f(t_0)) \\ & \quad - \int_{t_0}^t d[A(r)]\Phi(r) \int_{t_0}^r d[\Phi^{-1}(s)](f(s) - f(t_0)). \end{aligned}$$

For a solution Φ of (1.5) we have

$$\int_{t_0}^t d[A(r)]\Phi(r) = \Phi(t) - \Phi(t_0)$$

and by Lemma 2.1 we have

$$\begin{aligned} & \int_{t_0}^t d[A(r)]\Phi(r) \int_{t_0}^r d[\Phi^{-1}(s)](f(s) - f(t_0)) \\ &= \Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)](f(s) - f(t_0)) + \int_{t_0}^t d[A(s)](f(s) - f(t_0)). \end{aligned}$$

Therefore

$$\begin{aligned}
& \int_{t_0}^t d[A(r)]x(r) \\
&= [\Phi(t) - \Phi(t_0)]\Phi^{-1}(t_0)\tilde{x} + \int_{t_0}^t d[A(r)](f(r) - f(t_0)) \\
&\quad - \Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)](f(s) - f(t_0)) - \int_{t_0}^t d[A(s)](f(s) - f(t_0)) = \Phi(t)\Phi^{-1}(t_0)\tilde{x} - \tilde{x} \\
&\quad - \Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)](f(s) - f(t_0)).
\end{aligned}$$

Hence

$$\int_{t_0}^t d[A(r)]x(r) = x(t) - \tilde{x} - (f(t) - f(t_0))$$

for every $t \in [0, 1]$ and this means that the function $x: [0, 1] \rightarrow X$ given by (2.8) is a solution of the equation (2.7). \square

Remark. From the point of view of the variation-of-constants formula (2.8) presented in Theorem 2.2 the assumption that the inverse $\Phi^{-1}: [0, 1] \rightarrow L(X)$ to $\Phi: [0, 1] \rightarrow L(X)$ given by Lemma 1.3 is such that $\Phi^{-1} \in (\mathcal{B})BV(L(X))$ is very unnatural. It would be nice if the property $\Phi^{-1} \in (\mathcal{B})BV(L(X))$ could be derived from the general assumptions, i.e. from the fact that $A: [0, 1] \rightarrow L(X)$ satisfies (1.3), (E) and (U).

In the next section we will show that in the special situation of $A \in BV(L(X))$ the variation-of-constants formula (2.8) holds without any further assumption.

3. THE VARIATION-OF-CONSTANTS FORMULA FOR THE CASE $A \in BV(L(X))$

Assume throughout this section that $A \in BV(L(X))$.

First of all it should be mentioned that by [9, 1.5] we have $A \in G(L(X))$ and therefore $A: [0, 1] \rightarrow L(X)$ evidently satisfies (1.3) because, as was already mentioned in the introductory part of this note, we have $BV(L(X)) \subset (\mathcal{B})BV(L(X))$ by [9, Prop. 1.1 and 1.2].

As was mentioned in the last Remark in [9], if $A \in BV(L(X))$ then A satisfies also condition (E).

Let us now prove the following proposition.

3.1. Proposition. *Assume that $A: [0, 1] \rightarrow L(X)$.*

Then $A \in BV(L(X))$ if and only if

$$(3.1) \quad \sup_P \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \right\} < \infty$$

where $P: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$ is a partition of $[0, 1]$, $C_j, D_j \in L(X)$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1, j = 1, \dots, k$, and

$$\text{var}_{[0,1]}(A) = \sup_P \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \right\}.$$

Proof. Assume that

$$P: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of $[0, 1]$.

If $C_j, D_j \in L(X)$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1, j = 1, \dots, k$ then

$$\begin{aligned} & \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \\ & \leq \sum_{j=1}^k \|D_j\|_{L(X)} \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} \|C_j\|_{L(X)} \\ & \leq \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)}. \end{aligned}$$

Hence

$$\sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \leq \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)}$$

where the supremum on the left hand side is taken over all $C_j, D_j \in L(X)$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$. Consequently,

$$(3.2) \quad \begin{aligned} & \sup_P \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \right\} \\ & \leq \sup_P \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} = \text{var}_{[0,1]}(A). \end{aligned}$$

Assume that $\widehat{D}_j \in L(X)$ with $\|\widehat{D}_j\|_{L(X)} \leq 1$ and $x_j \in X$ with $\|x_j\|_X \leq 1$, $j = 1, \dots, k$. Let us take $w \in X$ such that $\|w\|_X = 1$. Then for all $j = 1, \dots, k$ there exist $\widehat{C}_j \in L(X)$ with $\|\widehat{C}_j\|_{L(X)} \leq 1$ such that $\widehat{C}_j w = x_j$. Hence

$$\begin{aligned} \left\| \sum_{j=1}^k \widehat{D}_j [A(\alpha_j) - A(\alpha_{j-1})] x_j \right\|_X &= \left\| \sum_{j=1}^k \widehat{D}_j [A(\alpha_j) - A(\alpha_{j-1})] \widehat{C}_j w \right\|_X \\ &\leq \sup_{\|y\|_X \leq 1} \left\| \sum_{j=1}^k \widehat{D}_j [A(\alpha_j) - A(\alpha_{j-1})] \widehat{C}_j y \right\|_X \\ &= \left\| \sum_{j=1}^k \widehat{D}_j [A(\alpha_j) - A(\alpha_{j-1})] \widehat{C}_j \right\|_{L(X)} \\ &\leq \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \end{aligned}$$

where the supremum on the right hand side is taken over all $C_j, D_j \in L(X)$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$. Passing to the supremum over all $\widehat{D}_j \in L(X)$ with $\|\widehat{D}_j\|_{L(X)} \leq 1$ and $x_j \in X$ with $\|x_j\|_X \leq 1$, $j = 1, \dots, k$ we get

$$(3.3) \quad \begin{aligned} \sup_{x_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] x_j \right\|_X \\ \leq \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)}. \end{aligned}$$

Assume that $\varepsilon > 0$ is given. Choose vectors $x_j \in X$ with $\|x_j\|_X \leq 1$, $j = 1, \dots, k$ such that

$$(3.4) \quad \|[A(\alpha_j) - A(\alpha_{j-1})]x_j\|_X > \|[A(\alpha_j) - A(\alpha_{j-1})]\|_{L(X)} - \frac{\varepsilon}{k}.$$

Let us set

$$v_j = \frac{[A(\alpha_j) - A(\alpha_{j-1})]x_j}{\|[A(\alpha_j) - A(\alpha_{j-1})]x_j\|_X} \text{ if } [A(\alpha_j) - A(\alpha_{j-1})]x_j \neq 0$$

and

$$v_j = 0 \text{ if } [A(\alpha_j) - A(\alpha_{j-1})]x_j = 0.$$

For $v_j \neq 0$ let Y_j be the onedimensional subspace of X given by

$$Y_j = \{\lambda v_j; \lambda \in \mathbb{R}\}$$

and assume that \tilde{f}_j is a bounded linear functional on Y_j such that $\tilde{f}_j(v_j) = 1$ and denote by $f_j \in X^*$ its extension onto X with $\|f_j\| = 1$.

Assume that $w \in X$ is fixed such that $\|w\|_X = 1$ and define the linear operator $D_j \in L(X)$ by the relation

$$D_j x = f_j(x)w, \quad x \in X, \quad j = 1, \dots, k.$$

Then certainly

$$\|D_j\|_{L(X)} = \|f_j\| \|w\| = 1$$

and

$$\begin{aligned} D_j[A(\alpha_j) - A(\alpha_{j-1})]x_j &= \|A(\alpha_j) - A(\alpha_{j-1})\|_X D_j v_j \\ &= \|A(\alpha_j) - A(\alpha_{j-1})\|_X f_j(v_j)w = \|A(\alpha_j) - A(\alpha_{j-1})\|_X w. \end{aligned}$$

Hence by (3.4) we get

$$\begin{aligned} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]x_j \right\|_X &= \left\| \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_X w \right\|_X \\ &= \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_X > \sum_{j=1}^k (\|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} - \frac{\varepsilon}{k}) \\ &= \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} - \varepsilon. \end{aligned}$$

Taking the supremum over all $D_j \in L(X)$ with $\|D_j\|_{L(X)} \leq 1$ and $x_j \in X$ with $\|x_j\|_X \leq 1$, $j = 1, \dots, k$ we get

$$\sup_{x_j, D_j} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]x_j \right\|_X > \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} - \varepsilon$$

and using (3.3) we finally obtain

$$\sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]C_j \right\|_{L(X)} \geq \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\|_{L(X)} - \varepsilon.$$

Taking the supremum over all partitions P of $[0, 1]$ we obtain together with (3.2) for every $\varepsilon > 0$ the inequality

$$\text{var}(A) - \varepsilon < \sup_P \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j[A(\alpha_j) - A(\alpha_{j-1})]C_j \right\|_{L(X)} \right\} \leq \text{var}(A)$$

and therefore

$$\operatorname{var}_{[0,1]}(A) = \sup_P \left\{ \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [A(\alpha_j) - A(\alpha_{j-1})] C_j \right\|_{L(X)} \right\}.$$

□

Remark. It has to be mentioned that the characterization of the space $BV(L(X))$ given by Proposition 3.1 is interesting independently of the context of the equations studied in this paper.

3.2. Lemma. *Assume that $A: [0, 1] \rightarrow L(X)$ satisfies $A \in BV(L(X))$ and (U). Then for the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5) we have $\Phi \in BV(L(X))$.*

Proof. Since $BV(L(X)) \subset (\mathcal{B}^*)BV(L(X))$ the conclusion of Lemma 1.2 holds and there exists a $K > 0$ such that $\|\Phi(t)\| \leq K$ for every $t \in [0, 1]$. It remains to show that the relation $\Phi \in BV(L(X))$ holds.

Assume that

$$P: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval $[0, 1]$ and that $C_j, D_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$ are given.

The fact that $\Phi \in G(L(X))$ yields by [6, Prop. 15] the existence of the integral $\int_0^1 d[A(r)]\Phi(r)$ and therefore by definition for every $\varepsilon > 0$ there is a gauge $\delta: [0, 1] \rightarrow (0, \infty)$ such that

$$\left\| \sum_{i=1}^l [A(\beta_i) - A(\beta_{i-1})]\Phi(\sigma_i) - \int_0^1 d[A(r)]\Phi(r) \right\|_{L(X)} < \frac{\varepsilon}{k+1}$$

for every δ -fine P-partition

$$\{\beta_0, \sigma_1, \beta_1, \dots, \beta_{l-1}, \sigma_l, \beta_l\}$$

of the interval $[0, 1]$.

By the Saks-Henstock Lemma (see [6, Lemma 16]) we have

$$(3.5) \quad \left\| \sum_{i=1}^{l_j} [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) - \int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r) \right\|_{L(X)} \leq \frac{\varepsilon}{k+1}$$

for every δ -fine P-partition

$$\{\beta_0^j, \sigma_1^j, \beta_1^j, \dots, \beta_{l_j-1}^j, \sigma_{l_j}^j, \beta_{l_j}^j\}$$

of the interval $[\alpha_{j-1}, \alpha_j]$, $j = 1, \dots, k$.

Further, we have

$$\Phi(\alpha_j) - \Phi(\alpha_{j-1}) = \int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r)$$

for every $j = 1, \dots, k$ by the definition of a solution of (1.5) and therefore

$$\begin{aligned} & \left\| \sum_{j=1}^k D_j [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] C_j \right\|_{L(X)} = \left\| \sum_{j=1}^k D_j \left[\int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r) \right] C_j \right\|_{L(X)} \\ & = \left\| \sum_{j=1}^k \left\{ D_j \left[\int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r) - \sum_{i=1}^{l_j} [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) \right] C_j \right\} \right. \\ & \quad \left. + \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) C_j \right\|_{L(X)} \\ & \leq \left\| \sum_{j=1}^k \left\{ D_j \left[\int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r) - \sum_{i=1}^{l_j} [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) \right] C_j \right\} \right\|_{L(X)} \\ & \quad + \left\| \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) C_j \right\|_{L(X)} \\ & \leq \sum_{j=1}^k \left\| \left[\int_{\alpha_{j-1}}^{\alpha_j} d[A(r)]\Phi(r) - \sum_{i=1}^{l_j} [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) \right] \right\|_{L(X)} \\ & \quad + \left\| \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) C_j \right\|_{L(X)} \end{aligned}$$

provided

$$\{\beta_0^j, \sigma_1^j, \beta_1^j, \dots, \beta_{l_j-1}^j, \sigma_{l_j}^j, \beta_{l_j}^j\}$$

is a δ -fine P-partition of the interval $[\alpha_{j-1}, \alpha_j]$, $j = 1, \dots, k$. Hence using (3.5) we obtain by the last inequalities

$$\begin{aligned} & \left\| \sum_{j=1}^k D_j [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] C_j \right\|_{L(X)} \\ & \leq \sum_{j=1}^k \frac{\varepsilon}{k+1} + \left\| \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) C_j \right\|_{L(X)} \\ & < \varepsilon + \left\| \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)]\Phi(\sigma_i^j) C_j \right\|_{L(X)}. \end{aligned}$$

For the second term on the right hand side we have

$$\begin{aligned}
& \left\| \sum_{j=1}^k \sum_{i=1}^{l_j} D_j [A(\beta_i^j) - A(\beta_{i-1}^j)] \Phi(\sigma_i^j) C_j \right\|_{L(X)} \\
& \leq \sum_{j=1}^k \sum_{i=1}^{l_j} \|D_j\|_{L(X)} \|A(\beta_i^j) - A(\beta_{i-1}^j)\|_{L(X)} \|\Phi(\sigma_i^j)\|_{L(X)} \|C_j\|_{L(X)} \\
& \leq K \cdot \sum_{j=1}^k \sum_{i=1}^{l_j} \|A(\beta_i^j) - A(\beta_{i-1}^j)\|_{L(X)} \leq K \cdot \text{var}_{[0,1]}(A).
\end{aligned}$$

Hence

$$\left\| \sum_{j=1}^k D_j [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] C_j \right\|_{L(X)} < \varepsilon + K \cdot \text{var}_{[0,1]}(A)$$

and since $\varepsilon > 0$ can be taken arbitrarily small, we get

$$\left\| \sum_{j=1}^k D_j [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] C_j \right\|_{L(X)} \leq K \cdot \text{var}_{[0,1]}(A)$$

for any partition

$$P: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$$

of the interval $[0, 1]$ and any choice of $C_j, D_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$.

Passing to the suprema over all $C_j, D_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$ and all partitions P of $[0, 1]$ we obtain

$$\sup_P \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] C_j \right\|_{L(X)} \leq K \cdot \text{var}_{[0,1]}(A)$$

and this together with Proposition 3.1 yields the result. \square

3.3. Lemma. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies $A \in BV(L(X))$ and (U).

Then the inverse $[\Phi(t)]^{-1} = \Phi^{-1}(t)$ to the solution $\Phi: [0, 1] \rightarrow L(X)$ of (1.5) exists for every $t \in [0, 1]$ and we have $\Phi^{-1} \in BV(L(X))$.

Proof. By the results given in Lemma 1.3 and 1.4 the inverse Φ^{-1} exists and $\Phi^{-1} \in G(L(X))$. Hence there is a constant $L > 0$ such that

$$\|\Phi^{-1}(t)\|_{L(X)} \leq L$$

for every $t \in [0, 1]$.

It remains to show that $\Phi^{-1} \in BV(L(X))$.

Assume that

$$P: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$$

is an arbitrary partition of the interval $[0, 1]$ and that $C_j, D_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$ are given.

We have

$$\begin{aligned} \left\| \sum_{j=1}^k D_j [\Phi^{-1}(\alpha_j) - \Phi^{-1}(\alpha_{j-1})] C_j \right\| &= \left\| \sum_{j=1}^k D_j \Phi^{-1}(\alpha_j) [I - \Phi(\alpha_j) \Phi^{-1}(\alpha_{j-1})] C_j \right\| \\ &= \left\| \sum_{j=1}^k D_j \Phi^{-1}(\alpha_j) [\Phi(\alpha_{j-1}) - \Phi(\alpha_j)] \Phi^{-1}(\alpha_{j-1}) C_j \right\| \\ &= \left\| \sum_{j=1}^k D_j \Phi^{-1}(\alpha_j) [\Phi(\alpha_j) - \Phi(\alpha_{j-1})] \Phi^{-1}(\alpha_{j-1}) C_j \right\| \\ &\leq L^2 \cdot \operatorname{var}_{[0,1]}(\Phi) \leq L^2 \cdot K \cdot \operatorname{var}_{[0,1]}(A). \end{aligned}$$

Passing to the suprema over all $C_j, D_j \in L(X), j = 1, \dots, k$ with $\|C_j\|_{L(X)} \leq 1, \|D_j\|_{L(X)} \leq 1$ and all partitions P of $[0, 1]$ we obtain

$$\sup_P \sup_{C_j, D_j} \left\| \sum_{j=1}^k D_j [\Phi^{-1}(\alpha_j) - \Phi^{-1}(\alpha_{j-1})] C_j \right\|_{L(X)} \leq L^2 \cdot K \cdot \operatorname{var}_{[0,1]}(A).$$

and this together with Proposition 3.1 yields $\Phi^{-1} \in BV(L(X))$. \square

3.4. Theorem. Assume that $A: [0, 1] \rightarrow L(X)$ satisfies $A \in BV(L(X))$ and (U). Let $\Phi: [0, 1] \rightarrow L(X)$ be the solution of (1.5).

Then for every $t_0 \in [0, 1], \tilde{x} \in X$ and $f \in G(X)$ the formula

$$(2.8) \quad x(t) = \Phi(t) \Phi^{-1}(t_0) \tilde{x} + f(t) - f(t_0) - \Phi(t) \int_{t_0}^t d[\Phi^{-1}(s)] (f(s) - f(t_0)),$$

$t \in [0, 1]$, represents a solution of (2.7).

Proof. By Lemma 3.3 the inverse $\Phi^{-1}: [0, 1] \rightarrow L(X)$ given by Lemma 1.3 belongs to $BV(L(X))$ and therefore we have also $\Phi^{-1} \in (\mathcal{B})BV(L(X))$. All the assumptions of Theorem 2.2 being satisfied we obtain the result by this theorem. \square

3.5 Example. Let us consider the abstract linear differential equation

$$(3.6) \quad \frac{dx}{dt} = a(t)x + \varphi(t)$$

on $[0, 1]$ where $a: [0, 1] \rightarrow L(X)$, $\varphi: [0, 1] \rightarrow X$ and both a and φ are Bochner integrable. For equations of this kind see e.g. [1].

A solution of (3.6) is understood to be a solution of the integral equation

$$(3.7) \quad x(t) = x_0 + \int_d^t a(s)x(s) ds + \int_a^t \varphi(s) ds$$

where $d \in [0, 1]$ and $x_0 = x(d)$.

More generally we can consider the integral equation of the form

$$(3.8) \quad x(t) = \int_d^t a(s)x(s) ds + g(t)$$

with $g \in G(X)$.

Let us set

$$A(t) = \int_d^t a(s) ds \text{ and } f(t) = \int_d^t \varphi(s) ds, \quad t \in [0, 1].$$

Assume that $D: 0 = \alpha_0 < \alpha_1 < \dots < \alpha_{k-1} < \alpha_k = 1$ is an arbitrary partition of $[0, 1]$. Then using the properties of the Bochner integral we get

$$\begin{aligned} \sum_{j=1}^k \|A(\alpha_j) - A(\alpha_{j-1})\| &= \sum_{j=1}^k \left\| \int_{\alpha_{j-1}}^{\alpha_j} a(s) ds \right\| \\ &\leq \sum_{j=1}^k \int_{\alpha_{j-1}}^{\alpha_j} \|a(s)\| ds = \int_0^1 \|a(s)\| ds < \infty \end{aligned}$$

and therefore $A \in BV(L(X))$. Since the function $\|a\|$ is Lebesgue integrable over $[0, 1]$ we have

$$\|A(t) - A(r)\| \leq \left| \int_r^t \|a(s)\| ds \right|$$

for $t, r \in [0, 1]$ and this yields the continuity of A on $[0, 1]$. Hence $\lim_{t \rightarrow r^+} A(t) = A(r)$ for $r \in [0, 1)$ and $\lim_{t \rightarrow r^-} A(t) = A(r)$ for $r \in (0, 1]$ and consequently we have $\Delta^+ A(r) = 0$ for $r \in [0, 1)$ and $\Delta^- A(r) = 0$ for $r \in (0, 1]$ and the function $A: [0, 1] \rightarrow L(X)$ satisfies the condition (U) given in Theorem 1.1. Similarly the function $f: [0, 1] \rightarrow X$ is also continuous and belongs trivially to $G(X)$.

It is a matter of routine to show that if $x \in G(X)$ then the integrals $\int_0^1 d[A(s)]x(s)$ and $\int_0^1 a(s)x(s) ds$ both exist and

$$\int_0^1 d[A(s)]x(s) = \int_0^1 a(s)x(s) ds.$$

Since g is assumed to belong to $G(X)$, every solution of (3.8) also belongs to $G(X)$ and therefore the equation (3.8) is equivalent to

$$x(t) = \int_d^t d[A(s)]x(s) + g(t) = g(d) + \int_d^t d[A(s)]x(s) + g(t) - g(d).$$

Hence by Theorem 2.10 in [9] there exists a unique solution $x: [0, 1] \rightarrow X$, $x \in G(X)$ of (3.8) and by Theorem 3.4 we get after a straightforward calculation

$$\begin{aligned} x(t) &= \Phi(t)\Phi^{-1}(t_0)g(d) + g(t) - g(d) - \Phi(t) \int_d^t d[\Phi^{-1}(s)](g(s) - g(d)) \\ &= g(t) - \Phi(t) \int_d^t d[\Phi^{-1}(s)]g(s) \end{aligned}$$

where the function $\Phi: [0, 1] \rightarrow L(X)$ is a solution of (1.5) with A given by $A(t) = \int_d^t a(s) ds$ for $t \in [0, 1]$.

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Author's address: Štefan Schwabik, Mathematical Institute, Academy of Sciences of the Czech Republic, Žitná 25, 115 67 Praha 1, Czech Republic, e-mail: schwabik@math.cas.cz.