

# Resting state network detection by graph partitioning using the Average Association criterion



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## Resting state networks

Resting state networks (RSNs) can be rather loosely defined as regions exhibiting higher-than-average functional connectivity (FC) in the resting state. We propose a clustering approach to detect the functional structure of the human brain from measurements of spontaneous fluctuations using fMRI in single subjects.

## The brain graph

- ▶ An undirected graph representing the functional connectivity in the brain is constructed.
  - ▷ vertices represent the voxels of the brain
  - ▷ edges between the vertices are weighted by the functional connectivity between the voxels
  - ▷ the sparsity depends on the connectivity but in general the graph is dense

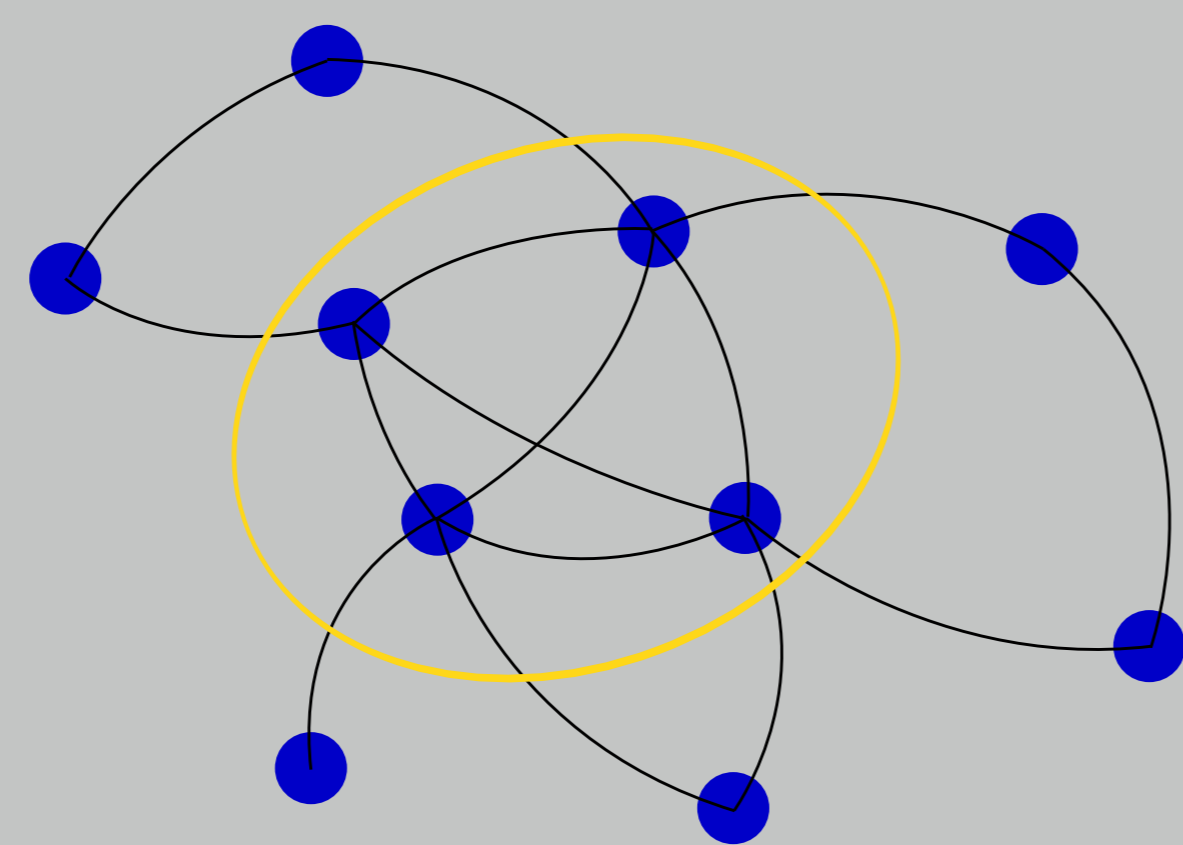


Figure: A schematic of the "brain graph". Circled region has a higher density of edges than other regions.

- ▶ Resting State Networks will correspond to sets of vertices in the graph which have a high density of strong edges among themselves.

## Average Association

- ▶ Let a graph have vertices  $p_i \in V$ ,  $|V| = N$ . Let the weight of the edge between vertices  $p_i$  and  $p_j$  be  $w_{i,j}$  for all pairs  $\{p_i, p_j\} \in V \times V$ .
- ▶ The graph is to be split into  $K$  clusters  $V_k$ ,  $|V_k| = N_k$  and a residual set  $V_o$ , which will contain all the voxels that don't have a strong association with any cluster. The clusters  $V_k$  and the residual set  $V_o$  together form a partition of the set of vertices  $V$ .
- ▶ The **Average Association (AA)** objective [2] is defined as

$$J_K = \sum_{k=1}^K \sum_{p_i, p_j \in V_k} \frac{w_{i,j}}{N_k} \quad (1)$$

- ▶ The objective  $J_K$  is equal to the sum of all edges inside each cluster  $V_k$  divided by the number of its vertices.
- ▶  $J_K$  must be optimized over all possible partitionings  $\{V_1, V_2, \dots, V_K, V_o\}$ .
- ▶ The clustering is crisp, a voxel either belongs to a cluster or it does not.
- ▶ **Note** in general not all voxels are assigned to clusters, some may be in the residual set  $V_o$ . The residual set may also be empty, the method is unconstrained in this respect.

## AA problem in matrix form

- ▶ The objective (1) is hard to optimize directly.
- ▶ A standard approach to solving the problem is a relaxation approach - we must reformulate the problem in matrix form.
- ▶ In matrix notation
  - ▷  $W = [w_{i,j}]_{N \times N}$  is the connectivity matrix
  - ▷ cluster memberships given by indicator vectors  $\mathbf{u}_k = \begin{cases} 1 & \text{if } p_i \in V_k \\ 0 & \text{otherwise} \end{cases}$
  - ▷ Since clusters are disjoint,  $\mathbf{u}_i^T \mathbf{u}_j = 0$  if  $i \neq j$
  - ▷ Gather indicator vectors into matrix  $U = (\mathbf{u}_1, \mathbf{u}_2, \dots, \mathbf{u}_K)$ ,  $U \in \mathbb{R}^{N \times K}$
  - ▷ The AA objective (1) becomes

$$J_K = \text{tr}\{(U^T U)^{-1} U^T W U\}$$

- ▷ Substituting  $Z = U(U^T U)^{-\frac{1}{2}}$  the optimization problem becomes

$$\max_{Z^T Z = I} Z^T W Z, \quad \mathbf{z}_k = \begin{cases} \frac{1}{\sqrt{N_k}} & \text{if } p_i \in V_k \\ 0 & \text{otherwise,} \end{cases} \quad (2)$$

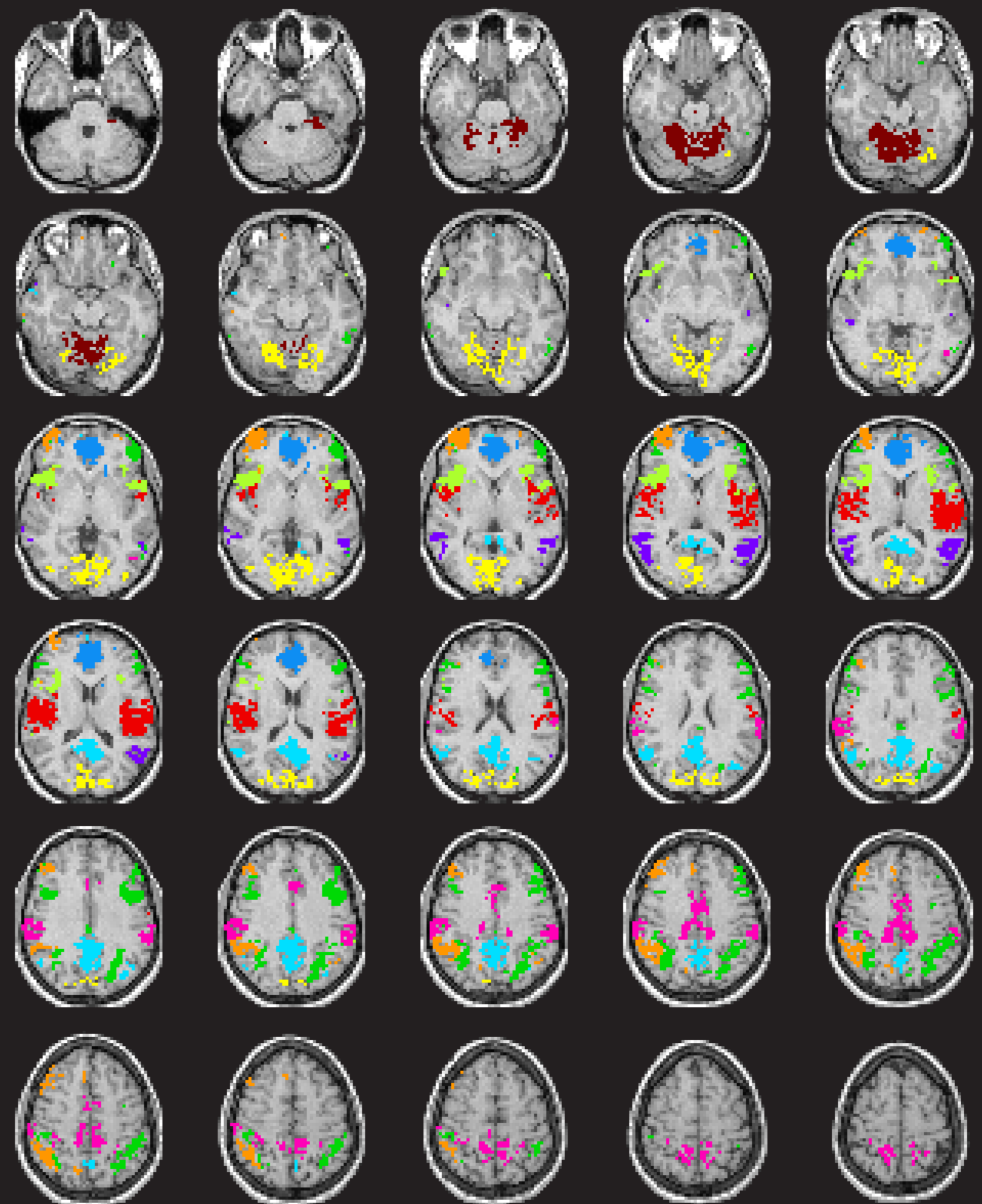
where  $\mathbf{z}_k$  is the  $k$ -th column vector of  $Z$ .

## Solving the AA problem

- ▶ Relaxation: drop the requirements on the discrete form of  $\mathbf{z}_k$  in (2).
- ▶ The relaxed solution  $Z \in \mathbb{R}^{N \times K}$  is given in terms of eigenvectors of  $W$
- ▶ The relaxed solution is not unique (for Normalized Cut see [3]). The space of relaxed solutions is parametrized by orthogonal transformations.
- ▶ This opens up the possibility of searching for better relaxed solutions.
- ▶ We have applied a classical procedure: the VARIMAX rotation [1].
- ▶ VARIMAX seeks an orthogonal  $R_V \in \mathbb{R}^{K \times K}$  such that column vectors of the the matrix  $Z_V = Z R_V$  have **simple structure**.
- ▶ Simple structure of an indicator vector implies a compact localization of each cluster  $V_k$  on the set of voxels  $V$ .
- ▶ Elements are assigned to the cluster where their loading is highest and the indicator vectors  $[\mathbf{z}_V]_k$  are individually thresholded to obtain the final cluster memberships. Any remaining elements are gathered into the residual set.

## Results

Selected clusters (out of 20) merged voxel-wise by majority vote from 6 subjects (except DAN: 2/5, Motor: 3/6 votes), 3600 ± 1200 voxels in the residual set. Measurement: 1.5T MRI, TR=2s, 10 min sessions, 27644 voxels 3mm<sup>3</sup>. Preprocessing: co-registration to Talairach atlas, spatial smoothing 6mm FWHM Gaussian, 0.009 – 0.08Hz BP, orthogonalization w.r.t. head motion, {CSF, WM, whole-brain} signals. Analysis: AA clustering with FC estimated using correlation coefficients. Only positive CCs significant at  $p < 0.004$  (uncorrected) were included.



**CEREBELLUM**  
**SALIENCE NETWORK**  
**VISUAL NETWORK**  
**LANGUAGE NETWORK**

**AUDITORY NETWORK**  
**DEFAULT MODE N. ACC**  
**DORSAL ATT. NETWORK**  
**MOTOR NETWORK**

## References and Acknowledgments

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