AN APPROXIMATION OF THE PRESSURE FOR THE TWO-DIMENSIONAL ISING MODEL

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A sequence of pressure functions corresponding to some one-dimensional models is used to approximate the pressure function of the two-dimensional Ising model. The rate of convergence is derived and the method is demonstrated with a numerical study.

1. INTRODUCTION

The two-dimensional Ising model is the simpliest non-trivial Gibbs random field. Namely, a probability measure μ on the space $\{0,1\}^{Z^2}$ is called to agree with the Ising model if its one-dimensional conditional distributions satisfy the "nearest-neighbor" property and can be expressed in the following way

$$\mu\left(x_t \,|\, x_{Z^2 \setminus \{t\}}\right) = \mu\left(x_t \,|\, x_{\partial t}\right) = \Pi_t\left(x_t \,|\, x_{Z^2 \setminus \{t\}}\right)$$

for every $t \in Z^d$ and a.e. $x \in \{0,1\}^T[\mu]$, where

$$\Pi_t \left(x_t \,|\, x_{Z^2 \setminus \{t\}} \right) = \frac{\exp\left\{ -x_t \left(h + J_1 \left(x_{t+u} + x_{t-u} \right) + J_2 \left(x_{t+v} + x_{t-v} \right) \right) \right\}}{1 + \exp\left\{ -h - J_1 \left(x_{t+u} + x_{t-u} \right) - J_2 \left(x_{t+v} + x_{t-v} \right) \right\}}$$

are called the local characteristics,

$$\partial t = \left\{ s \in Z^2; \|t - s\| = 1 \right\} = \left\{ u, -u, v, -v \right\}, \qquad u = (1, 0), \ v = (0, 1),$$

and h, J_1, J_2 are arbitrary constants.

In general, the system $\{\Pi_t(\cdot|\cdot)\}_{t\in\mathbb{Z}^2}$ depending on the triplet (h, J_1, J_2) does not determine the probability measure μ uniquely. The existence, uniqueness, and other properties of the Ising model are closely related to the function called the pressure and defined by the limit

$$\lim_{V \nearrow Z^2} |V|^{-1} \log \sum_{x_V \in \{0,1\}^V} \exp\left\{-h \sum_{t \in V} x_t - J_1 \sum_{t \in V \cap (V-u)} x_t x_{t+u} - J_2 \sum_{t \in V \cap (V-v)} x_t x_{t+v}\right\} = p(h, J_1, J_2)$$

where $V \nearrow Z^2$ means the expansion ensuring $|V|^{-1} |V \cap (V-t)| \longrightarrow 1$ for every $t \in Z^2$. (By |V| we denote the cardinality.)

But, with the exception of the famous Onsager's result (cf. [3]), concerning a special case of the problem, no direct way of calculating the pressure p is known. Therefore various approximative methods, using mostly some kind of expansion, are applied. Here, we propose a new approximative method based on an approximation of the pressure of the two-dimensional model by the pressure of some properly chosen one-dimensional models, for which the transfer matrix method is available (cf. [2]).

As will be seen later, the method works quite well in the "high temperature" area (i.e. for "small" parameters h, J_1 , J_2) and even in the neighborhood of the critical point it seems to give satisfactory results.

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2. BASIC LEMMA

For a fixed positive integer R and a real γ let us consider the two-dimensional model with the state space $\overline{X} = \{0, 1\}^R$ and the "nearest-neighbor" local characteristics given by

$$\overline{\Pi}_{t}^{\gamma}\left(\overline{x}_{t} \,|\, \overline{x}_{Z^{2} \setminus \{t\}}\right) = \frac{\exp\left\{-U_{\gamma}^{0}(\overline{x}_{t}) - \sum_{s \in \partial t} U_{\gamma}^{s}(\overline{x}_{t}, \overline{x}_{t+s}\right\}}{\sum_{\overline{y}_{t} \in \overline{X}} \exp\left\{-U_{\gamma}^{0}(\overline{y}_{t}) - \sum_{s \in \partial t} U_{\gamma}^{s}(\overline{y}_{t}, \overline{x}_{t+s})\right\}}$$

for every $\overline{x}_t \in \overline{X}, \ \overline{x}_{\partial t} \in \overline{X}^{\partial t}$, where

$$U^{0}_{\gamma}(\overline{x}) = h \cdot \sum_{i=1}^{R} \overline{x}^{i} + J_{1} \sum_{i=1}^{R-1} \overline{x}^{i} \overline{x}^{i+1},$$

$$U^{u}_{\gamma}(\overline{x}, \overline{y}) = \gamma \cdot J_{1} \cdot \overline{x}^{R} \overline{y}^{1}, \qquad U^{-u}(\overline{x}, \overline{y}) = U^{u}(\overline{y}, \overline{x}),$$

$$U^{v}_{\gamma}(\overline{x}, \overline{z}) = J_{2} \cdot \sum_{i=1}^{R} \overline{x}^{i} \overline{z}^{i} + (1 - \gamma) J_{1} \overline{x}^{R} \overline{z}^{1}, \qquad U^{-v}(\overline{x}, \overline{z}) = U^{v}(\overline{z}, \overline{x}),$$

for every $\overline{x}, \overline{y}, \overline{z} \in \overline{X}$. Let us denote by $G_I(\gamma)$ the set of translation invariant probability distributions on \overline{X}^{Z^2} with the one-dimensional conditional distributions equal a.s. to the local characteristics $\left\{\overline{\Pi}_t^{\gamma}\right\}_{t\in Z^2}$. Finally, we denote by

$$\overline{p}_{\gamma}(h, J_1, J_2) = \\ = \lim_{V \nearrow \mathbb{Z}^2} |V|^{-1} \log \sum_{\overline{x}_V \in \overline{X}^V} \exp \Biggl\{ -\sum_{t \in V} U^0_{\gamma}(\overline{x}_t) - \sum_{t \in V \cap (V-u)} U^u_{\gamma}(\overline{x}_t, \overline{x}_{t+u}) - \sum_{t \in V \cap (V-v)} U^v_{\gamma}(\overline{x}_t, \overline{x}_{t+v}) \Biggr\}$$

the pressure corresponding to above defined model.

Lemma. Let $\gamma^* \in [0,1]$ be the point at which the function

$$F(\gamma) = \gamma \overline{p}_1 \left(h, J_1, J_2 \right) + (1 - \gamma) \overline{p}_0 \left(h, J_1, J_2 \right) - \overline{p}_\gamma \left(h, J_1, J_2 \right)$$

assumes its maximum. Then there exists

$$\mu^* \in G_I(\gamma^*)$$

such that

$$\overline{p}_1\left(h, J_1, J_2\right) - \overline{p}_0\left(h, J_1, J_2\right) = J_1\left[\mu^*\left(\overline{x}_0^R \cdot \overline{x}_u^1 = 1\right) - \mu^*\left(\overline{x}_0^R \cdot \overline{x}_v^1 = 1\right)\right]$$

holds.

Proof. The statement follows immediately from the equivalence between translation invariant Gibbs states and tangent functionals to the convex functional p (cf. [4], Thm. 8.3) and the general subdifferential calculus (cf. e.g. [5], Sec. 5).

3. MAIN RESULT

Now, let us make clear what was the aim of introducing the models with the "aggregated" state space \overline{X} in the preceding section.

Directly from the definitions it is easy to see that

$$\overline{p}_1(h, J_1, J_2) = R \cdot p(h, J_1, J_2)$$

holds for every triplet (h, J_1, J_2) .

Since for $\gamma = 0$ there is no horizontal interaction, i.e. the model consists of mutually independent columns, we may view the model as a one-dimensional one. And, considering all \overline{x}_t , $t \in Z$ as the corresponding segments of a sequence $x_Z = \{x_s\}_{s\in Z} \in \{0,1\}^Z$ (we put $x_s = \overline{x}_t^i$ for $s = t \cdot R + i$), we conclude that

$$\overline{p}_0(h, J_1, J_2) = R \cdot p^R(h, J_1, J_2),$$

where

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$$p^{R}(h, J_{1}, J_{2}) = \\ = \lim_{n \to \infty} |2n+1|^{-1} \log \sum_{x_{[-n,n]} \in \{0,1\}^{[-n,n]}} \exp\left\{-h \sum_{j=-n}^{n} x_{j} - J_{1} \sum_{i=-n}^{n-1} x_{j} x_{j+1} - J_{2} \sum_{i=-n}^{n-R} x_{j} x_{j+R}\right\}$$

is the pressure of the one-dimensional model with the state space $\{0,1\}$ and the local characteristics

$$\Pi_t^0\left(x_t \,|\, x_{Z \setminus \{t\}}\right) = \frac{\exp\left\{-h \,x_t - J_1 x_t \left(x_{t+1} + x_{t-1}\right) - J_2 \left(x_{t-R} + y_{t+R}\right)\right\}}{1 + \exp\left\{-h - J_1 \left(x_{t+1} + x_{t-1}\right) - J_2 \left(x_{t-R} + x_{t+R}\right)\right\}},$$

for every $t \in Z$, $x_t \in \{0,1\}$, $x_{Z \setminus \{t\}} \in \{0,1\}^{Z \setminus \{t\}}$.

Now, we may formulate the main result on the approximation.

Theorem. For every triplet (h, J_1, J_2) it holds

$$|p(h, J_1, J_2) - p^R(h, J_1, J_2)| \le (2R)^{-1} |J_1|,$$

and therefore

$$p(h, J_1, J_2) = \lim_{R \to \infty} p^R(h, J_1, J_2)$$

Proof. The statement follows from Lemma and the considerations above if we realize that the probability measures

$$\nu_u(x,y) = \mu^* \left(\overline{x}_0^R = x, \ \overline{x}_u^1 = y \right), \qquad x, \ y \in \{0,1\},$$

and

$$\nu_v(x,y) = \mu^* \left(\overline{x}_0^R = x, \ \overline{x}_v^1 = y \right), \qquad x, \ y \in \{0,1\}$$

have the same marginals, and therefore

$$|\nu_u(1,1) - \nu_v(1,1)| \le \frac{1}{2}.$$

Remark. The values of p^R may be calculated with the aid of the transfer matrix (for details see e. g. [2], Section I.2.1). Of course, actually we are able to calculate p^R for rather small R only. But the convergence is, in fact, quite fast, and even R = 6 or R = 7, especially in high temperature area (i. e. for rather small interactions), give nice results.

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4. NUMERICAL STUDY

Now, we try to demonstrate the method with a particular case which has been chosen in order to make possible a comparison of the obtained results with the rigorous Onsager's one.

Therefore, let $J_1 = J_2 = J \ge 0$ and h = -2J.

For R = 4, 5, 6, 7 and some $J \in [0, 2]$ the values of $p^R(-2J, J, J)$ obtained by the transfer matrix method (cf. [2], Section I.2.1) are given in the table.

	J = 0	J = 0.5	J = 1.0	J = 1.5	$J = 2 \cdot \log(1 + \sqrt{2})$	J = 2
R = 4	0.6931	0.9589	1.2579	1.5916	1.7800	1.9568
R = 5	0.6931	0.9590	1.2595	1.6085	1.8213	2.0320
R = 6	0.6931	0.9590	1.2590	1.5999	1.7968	1.9841
R = 7	0.6931	0.9590	1.2591	1.6051	1.8158	2.0297

Here, for the critical point $J_c = 2 \log (1 + \sqrt{2})$ the exact Onsager's solution gives

$$p(-2J_c, J_c, J_c) = \log(1 + \sqrt{2}) + \log 2/2 + 2 \cdot G/\pi \doteq 1.8110692$$

(G = 0.915965594 is the Catalan's constant).

Trying to make differences between the functions p^R for various R's more evident, we deal with their deviations

$$q^{R}(J) = p^{R}(-2J, J, J) - \log 2 - J/2$$

from the line $\log 2 + J/2$ (i.e. their common tangent in J = 0) in the following figure.

Similarly, we denote $q(J_c) = p(-2J_c, J_c, J_c) - \log 2 - J_c/2 \doteq 0.2365$.

5. CONCLUDING REMARK

Approximation of the described type was at first derived in [1] for purpose of application in mathematical statistics. But here a completely different proof is used, which yields a stronger result and deeper insight into the problem.

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