# AN APPROXIMATION OF THE PRESSURE FOR THE TWO-DIMENSIONAL ISING MODEL

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A sequence of pressure functions corresponding to some one-dimensional models is used to approximate the pressure function of the two-dimensional Ising model. The rate of convergence is derived and the method is demonstrated with a numerical study.

## 1. INTRODUCTION

The two-dimensional Ising model is the simpliest non-trivial Gibbs random field. Namely, a probability measure  $\mu$  on the space  $\{0,1\}^{\mathbb{Z}^2}$  is called to agree with the Ising model if its one-dimensional conditional distributions satisfy the "nearest-neighbor" property and can be expressed in the following way

$$
\mu\left(x_t \,|\, x_{Z^2 \setminus \{t\}}\right) = \mu\left(x_t \,|\, x_{\partial t}\right) = \Pi_t\left(x_t \,|\, x_{Z^2 \setminus \{t\}}\right)
$$

for every  $t \in \mathbb{Z}^d$  and a.e.  $x \in \{0,1\}^T[\mu]$ , where

$$
\Pi_t \left( x_t \, | \, x_{Z^2 \setminus \{t\}} \right) = \frac{\exp \left\{ -x_t \left( h + J_1 \left( x_{t+u} + x_{t-u} \right) + J_2 \left( x_{t+v} + x_{t-v} \right) \right) \right\}}{1 + \exp \left\{ -h - J_1 \left( x_{t+u} + x_{t-u} \right) - J_2 \left( x_{t+v} + x_{t-v} \right) \right\}}
$$

are called the local characteristics,

$$
\partial t = \left\{ s \in \mathbb{Z}^2; \ \|t - s\| = 1 \right\} = \left\{ u, -u, v, -v \right\}, \qquad u = (1, 0), \ v = (0, 1),
$$

and  $h, J_1, J_2$  are arbitrary constants.

In general, the system  $\{\Pi_t(\cdot|\cdot)\}_{t\in Z^2}$  depending on the triplet  $(h,J_1,J_2)$  does not determine the probability measure  $\mu$  uniquely. The existence, uniqueness, and other properties of the Ising model are closely related to the function called the pressure and defined by the limit

$$
\lim_{V \nearrow Z^2} |V|^{-1} \log \sum_{x_V \in \{0,1\}^V} \exp \left\{-h \sum_{t \in V} x_t - J_1 \sum_{t \in V \cap (V-u)} x_t x_{t+u} - J_2 \sum_{t \in V \cap (V-v)} x_t x_{t+v}\right\} =
$$
\n
$$
= p(h, J_1, J_2)
$$

where  $V \nearrow Z^2$  means the expansion ensuring  $|V|^{-1}|V \cap (V - t)| \longrightarrow 1$  for every  $t \in Z^2$ . (By |V| we denote the cardinality.)

But, with the exception of the famous Onsager's result (cf. [3]), concerning a special case of the problem, no direct way of calculating the pressure  $p$  is known. Therefore various approximative methods, using mostly some kind of expansion, are applied. Here, we propose a new approximative method based on an approximation of the pressure of the two-dimensional model by the pressure of some properly chosen one-dimensional models, for which the transfer matrix method is available (cf. [2]).

As will be seen later, the method works quite well in the "high temperature" area (i.e. for "small" parameters  $h, J_1, J_2$ ) and even in the neighborhood of the critical point it seems to give satisfactory results.

## 2. BASIC LEMMA

For a fixed positive integer R and a real  $\gamma$  let us consider the two-dimensional model with the state space  $\overline{X} = \{0,1\}^R$  and the "nearest-neighbor" local characteristics given by

$$
\overline{\Pi}_{t}^{\gamma} \left( \overline{x}_{t} \, | \, \overline{x}_{Z^{2} \setminus \{t\}} \right) = \frac{\exp \left\{ -U_{\gamma}^{0}(\overline{x}_{t}) - \sum_{s \in \partial t} U_{\gamma}^{s}(\overline{x}_{t}, \overline{x}_{t+s} \right\}}{\sum\limits_{\overline{y}_{t} \in \overline{X}} \exp \left\{ -U_{\gamma}^{0}(\overline{y}_{t}) - \sum_{s \in \partial t} U_{\gamma}^{s}(\overline{y}_{t}, \overline{x}_{t+s}) \right\}}
$$

for every  $\overline{x}_t \in \overline{X}$ ,  $\overline{x}_{\partial t} \in \overline{X}^{\partial t}$ , where

$$
U_{\gamma}^{0}(\overline{x}) = h \cdot \sum_{i=1}^{R} \overline{x}^{i} + J_{1} \sum_{i=1}^{R-1} \overline{x}^{i} \overline{x}^{i+1},
$$
  
\n
$$
U_{\gamma}^{u}(\overline{x}, \overline{y}) = \gamma \cdot J_{1} \cdot \overline{x}^{R} \overline{y}^{1}, \qquad U^{-u}(\overline{x}, \overline{y}) = U^{u}(\overline{y}, \overline{x}),
$$
  
\n
$$
U_{\gamma}^{v}(\overline{x}, \overline{z}) = J_{2} \cdot \sum_{i=1}^{R} \overline{x}^{i} \overline{z}^{i} + (1 - \gamma) J_{1} \overline{x}^{R} \overline{z}^{1}, \qquad U^{-v}(\overline{x}, \overline{z}) = U^{v}(\overline{z}, \overline{x}),
$$

for every  $\overline{x}, \overline{y}, \overline{z} \in \overline{X}$ .

Let us denote by  $G_I(\gamma)$  the set of translation invariant probability distributions on  $\overline{X}^{\omega}$  with the one-dimensional conditional distributions equal a.s. to the local Z 2 on X with the o<br>characteristics  $\left\{\overline{\Pi}^{\gamma}_t\right\}$  $t\bigg\}_{t\in Z^2}.$ 

Finally, we denote by

$$
\overline{p}_{\gamma}(h, J_1, J_2) = \lim_{V \nearrow Z^2} |V|^{-1} \log \sum_{\overline{x}_V \in \overline{X}^V} \exp \left\{ -\sum_{t \in V} U_{\gamma}^0(\overline{x}_t) - \sum_{t \in V \cap (V - u)} U_{\gamma}^u(\overline{x}_t, \overline{x}_{t+u}) - \sum_{t \in V \cap (V - v)} U_{\gamma}^v(\overline{x}_t, \overline{x}_{t+v}) \right\}
$$

the pressure corresponding to above defined model.

**Lemma.** Let  $\gamma^* \in [0, 1]$  be the point at which the function

$$
F(\gamma) = \gamma \overline{p}_1(h, J_1, J_2) + (1 - \gamma) \overline{p}_0(h, J_1, J_2) - \overline{p}_\gamma(h, J_1, J_2)
$$

assumes its maximum. Then there exists

$$
\mu^* \in G_I(\gamma^*)
$$

such that

$$
\overline{p}_1(h, J_1, J_2) - \overline{p}_0(h, J_1, J_2) = J_1 \left[ \mu^* \left( \overline{x}_0^R \cdot \overline{x}_u^1 = 1 \right) - \mu^* \left( \overline{x}_0^R \cdot \overline{x}_v^1 = 1 \right) \right]
$$

holds.

Proof. The statement follows immediately from the equivalence between translation invariant Gibbs states and tangent functionals to the convex functional p (cf. [4], Thm. 8.3) and the general subdifferential calculus (cf. e. g. [5], Sec. 5).

# 3. MAIN RESULT

Now, let us make clear what was the aim of introducing the models with the "aggregated" state space  $\overline{X}$  in the preceding section.

Directly from the definitions it is easy to see that

$$
\overline{p}_1(h, J_1, J_2) = R \cdot p(h, J_1, J_2)
$$

holds for every triplet  $(h, J_1, J_2)$ .

Since for  $\gamma = 0$  there is no horizontal interaction, i.e. the model consists of mutually independent columns, we may view the model as a one-dimensional one. And, considering all  $\overline{x}_t$ ,  $t \in Z$  as the corresponding segments of a sequence  $x_Z =$  ${x_s}_{s \in Z} \in \{0,1\}^Z$  (we put  $x_s = \overline{x}_t^i$  for  $s = t \cdot R + i$ ), we conclude that

$$
\bar{p}_0(h, J_1, J_2) = R \cdot p^R(h, J_1, J_2),
$$

where

$$
p^{R}(h, J_1, J_2) =
$$
  
=  $\lim_{n \to \infty} |2n + 1|^{-1} \log \sum_{x_{[-n,n]} \in \{0,1\}^{[-n,n]}} \exp \left\{-h \sum_{j=-n}^{n} x_j - J_1 \sum_{i=-n}^{n-1} x_j x_{j+1} - J_2 \sum_{i=-n}^{n-R} x_j x_{j+R}\right\}$ 

is the pressure of the one-dimensional model with the state space  $\{0, 1\}$  and the local characteristics

$$
\Pi_t^0(x_t | x_{Z \setminus \{t\}}) = \frac{\exp \{-h x_t - J_1 x_t (x_{t+1} + x_{t-1}) - J_2 (x_{t-R} + y_{t+R})\}}{1 + \exp \{-h - J_1 (x_{t+1} + x_{t-1}) - J_2 (x_{t-R} + x_{t+R})\}},
$$

for every  $t \in Z$ ,  $x_t \in \{0,1\}$ ,  $x_{Z \setminus \{t\}} \in \{0,1\}^{Z \setminus \{t\}}$ .

Now, we may formulate the main result on the approximation.

**Theorem.** For every triplet  $(h, J_1, J_2)$  it holds

$$
\left| p\left( h, J_1, J_2 \right) - p^R\left( h, J_1, J_2 \right) \right| \leq (2R)^{-1} |J_1|,
$$

and therefore

$$
p(h, J_1, J_2) = \lim_{R \to \infty} p^R(h, J_1, J_2).
$$

Proof. The statement follows from Lemma and the considerations above if we realize that the probability measures

$$
\nu_u(x, y) = \mu^* \left( \overline{x}_0^R = x, \ \overline{x}_u^1 = y \right), \qquad x, y \in \{0, 1\},\
$$

and

$$
\nu_v(x, y) = \mu^* \left( \overline{x}_0^R = x, \ \overline{x}_v^1 = y \right), \qquad x, \ y \in \{0, 1\}
$$

have the same marginals, and therefore

$$
|\nu_u(1,1)-\nu_v(1,1)| \leq \frac{1}{2}.
$$

 $\Box$ 

Remark. The values of  $p<sup>R</sup>$  may be calculated with the aid of the transfer matrix (for details see e.g. [2], Section I.2.1). Of course, actually we are able to calculate  $p<sup>R</sup>$ for rather small R only. But the convergence is, in fact, quite fast, and even  $R = 6$ or  $R = 7$ , especially in high temperature area (i.e. for rather small interactions), give nice results.

## 4. NUMERICAL STUDY

Now, we try to demonstrate the method with a particular case which has been chosen in order to make possible a comparison of the obtained results with the rigorous Onsager's one.

Therefore, let  $J_1 = J_2 = J \geq 0$  and  $h = -2J$ .

For  $R = 4, 5, 6, 7$  and some  $J \in [0, 2]$  the values of  $p^R(-2J, J, J)$  obtained by the transfer matrix method (cf. [2], Section I.2.1) are given in the table.



Here, for the critical point  $J_c = 2 \log(1 + \sqrt{2})$ ¢ the exact Onsager's solution gives

$$
p(-2J_c, J_c, J_c) = \log\left(1 + \sqrt{2}\right) + \log 2/2 + 2\cdot G/\pi \doteq 1.8110692
$$

 $(G = 0.915965594$  is the Catalan's constant).

Trying to make differences between the functions  $p<sup>R</sup>$  for various R's more evident, we deal with their deviations

$$
q^{R}(J) = p^{R}(-2J, J, J) - \log 2 - J/2
$$

from the line  $log 2 + J/2$  (i.e. their common tangent in  $J = 0$ ) in the following figure.

Similarly, we denote  $q(J_c) = p(-2J_c, J_c, J_c) - \log 2 - J_c/2 = 0.2365$ .

# 5. CONCLUDING REMARK

Approximation of the described type was at first derived in [1] for purpose of application in mathematical statistics. But here a completely different proof is used, which yields a stronger result and deeper insight into the problem.

R E F E R E N C E S

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