

# Scaling and singular limits in fluid mechanics

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# Recommended literature

- R. Klein: Scale-dependent models for atmospheric flows. *In Annual review of fluid mechanics* **42**, pages 249-274, 2012
- S. Klainerman and A. Majda: *Singular limits of quasilinear hyperbolic systems with large parameters and the incompressible limit of compressible fluids.* Comm. Pure Appl. Math. **34**: 481-524, 1981.
- N. Masmoudi: Examples of singular limits in hydrodynamics. *In Handbook of Differential Equations, III, C. Dafermos, E. Feireisl Eds., Elsevier, Amsterdam, 2006*
- E. F. and A. Novotný: Singular limits in thermodynamics of viscous fluids. *Birkhäuser-Verlag, Basel, 2009*

# Balance laws

## General balance law

$$\partial_t d + \operatorname{div}_x(\mathbf{F}) = S, \quad d \text{ density, } \mathbf{F} \text{ flux, } S \text{ source (sink)}$$

## Equation of continuity

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0, \quad \varrho \text{ mass density, } \mathbf{u} \text{ velocity field}$$

## Balance law - Eulerian form

$$\partial_t(\varrho s) + \underbrace{\operatorname{div}_x(\varrho s \mathbf{u})}_{\text{convective flux}} + \underbrace{\operatorname{div}_x \mathbf{q}}_{\text{diffusive flux}} = S$$

## Material derivative

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) \equiv \varrho \left[ \partial_t s + \mathbf{u} \cdot \nabla_x s \right] \equiv \varrho \frac{d}{dt} s(t, \mathbf{X}(t, x))$$

$$\frac{d}{dt} \mathbf{X} = \mathbf{u}(t, \mathbf{X})$$

# Characteristic values and scaling

## Geometry

$$t \rightarrow \frac{t}{T_{\text{char}}}, \quad x \rightarrow \frac{x}{L_{\text{char}}}, \quad \mathbf{u} \rightarrow \frac{\mathbf{u}}{U_{\text{char}}}$$

$$\partial_t \rightarrow \frac{1}{T_{\text{char}}} \partial_t, \quad \partial_x \rightarrow \frac{x}{L_{\text{char}}} \partial_x$$

## Re-scaled (dimensionless) balance law

$$\begin{aligned} & \left[ \frac{L_{\text{char}}}{T_{\text{char}} U_{\text{char}}} \right] \partial_t (\varrho s) + \operatorname{div}_x (\varrho s \mathbf{u}) + \frac{q_{\text{char}}}{\varrho_{\text{char}} s_{\text{char}} U_{\text{char}}} \operatorname{div}_x \mathbf{q} \\ &= \frac{S_{\text{char}}}{\varrho_{\text{char}} s_{\text{char}} U_{\text{char}} L_{\text{char}}} S \end{aligned}$$

## Strouhal number

$$[\text{Sr}] \equiv \frac{L_{\text{char}}}{T_{\text{char}} U_{\text{char}}}$$

# Compressible viscous rotating fluids

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \underbrace{\varrho \mathbf{f} \times \mathbf{u}}_{\text{Coriolis force}} + \nabla_x p(\varrho) = \operatorname{div}_x \mathbb{S} + \varrho \nabla_x G$$

## Newton's rheological law - viscous stress

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}$$

## Geo-potential

$$G = \underbrace{g}_{\text{gravity}} + \underbrace{\frac{1}{2} |\mathbf{f} \times \mathbf{x}|^2}_{\text{centrifugal force}}$$

# Scaled system

## Field equations

$$[\text{Sr}] \partial_t \varrho + \operatorname{div}_x (\varrho \mathbf{u}) = 0$$

$$\begin{aligned} [\text{Sr}] \partial_t (\varrho \mathbf{u}) + \operatorname{div}_x (\varrho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{[\text{Ro}]} \varrho \mathbf{f} \times \mathbf{u} + \frac{1}{[\text{Ma}]^2} \nabla_x p(\varrho) \\ = \frac{1}{[\text{Re}]} \operatorname{div}_x \mathbb{S} + \frac{1}{[\text{Fr}]^2} \varrho \nabla_x G \end{aligned}$$

## Characteristic numbers

Rossby number .....	$\text{Ro} = \frac{U_{\text{char}}}{L_{\text{char}} f_{\text{char}}}$
Mach number .....	$\text{Ma} = \frac{U_{\text{char}}}{\sqrt{\rho_{\text{char}} / \varrho_{\text{char}}}}$
Reynolds number .....	$\text{Re} = \frac{\varrho_{\text{char}} L_{\text{char}} U_{\text{char}}}{\mu_{\text{char}}}$
Froude number I .....	$\text{Fr}_{\text{I}} = \frac{U_{\text{char}}}{\sqrt{g_{\text{char}}}}$
Froude number II .....	$\text{Fr}_{\text{II}} = \frac{U_{\text{char}}}{L_{\text{char}} f_{\text{char}}}$

# Incompressible limit

## Primitive system

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \boxed{\frac{1}{\varepsilon^2} \nabla_x p(\varrho)} = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

## Formal singular limit - target problem

$$\nabla_x p(\varrho) = 0 \Rightarrow \varrho = \varrho_{\text{char}} \equiv \bar{\varrho} \Rightarrow \operatorname{div}_x \mathbf{u} = 0$$

$$\bar{\varrho} [\partial_t \mathbf{u} + \operatorname{div}_x(\mathbf{u} \otimes \mathbf{u})] + \nabla_x \Pi = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u}) = \operatorname{div}_x [\mu (\nabla_x \mathbf{u} + \nabla_x^t \mathbf{u})]$$

## Stability condition

$$p'(\varrho) > 0 \text{ for all } \varrho > 0$$

# Fast rotation

Primitive system - incompressible Navier-Stokes equations

$$\operatorname{div}_x \mathbf{u} = 0$$

$$\partial_t \mathbf{u} + \operatorname{div}_x (\mathbf{u} \otimes \mathbf{u}) + \left[ \frac{1}{\varepsilon} \mathbf{f} \times \mathbf{u} + \nabla_x \Pi \right] = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

Target problem

$$\mathbf{f} = [0, 0, 1] \Rightarrow \mathbf{f} \times \mathbf{u} \equiv \begin{pmatrix} -u_2 \\ u_1 \\ 0 \end{pmatrix} = \nabla_x \Psi \Rightarrow \mathbf{u} = [\mathbf{u}_h(x_1, x_2), 0]$$

$$\operatorname{div}_x \mathbf{u}_h = 0$$

$$\partial_t \mathbf{u}_h + \operatorname{div}_x (\mathbf{u}_h \otimes \mathbf{u}_h) + \nabla_h \Pi = \mu \Delta_h \mathbf{u}_h$$

# Inviscid limit

## Primitive system - incompressible Navier-Stokes equations

$$\operatorname{div}_x \mathbf{u} = 0$$

$$\partial_t \mathbf{u} + \operatorname{div}_x (\mathbf{u} \otimes \mathbf{u}) + \nabla_x \Pi = \boxed{\varepsilon} \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

## Target problem - incompressible Euler system

$$\operatorname{div}_x \mathbf{u} = 0$$

$$\partial_t \mathbf{u} + \operatorname{div}_x (\mathbf{u} \otimes \mathbf{u}) + \nabla_x \Pi = 0$$

# Strongly stratified limit

## Primitive system - compressible Navier-Stokes equations

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \left[ \frac{1}{\varepsilon^2} \nabla_x p(\varrho) \right] = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u}) + \frac{1}{\varepsilon^2} \varrho \nabla_x g$$

## Stationary density profile

$$\nabla_x p(\tilde{\varrho}) = \tilde{\varrho} \nabla_x g \Rightarrow P(\tilde{\varrho}) = g + \text{const}, \quad P'(\varrho) = \frac{p'(\varrho)}{\varrho}$$

## Target problem - anelastic system

$$\operatorname{div}_x(\tilde{\varrho} \mathbf{u}) = 0$$

$$\tilde{\varrho} \left[ \partial_t \mathbf{u} + \mathbf{u} \cdot \nabla_x \mathbf{u} \right] + \tilde{\varrho} \nabla_x \Pi = \mu \Delta \mathbf{u}$$

# Fundamental issues

## Solvability of the primitive system

The primitive system should admit (global) in time solutions for any choice of the scaling parameters and any admissible initial data

## Solvability of the target system

The target system should admit solutions, at least locally in time; the solutions are regular

## Stability

The family of solutions to the primitive system should be stable with respect to the scaling parameters

## Control of the “oscillatory” component of solutions

The component of solutions to the primitive system that “disappears” in the singular limit must be controlled

# Analysis of singular limits

## Primitive system

$$\partial_t U + \frac{1}{\varepsilon} \mathcal{A}[U] + \mathcal{B}[U] = 0, \quad U(0, \cdot) = U_0$$

- Existence of solutions on a time interval  $(0, T)$ ,  $T$  independent of  $\varepsilon$

## Identifying the limit system

$$\mathcal{A}[U] = 0, \quad U_{\text{limit}} \in \text{Ker}[\mathcal{A}], \quad U_{\text{osc}} \in \text{Range}[\mathcal{A}], \quad U = U_{\text{osc}} + U_{\text{limit}}$$

## Uniform bounds

- Find uniform bounds  $\|U_\varepsilon\|_X < c$  independent of  $\varepsilon \rightarrow 0$ , prepared initial data

# Equations for the limit and oscillatory components

## Compactness of the “limit” component

$$\partial_t U_{\lim} + \mathcal{B}[U_{\lim}] = 0$$

- Convergence via standard compactness arguments or “stability” of the system

## Equation for the oscillatory component

$$\varepsilon \partial_t U_{\text{osc}} + \mathcal{A}[U_{\text{osc}}] \approx 0, \quad U_{\text{osc}} \approx V\left(\frac{t}{\varepsilon}\right), \quad \partial_t V + \mathcal{A}[V] = 0$$

- Goal is to show

$$U_{\text{osc}} \rightarrow 0 \text{ in some sense}$$

- Convergence via dispersive estimates

# Global-in-time solutions to the primitive system

## Navier-Stokes system (in rotating frame)

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \varrho \mathbf{f} \times \mathbf{u} + \nabla_x p(\varrho) = \operatorname{div}_x \mathbb{S} + \varrho \nabla_x G$$

## Slip boundary and far field conditions

$$\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0, \quad [\mathbb{S} \cdot \mathbf{n}]_{\tan}|_{\partial\Omega} = 0$$

$$\varrho \rightarrow \bar{\varrho}, \quad \mathbf{u} \rightarrow 0 \text{ as } |x| \rightarrow \infty$$

## Initial data

$$\varrho(0, \cdot) = \varrho_0 > 0, \quad \mathbf{u}(0, \cdot) = \mathbf{u}_0 \text{ in } \Omega \subset \mathbb{R}^3$$

## Newton's law

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}, \quad \mu > 0, \quad \eta \geq 0$$

# Lyapunov function - energy inequality

## Stationary solutions

$$\nabla_x p(\tilde{\varrho}) = \tilde{\varrho} \nabla_x G, \quad \tilde{\varrho} \rightarrow \bar{\varrho} \text{ as } |x| \rightarrow \infty$$

## Potential energy

$$H(\varrho) = \varrho \int_{\bar{\varrho}}^{\varrho} \frac{p(z)}{z^2} dz$$

## Energy inequality

$$\begin{aligned} & \int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + H(\varrho) - H'(\tilde{\varrho})(\varrho - \tilde{\varrho}) - H(\tilde{\varrho}) \right) dx \\ & + \int_0^\tau \int_{\Omega} \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} dx dt \\ & \leq \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + H(\varrho_0) - H'(\tilde{\varrho})(\varrho_0 - \tilde{\varrho}) - H(\tilde{\varrho}) \right) dx \end{aligned}$$

# A priori bounds

## Energy bounds

$$\sqrt{\varrho} \mathbf{u} \in L^\infty(0, T; L^2(\Omega; R^3))$$

$\varrho - \tilde{\varrho} \in L^\infty(0, T; L^2 + L^\gamma(\Omega))$  provided  $p(\varrho) \approx \varrho^\gamma$

## Bounds due to dissipation

$$\mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} \in L^1((0, T) \times \Omega)$$

$$\nabla_x \mathbf{u} \in L^2(0, T; L^2(\Omega; R^3)), \quad \mathbf{u} \in L^2(0, T; W^{1,2}(\Omega; R^3))$$

# Existence for the primitive system

## Renormalized equation of continuity

$$\partial_t b(\varrho) + \operatorname{div}_x(b(\varrho)\mathbf{u}) + \left( b'(\varrho)\varrho - b(\varrho) \right) \operatorname{div}_x \mathbf{u} = 0$$

$$b(\varrho) = \varrho \log(\varrho)$$

## Compactness of (approximate) solutions

$\varrho_n \rightarrow \varrho$  weakly in  $L^p$

$$\partial_t \int (\varrho \log(\varrho)) + \int (\varrho \operatorname{div}_x \mathbf{u}) = 0$$

$$\partial_t \int \left( \overline{\varrho \log(\varrho)} \right) + \int \left( \overline{\varrho \operatorname{div}_x \mathbf{u}} \right) = 0$$

# Effective viscous flux

## Renormalized equation identity

$$\begin{aligned} & \int \left( \overline{\varrho \log(\varrho)} - \varrho \log(\varrho) \right) (\tau) + \int_0^\tau \int \left( \overline{\varrho \operatorname{div}_x \mathbf{u}} - \varrho \operatorname{div}_x \mathbf{u} \right) \\ &= \int \left( \overline{\varrho \log(\varrho)} - \varrho \log(\varrho) \right) (0) = 0, \quad p(\varrho) \approx \varrho^\gamma, \quad \gamma > \frac{3}{2} \end{aligned}$$

## Lions' identity

$$\overline{\varrho \operatorname{div}_x \mathbf{u}} - \varrho \operatorname{div}_x \mathbf{u} = \overline{p(\varrho)\varrho} - \overline{p(\varrho)} \quad \varrho \geq 0$$

## Strong convergence

$$\begin{aligned} & \int \left( \overline{\varrho \log(\varrho)} - \varrho \log(\varrho) \right) (\tau) = 0 \\ & \Rightarrow \end{aligned}$$

$$\varrho_n \rightarrow \varrho \text{ strongly in } L^1$$

# Relative entropy (energy)

## Relative entropy functional

$$\begin{aligned} & \mathcal{E}(\varrho, \mathbf{u} \mid r, \mathbf{U}) \\ &= \int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u} - \mathbf{U}|^2 + H(\varrho) - H'(r)(\varrho - r) - H(r) \right) dx \end{aligned}$$

## Potential energy

$$H(\varrho) = \varrho \int_{\bar{\varrho}}^{\varrho} \frac{p(z)}{z^2} dz$$

## Coercivity of the elastic energy

$\varrho \mapsto p(\varrho)$  strictly increasing  $\Rightarrow \varrho \mapsto H(\varrho)$  strictly convex

# Dissipative solutions

## Relative entropy inequality

$$\begin{aligned} & \left[ \mathcal{E}(\varrho, \mathbf{u} | r, \mathbf{U}) \right]_{t=0}^{\tau} + \int_0^{\tau} \int_{\Omega} \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} \, dx \, dt \\ & \leq \int_0^{\tau} \mathcal{R}(\varrho, \mathbf{u}, r, \mathbf{U}) \, dt \end{aligned}$$

for any  $r > 0$ ,  $\mathbf{U}$  satisfying relevant boundary and far field conditions

## Dissipative solutions

*Dissipative solution* is a weak solution satisfying the relative entropy inequality

# Remainder

$$\boxed{\mathcal{R}(\varrho, \mathbf{u}, r, \mathbf{U})}$$

$$\begin{aligned} &= \int_{\Omega} \left( \varrho \left( \partial_t \mathbf{U} + \mathbf{u} \cdot \nabla_x \mathbf{U} \right) \cdot (\mathbf{U} - \mathbf{u}) + \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{U} \right) dx \\ &\quad + \int_{\Omega} \left[ \left( p(r) - p(\varrho) \right) \operatorname{div} \mathbf{U} + \frac{\varrho}{r} (\mathbf{U} - \mathbf{u}) \cdot \nabla_x p(r) \right] dx \\ &\quad + \int_{\Omega} \frac{r - \varrho}{r} \left( \partial_t p(r) + \mathbf{U} \cdot \nabla_x p(r) \right) dx \\ &\quad + \int_{\Omega} (\varrho \mathbf{f} \times \mathbf{u}) \cdot (\mathbf{U} - \mathbf{u}) dx + \int_{\Omega} \varrho \nabla_x G \cdot (\mathbf{u} - \mathbf{U}) dx \end{aligned}$$

# Applications of the relative entropy inequality

## Weak strong uniqueness

Weak and strong solutions emanating from the same initial data coincide as long as the latter exists

## Regularity criterion

Suppose that a weak solution to the compressible Navier-Stokes system emanating from *regular* initial data admits a bound  $\|\varrho\|_{L^\infty} < c$ . Then the solution is smooth.

## Dimension reduction

Solutions of the compressible Navier-Stokes system on “thin” domains converge to the solutions of the limit problem

## Stability

Stability in the singular limits problems without compactness, e.g. the inviscid limit

# Weak solutions - summary

## Stability hypothesis (not strictly necessary for existence)

$p \in C[0, \infty) \cap C^2(0, \infty)$ ,  $p(0) = 0$ ,  $p'(\varrho) > 0$  for all  $\varrho > 0$

$$\lim_{\varrho \rightarrow \infty} \frac{p'(\varrho)}{\varrho^{\gamma-1}} = p_\infty > 0, \quad \gamma > \frac{3}{2}$$

## Global existence in the viscous case

Global-in-time weak dissipative solutions of the **Navier-Stokes system** exist for any finite energy initial data (under some hypotheses imposed on constitutive relations)

## Weak-strong uniqueness

Weak and strong solutions emanating from the same (regular) initial data coincide as long as the latter exists. The strong solutions are unique in the class of weak solutions

# General strategy - Step I

## Ansatz

$\varrho = \varrho_\varepsilon, \mathbf{u} = \mathbf{u}_\varepsilon$  – a dissipative weak solution

$$r = \varrho_{\text{limit}} + \varrho_{\text{osc},\varepsilon,\delta}, \quad \mathbf{U} = \mathbf{u}_{\text{limit}} + \mathbf{u}_{\text{osc},\varepsilon,\delta}$$

## Initial data

$$\varrho_{\text{osc},\varepsilon,\delta}(0, \cdot) = \varrho_{0,\text{osc},\delta}, \quad \mathbf{u}_{\text{osc},\varepsilon,\delta}(0 \cdot) = \mathbf{u}_{0,\text{osc},\delta}$$

$$\mathcal{E}_\varepsilon \left( \varrho_{0,\varepsilon}, \mathbf{u}_{0,\varepsilon} \mid \varrho_{0,\text{limit}} + \varrho_{0,\text{osc},\delta}, \mathbf{u}_{0,\text{limit}} + \mathbf{u}_{0,\text{osc},\delta} \right) \rightarrow h(\delta) \text{ as } \varepsilon \rightarrow 0$$

$$h(\delta) \rightarrow 0 \text{ as } \delta \rightarrow 0$$

## General strategy - Step 2

### Vanishing oscillatory components

$\|\varrho_{\text{osc},\varepsilon,\delta}(\tau, \cdot)\|_{L^\infty} \rightarrow 0, \quad \|\mathbf{u}_{\text{osc},\varepsilon,\delta}\|_{L^\infty} \rightarrow 0 \text{ as } \varepsilon \rightarrow 0$

for any any fixed  $\delta > 0$  and any  $\tau > 0$

### Gronwall type argument

$$\begin{aligned} & \mathcal{E}_\varepsilon \left( \varrho_\varepsilon, \mathbf{u}_\varepsilon \mid \varrho_{0,\text{limit}} + \varrho_{\text{osc},\varepsilon,\delta}, \mathbf{u}_{0,\text{limit}} + \mathbf{u}_{\text{osc},\varepsilon,\delta} \right) (\tau) \\ & \leq \mathcal{E}_\varepsilon \left( \varrho_{0,\varepsilon}, \mathbf{u}_{0,\varepsilon} \mid \varrho_{0,\text{limit}} + \varrho_{0,\text{osc},\delta}, \mathbf{u}_{0,\text{limit}} + \mathbf{u}_{0,\text{osc},\delta} \right) K(T) \end{aligned}$$

for a.a.  $\tau \in (0, T)$

### Limit passage

Taking the limits: first  $\varepsilon \rightarrow 0$  then  $\delta \rightarrow 0$

# Example: Inviscid, incompressible limit

## Primitive system

$$\partial_t \varrho_\varepsilon + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0$$

$$\partial_t (\varrho_\varepsilon \mathbf{u}_\varepsilon) + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) + \frac{1}{\varepsilon^2} \nabla_x p(\varrho_\varepsilon)$$

$$= \mu_\varepsilon \operatorname{div}_x \left( \nabla_x \mathbf{u}_\varepsilon + \nabla_x^t \mathbf{u}_\varepsilon - \frac{2}{3} \operatorname{div}_x \mathbf{u}_\varepsilon \mathbb{I} \right)$$

$$\mu_\varepsilon \rightarrow 0 \text{ as } \varepsilon \rightarrow 0$$

$$\varrho \rightarrow \bar{\varrho}, \quad \mathbf{u} \rightarrow 0 \text{ for } |x| \rightarrow \infty$$

## Target system

$$\varrho_{\text{limit}} = \bar{\varrho}, \quad \mathbf{u}_{\text{limit}} = \mathbf{v}$$

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla_x \mathbf{v} + \nabla_x \Pi = 0$$

# Energy inequality and initial data

## Scaled energy inequality

$$\begin{aligned} & \int_{\Omega} \left[ \frac{1}{2} \varrho_{\varepsilon} |\mathbf{u}_{\varepsilon}|^2 + \frac{1}{\varepsilon^2} \left( H(\varrho_{\varepsilon}) - H'(\bar{\varrho})(\varrho_{\varepsilon} - \bar{\varrho}) - H(\bar{\varrho}) \right) \right] dx \\ & \quad + \mu_{\varepsilon} \int_0^{\tau} \int_{\Omega} \mathbb{S}(\nabla_x \mathbf{u}_{\varepsilon}) : \nabla_x \mathbf{u}_{\varepsilon} dx dt \\ & \leq \int_{\Omega} \left[ \frac{1}{2} \varrho_{0,\varepsilon} |\mathbf{u}_{0,\varepsilon}|^2 + \frac{1}{\varepsilon^2} \left( H(\varrho_{0,\varepsilon}) - H'(\bar{\varrho})(\varrho_{0,\varepsilon} - \bar{\varrho}) - H(\bar{\varrho}) \right) \right] dx \end{aligned}$$

## III prepared initial data

$$\mathbf{u}_{0,\varepsilon} \rightarrow \mathbf{u}_0 \text{ in } L^2(\Omega; \mathbb{R}^3), \quad \varrho_{0,\varepsilon} = \bar{\varrho} + \varepsilon \varrho_{0,\varepsilon}^{(1)}$$

$$\|\varrho_{0,\varepsilon}^{(1)}\|_{L^\infty(\Omega)} \leq c, \quad \varrho_{0,\varepsilon}^{(1)} \rightarrow \varrho_0^{(1)} \text{ in } L^2(\Omega)$$

# Uniform bounds

## Bounds in $L^p$

$\frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon}$  bounded in  $L^\infty(0, T; (L^2 + L^\gamma)(\Omega))$

## Dissipative bounds

$$\mu_\varepsilon \int_0^T \int_{\Omega} \mathbb{S}(\nabla_x \mathbf{u}_\varepsilon) : \nabla_x \mathbf{u}_\varepsilon \, dx \, dt \approx \mu_\varepsilon \|\nabla_x \mathbf{u}_\varepsilon\|_{L^2}^2 < c$$

# Relative entropy and the initial data

## Scaled relative entropy

$$\begin{aligned} & \mathcal{E}_\varepsilon \left( \varrho_{0,\varepsilon}, \mathbf{u}_{0,\varepsilon} \mid r(0, \cdot), \mathbf{U}(0, \cdot) \right) \\ &= \int_{\Omega} \frac{1}{2} \varrho_{0,\varepsilon} \left| \mathbf{u}_{0,\varepsilon} - \mathbf{v}_0 - \mathbf{u}_{0,\text{osc},\delta} \right|^2 dx \\ & \quad + \frac{1}{\varepsilon^2} \int_{\Omega} \left( H(\varrho_{0,\varepsilon}) \right. \\ & \quad \left. - H'(\bar{\varrho} + \varepsilon s_{\varepsilon,\delta})(\varrho_{0,\varepsilon} - \bar{\varrho} - \varepsilon s_{\varepsilon,\delta}) - H(\bar{\varrho} + \varepsilon s_{\varepsilon,\delta}) \right) dx \end{aligned}$$

## Initial data

$$\mathbf{u}_0 = \mathbf{H}[\mathbf{u}_0] + \mathbf{H}^\perp[\mathbf{u}_0] = \mathbf{v}_0 + \nabla_x \Psi_0, \quad \mathbf{u}_{0,\text{osc},\delta} \approx \nabla_x \Psi_0$$

$$\varrho_{0,\text{osc},\delta} = \varepsilon s_{\varepsilon,\delta}$$

$$\varrho_{0,\text{osc},\delta} = \varepsilon s_{0,\delta}, \quad s_{0,\delta} \approx \varrho_0^{(1)}$$

# Acoustic analogy

## Lighthill's acoustic analogy

$$\varepsilon \partial_t \left( \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} \right) + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0$$

$$\varepsilon \partial_t (\varrho_\varepsilon \mathbf{u}_\varepsilon) + p'(\bar{\varrho}) \nabla_x \left( \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} \right) = -\varepsilon \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) + \varepsilon \mu_\varepsilon \operatorname{div}_x \mathbb{S}$$

$$-\frac{1}{\varepsilon} \nabla_x \left( p(\varrho_\varepsilon) - p'(\bar{\varrho}) \nabla_x \left( \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} \right) - p(\bar{\varrho}) \right) \approx o(\varepsilon)$$

## Oscillatory part

$$\varrho_{\text{osc}, \varepsilon, \delta} = \varepsilon s_{\varepsilon, \delta}, \quad s_{\varepsilon, \delta} \approx \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon}, \quad \mathbf{u}_{\text{osc}, \varepsilon, \delta} = \nabla_x \Psi_{\varepsilon, \delta} \approx \mathbf{H}^\perp [\mathbf{u}_\varepsilon]$$

$\mathbf{H}$  - Helmholtz projection

# Acoustic waves

## Acoustic (wave) equation

$$\varepsilon \partial_t s_{\varepsilon,\delta} + \bar{\varrho} \Delta_x \Psi_{\varepsilon,\delta} = 0$$

$$\varepsilon \bar{\varrho} \partial_t \Psi_{\varepsilon,\delta} + p'(\bar{\varrho}) s_{\varepsilon,\delta} = 0$$

## Initial data

$$s_{\varepsilon,\delta}(0, \cdot) = s_{0,\delta} \rightarrow \varrho_0^{(1)} \text{ in } L^2(\Omega), \quad \|s_{0,\delta}\|_{L^\infty(\Omega)} \leq c(\delta)$$

$$\Psi_{\varepsilon,\delta}(0, \cdot) = \Psi_{0,\delta}, \quad \nabla_x \Psi_{0,\delta} \rightarrow \mathbf{H}^\perp[\mathbf{u}_0] \text{ in } L^2(\Omega; \mathbb{R}^3)$$

as  $\delta \rightarrow 0$

## Boundary conditions

$$\nabla_x \Psi_{\varepsilon,\delta} \cdot \mathbf{n}|_{\partial\Omega} = 0$$

# Dispersive estimates

$$\Omega = \mathbb{R}^3$$

## Total energy conservation

$$\begin{aligned} & \frac{d}{dt} \int_{\Omega} \left( \frac{1}{2} |\nabla_x \Psi_{\varepsilon, \delta}|^2 + \frac{p'(\bar{\varrho})}{2\bar{\varrho}^2} |s_{\varepsilon, \delta}|^2 \right) dx = 0 \\ & \int_{\Omega} \left( \frac{1}{2} |\nabla_x D^m \Psi_{\varepsilon, \delta}|^2 + \frac{p'(\bar{\varrho})}{2\bar{\varrho}^2} |D^m s_{\varepsilon, \delta}|^2 \right) dx \\ &= \int_{\Omega} \left( \frac{1}{2} |\nabla_x D^m \Psi_{0, \delta}|^2 + \frac{p'(\bar{\varrho})}{2\bar{\varrho}^2} |D^m s_{0, \delta}|^2 \right) dx, \quad m = 0, 1, \dots \end{aligned}$$

## $L^1 - L^\infty$ -estimates

$$\begin{aligned} & \|\Psi_{\varepsilon, \delta}(t, \cdot)\|_{L^\infty(\Omega)} + \|s_{\varepsilon, \delta}(t, \cdot)\|_{L^\infty(\Omega)} \\ & \leq c(\bar{\varrho}) \left( \frac{\varepsilon}{t} \right) (\|\Psi_{0, \delta}\|_{W^{k,1}(\Omega)} + \|s_{0, \delta}\|_{W^{k,1}(\Omega)}), \quad k = k(N) \end{aligned}$$

# Dispersive estimates - elementary approach

## Approximation

$$s_{0,\delta} = \mathcal{F}_{\xi \rightarrow x}^{-1} \left[ \psi_\delta(|\xi|) \varrho_0^{(1)} \right], \quad \psi_\delta \in C_c^\infty(0, \infty), \quad \psi_\delta \nearrow 1$$

## Typical terms in the wave equation

$$Z(\tau, x) = \mathcal{F}_{\xi \rightarrow x}^{-1} \left[ \exp \left( \pm i|\xi|\tau \right) \psi_\delta(|\xi|) h(\xi) \right], \quad \boxed{\tau = \frac{t}{\varepsilon}}$$

$$\begin{aligned} \|Z(\tau, \cdot)\|_{L^\infty(R^3)} &\leq \left\| \mathcal{F}_{\xi \rightarrow x}^{-1} \left[ \exp \left( \pm i|\xi|\tau \right) \psi_\delta(|\xi|) h(\xi) \right] \right\|_{L^\infty(R^3)} \\ &\leq \left\| \mathcal{F}_{\xi \rightarrow x}^{-1} \left[ \exp \left( \pm i|\xi|\tau \right) \psi_\delta(|\xi|) \right] \right\|_{L^\infty(R^3)} \|h\|_{L^1(R^3)} \end{aligned}$$

## Fourier transform of radially symmetric functions

$$\begin{aligned} &\mathcal{F}_{\xi \rightarrow x}^{-1} \left[ \exp \left( \pm i|\xi|\tau \right) \right] (x) \\ &= \int_0^\infty \exp(\pm i\tau r) \psi_\delta(r) r^{3/2} |x|^{-1/2} J_{1/2}(r|x|) dr \end{aligned}$$

# van der Corput's lemma

## Lemma

Let  $\Lambda = \Lambda(z)$  be a smooth function away from the origin,

$$\partial_z \Lambda(z) \text{ monotone, } |\partial_z \Lambda(z)| \geq \Lambda_0 > 0$$

for all  $z \in [a, b]$ ,  $0 < a < b < \infty$ . Let  $\Phi$  be a smooth function on  $[a, b]$ .

Then

$$\left| \int_a^b \exp(i\Lambda(z)\tau) \Phi(z) dz \right| \leq c \frac{1}{\tau \Lambda_0} \left[ |\Phi(b)| + \int_a^b |\partial_z \Phi(z)| dz \right],$$

where  $c$  is an absolute constant independent of the specific shape  $\Lambda$  and  $\Phi$ .

# Convergence - application of relative entropy

$$\begin{aligned} & \mathcal{R}(\varrho, \mathbf{u}, r, \mathbf{U}) \\ &= \int_{\Omega} \left( \varrho \left( \partial_t \mathbf{U} + \boxed{\mathbf{u} \cdot \nabla_x \mathbf{U}} \right) \cdot (\mathbf{U} - \mathbf{u}) \right] + \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{U} \right) dx \\ &+ \int_{\Omega} \left[ (p(r) - p(\varrho)) \operatorname{div} \mathbf{U} + \frac{\varrho}{r} (\mathbf{U} - \mathbf{u}) \cdot \nabla_x p(r) \right] dx \\ &+ \int_{\Omega} \frac{r - \varrho}{r} \left( \partial_t p(r) + \mathbf{U} \cdot \nabla_x p(r) \right) dx \\ &+ \int_{\Omega} (\varrho \mathbf{f} \times \mathbf{u}) \cdot (\mathbf{U} - \mathbf{u}) dx + \int_{\Omega} \varrho \nabla_x G \cdot (\mathbf{u} - \mathbf{U}) dx \end{aligned}$$

# Convergence - example

$$\begin{aligned} & \int_{\Omega} \varrho_{\varepsilon} \mathbf{u}_{\varepsilon} \cdot \nabla_x (\mathbf{v} + \nabla_x \Psi_{\varepsilon}) \cdot (\mathbf{v} + \nabla_x \Psi_{\varepsilon} - \mathbf{u}_{\varepsilon}) \, dx \\ & \approx \int_{\Omega} \varrho_{\varepsilon} \left| \nabla_x (\mathbf{v} + \nabla_x \Psi_{\varepsilon}) \right| \left| \mathbf{v} + \nabla_x \Psi_{\varepsilon} - \mathbf{u}_{\varepsilon} \right|^2 \, dx \\ & + \int_{\Omega} \varrho_{\varepsilon} \left( \mathbf{v} + \nabla_x \Psi_{\varepsilon} \right) \cdot \nabla_x (\mathbf{v} + \nabla_x \Psi_{\varepsilon}) \cdot (\mathbf{v} + \nabla_x \Psi_{\varepsilon} - \mathbf{u}_{\varepsilon}) \, dx \\ & \approx \int_{\Omega} \varrho_{\varepsilon} \left| \nabla_x (\mathbf{v} + \nabla_x \Psi_{\varepsilon}) \right| \left| \mathbf{v} + \nabla_x \Psi_{\varepsilon} - \mathbf{u}_{\varepsilon} \right|^2 \, dx \\ & + \int_{\Omega} \bar{\varrho} \mathbf{v} \cdot \nabla_x \mathbf{v} \cdot (\mathbf{v} - \mathbf{u}_{\varepsilon}) \, dx \end{aligned}$$

- First integral “absorbed” by Gornwall type argument
- Second integral forms a part of the limit system

# Rotating fluids

## Primitive system

$$\partial_t \varrho_\varepsilon + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0$$

$$\begin{aligned} \partial_t (\varrho_\varepsilon \mathbf{u}_\varepsilon) + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) &+ \left[ \frac{1}{\varepsilon} \right] \varrho_\varepsilon \mathbf{f} \times \mathbf{u}_\varepsilon + \left[ \frac{1}{\varepsilon^{2m}} \right] \nabla_x p(\varrho_\varepsilon) \\ &= \left[ \varepsilon^\alpha \right] \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u}_\varepsilon) + \left[ \frac{1}{\varepsilon^{2n}} \right] \varrho_\varepsilon \nabla_x G \end{aligned}$$

## Infinite strip

$$\mathbf{f} = [0, 0, -1], \quad \Omega = \mathbb{R}^2 \times (0, 1), \quad \mathbf{u} \cdot \mathbf{n} = [\mathbb{S} \cdot \mathbf{n}]_{\tan}|_{\partial\Omega} = 0$$

$$\mathbf{u} \rightarrow 0, \quad \varrho \rightarrow \tilde{\varrho}_\varepsilon \approx \bar{\varrho} \text{ as } |x| \rightarrow \infty, \quad \nabla_x p(\tilde{\varrho}_\varepsilon) = \varepsilon^{2m-2n} \tilde{\varrho}_\varepsilon \nabla_x G$$

## Multiscale limit

$$\alpha > 0, \quad \frac{m}{2} > n \geq 1$$

# Expected limit for $\varepsilon \rightarrow 0$

## Low Mach number

Mach number  $\approx \varepsilon^m$ :

compressible  $\rightarrow$  incompressible

## Low Rossby number

Rossby number  $\approx \varepsilon$ :

3D flow  $\rightarrow$  2D flow

## High Reynolds number

Reynolds number  $\approx \varepsilon^{-\alpha}$ :

viscous (Navier-Stokes)  $\rightarrow$  inviscid (Euler)

# Target system

## Limit density deviation

$$\text{ess} \sup_{t \in (0, T)} \|\varrho_\varepsilon(t, \cdot) - \bar{\varrho}\|_{L^1_{\text{loc}}(\Omega)} \leq \varepsilon^m c$$

## Limit velocity

$$\sqrt{\varrho_\varepsilon} \mathbf{u}_\varepsilon \rightarrow \sqrt{\bar{\varrho}} \mathbf{v} \begin{cases} \text{weakly-(*) in } L^\infty(0, T; L^2(\Omega; R^3)), \\ \boxed{\text{strongly in } L^1_{\text{loc}}((0, T) \times \Omega; R^3)}, \end{cases}$$

## Euler system

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla_x \mathbf{v} + \nabla_x \Pi = 0 \text{ in } (0, T) \times R^2$$

$$\mathbf{v}_0 = \mathbf{H} \left[ \int_0^1 \mathbf{u}_0 \, dx_3 \right]$$

# Oscillatory - vanishing part

## Poincaré waves

$$\varepsilon^m \partial_t s_{\varepsilon,\delta} + \operatorname{div}_x \mathbf{V}_{\varepsilon,\delta} = 0$$

$$\varepsilon^m \partial_t \mathbf{V}_{\varepsilon,\delta} + \boxed{\omega \mathbf{f} \times \mathbf{V}_{\varepsilon,\delta}} + \nabla_x s_{\varepsilon,\delta} = 0, \quad \omega = \varepsilon^{m-1}$$

## Antisymmetric acoustic propagator

$$\mathcal{B}(\omega) : \begin{bmatrix} s \\ \mathbf{V} \end{bmatrix} \mapsto \begin{bmatrix} \operatorname{div}_x \mathbf{V} \\ \omega \mathbf{f} \times \mathbf{V} + \nabla_x s \end{bmatrix}.$$

# Fourier representation

## Poincaré waves

$$\varepsilon^m \partial_t \begin{bmatrix} s_\varepsilon(\xi, k, \omega) \\ \mathbf{V}_\varepsilon(\xi, k, \omega) \end{bmatrix} = i\mathcal{A}(\xi, k, \omega) \begin{bmatrix} s_\varepsilon(\xi, k, \omega) \\ \mathbf{V}_\varepsilon(\xi, k, \omega) \end{bmatrix}$$

## Hermitian matrix

$$i\mathcal{B}(\omega) \approx \mathcal{A}(\xi, k, \omega) = \begin{bmatrix} 0 & \xi_1 & \xi_2 & k \\ \xi_1 & 0 & \omega i & 0 \\ \xi_2 & -\omega i & 0 & 0 \\ k & 0 & 0 & 0 \end{bmatrix}.$$

## Eigenvalues

$$\lambda_{1,2}(\xi, k, \omega) = \pm \left[ \frac{\omega^2 + |\xi|^2 + k^2 + \sqrt{(\omega^2 + |\xi|^2 + k^2)^2 - 4\omega^2 k^2}}{2} \right]^{1/2}$$

$$\lambda_{3,4}(\xi, k, \omega) = \pm \left[ \frac{\omega^2 + |\xi|^2 + k^2 - \sqrt{(\omega^2 + |\xi|^2 + k^2)^2 - 4\omega^2 k^2}}{2} \right]^{1/2}$$

# Fourier analysis

## Frequency cut-off

$k$  fixed,  $\psi \in C_c^\infty(0, \infty)$ ,  $0 \leq \psi \leq 1$ ,  $h \approx \hat{h}(\xi, k)$

$$Z(\tau, x_h, k, \omega) = \mathcal{F}_{\xi \rightarrow x_h}^{-1} \left[ \exp \left( \pm i \lambda_j(|\xi|, k, \omega) \tau \right) \psi(|\xi|) \hat{h}(\xi, k) \right], \quad \tau = \frac{t}{\varepsilon^m}$$

## Fourier transform of radially symmetric function

$$\begin{aligned} & \|Z(\tau, \cdot, k, \omega)\|_{L^\infty(R^2)} \\ & \leq \left\| \mathcal{F}_{\xi \rightarrow x_h}^{-1} \left[ \exp \left( \pm i \lambda_j(|\xi|, k, \omega) \tau \right) \psi(|\xi|) \right] \right\|_{L^\infty(R^2)} \|h\|_{L^1(R^2)} \\ & \quad \mathcal{F}_{\xi \rightarrow x_h}^{-1} \left[ \exp \left( \pm i \lambda_j(|\xi|, k, \omega) \tau \right) \psi(|\xi|) \right] (x_h) \\ & = \int_0^\infty \exp \left( \pm i \lambda_j(r, k, \omega) \tau \right) \psi(r) r J_0(r|x_h|) dr, \end{aligned}$$

# van der Corput's lemma

## Lemma

Let  $\Lambda = \Lambda(z)$  be a smooth function away from the origin,

$$\partial_z \Lambda(z) \text{ monotone, } |\partial_z \Lambda(z)| \geq \Lambda_0 > 0$$

for all  $z \in [a, b]$ ,  $0 < a < b < \infty$ . Let  $\Phi$  be a smooth function on  $[a, b]$ .

Then

$$\left| \int_a^b \exp(i\Lambda(z)\tau) \Phi(z) dz \right| \leq c \frac{1}{\tau \Lambda_0} \left[ |\Phi(b)| + \int_a^b |\partial_z \Phi(z)| dz \right],$$

where  $c$  is an absolute constant independent of the specific shape  $\Lambda$  and  $\Phi$ .

# Decay estimates

## $L^p - L^q$ estimates

$$\|Z(\tau, \cdot, k, \omega)\|_{L^p(R^2)} \leq c(\psi, p, k) \max \left\{ \frac{1}{\omega \tau^{1-\beta/2}}, \frac{1}{\tau^{\beta/2}} \right\}^{1-\frac{2}{p}} \|h\|_{L^{p'}(R^2)}$$

for  $p \geq 2$ ,  $\frac{1}{p} + \frac{1}{p'} = 1$ ,  $\beta > 0$ ,  $\lambda_j \neq 0$ .

## Scaling

$$\omega \approx \varepsilon^{m-1}, \quad \tau \approx t/\varepsilon^m$$

## Dispersive decay

$$\left\| Z\left(\frac{t}{\varepsilon^m}, \cdot, k, \omega\right) \right\|_{L^p(R^2)} \leq c \varepsilon^{\frac{1}{2}-\frac{1}{p}} \max \left\{ \frac{1}{t^{1-1/2m}}, \frac{1}{t^{1/2m}} \right\}^{1-\frac{2}{p}} \|h\|_{L^{p'}(R^2)}$$

# Navier-Stokes-Fourier system

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho, \vartheta) = \operatorname{div}_x \mathbb{S}(\nabla_x \mathbf{u})$$

## Internal energy balance

$$\partial_t(\varrho e(\varrho, \vartheta)) + \operatorname{div}_x(\varrho e(\varrho, \vartheta) \mathbf{u}) + \operatorname{div}_x \mathbf{q} = \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} - p(\varrho, \vartheta) \operatorname{div}_x \mathbf{u}$$

# Constitutive relations

## Newton's law

$$\mathbb{S}(\nabla_x \mathbf{u}) = \mu \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta \operatorname{div}_x \mathbf{u} \mathbb{I}$$

## Fourier's law

$$\mathbf{q} = -\kappa \nabla_x \vartheta$$

## Gibbs' equation

$$\vartheta Ds(\varrho, \vartheta) = De(\varrho, \vartheta) + p(\varrho, \vartheta)D\left(\frac{1}{\varrho}\right)$$

## Thermodynamics stability

$$\frac{\partial p(\varrho, \vartheta)}{\partial \varrho} > 0, \quad \frac{\partial e(\varrho, \vartheta)}{\partial \vartheta} > 0$$

# Local well posedness

## Initial data

$$\varrho(0, \cdot) = \varrho_0 > 0, \quad \vartheta(0, \cdot) = \vartheta_0 > 0, \quad \mathbf{u}(0, \cdot) = \mathbf{u}_0$$

## Regularity

$$\varrho, \vartheta, \mathbf{u} \in W^{m,2}, \quad m \geq 3$$

## Local existence for viscous fluids - Navier-Stokes-Fourier system

A. Valli, W.Zajaczkowski [1982] - local existence for large data,  
A. Matsumura, T. Nishida [1980,1983] - global existence for small data

## Local existence for ideal (inviscid) fluids - Euler-Fourier system

T. Alazard [2006] - local existence for large data

# Several “equivalent” forms of energy balance

## Internal energy balance

$$\partial_t(\varrho e) + \operatorname{div}_x(\varrho e \mathbf{u}) + \operatorname{div}_x \mathbf{q} = \boxed{\mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u}} - \boxed{p \operatorname{div}_x \mathbf{u}}$$

## Entropy production

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) \equiv \frac{1}{\vartheta} \left( \boxed{\mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u}} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta} \right)$$

## Total energy balance

$$\begin{aligned} \partial_t \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \varrho e \right) + \operatorname{div}_x \left[ \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \varrho e \right) \mathbf{u} + p \mathbf{u} \right] + \operatorname{div}_x \mathbf{q} \\ = - \boxed{\operatorname{div}_x (\mathbb{S}(\nabla_x \mathbf{u}) \cdot \mathbf{u})} \end{aligned}$$

# Weak formulation

## Second law - entropy inequality

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x\left(\frac{\mathbf{q}}{\vartheta}\right) \geq \frac{1}{\vartheta} \left( \mathbb{S}(\nabla_x \mathbf{u}) : \nabla_x \mathbf{u} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta} \right)$$

## First law - total energy balance

$$\partial_t \int \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \varrho e \right) dx = 0$$

# Relative entropy (energy)

## Relative entropy functional

$$\mathcal{E}(\varrho, \vartheta, \mathbf{u} \mid r, \Theta, \mathbf{U})$$

$$= \int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u} - \mathbf{U}|^2 + H_{\Theta}(\varrho, \vartheta) - \frac{\partial H_{\Theta}(r, \Theta)}{\partial \varrho} (\varrho - r) - H_{\Theta}(r, \Theta) \right) dx$$

## Ballistic free energy

$$H_{\Theta}(\varrho, \vartheta) = \varrho \left( e(\varrho, \vartheta) - \Theta s(\varrho, \vartheta) \right)$$

## Coercivity of the ballistic free energy

$\varrho \mapsto H_{\Theta}(\varrho, \Theta)$  strictly convex

$\vartheta \mapsto H_{\Theta}(\varrho, \vartheta)$  decreasing for  $\vartheta < \Theta$  and increasing for  $\vartheta > \Theta$

# Dissipative solutions

## Relative entropy inequality

$$\begin{aligned} & \left[ \mathcal{E}(\varrho, \vartheta, \mathbf{u} \mid r, \Theta, \mathbf{U}) \right]_{t=0}^{\tau} \\ & + \int_0^{\tau} \int_{\Omega} \frac{\Theta}{\vartheta} \left( \mathbb{S}(\vartheta, \nabla_{\mathbf{x}} \mathbf{u}) : \nabla_{\mathbf{x}} \mathbf{u} - \frac{\mathbf{q}(\vartheta, \nabla_{\mathbf{x}} \vartheta) \cdot \nabla_{\mathbf{x}} \vartheta}{\vartheta} \right) \, d\mathbf{x} \, dt \\ & \leq \int_0^{\tau} \mathcal{R}(\varrho, \vartheta, \mathbf{u}, r, \Theta, \mathbf{U}) \, dt \end{aligned}$$

for any  $r > 0$ ,  $\Theta > 0$ ,  $\mathbf{U}$  satisfying relevant boundary conditions

# Reminder

$$\mathcal{R}(\varrho, \vartheta, \mathbf{u}, r, \Theta, \mathbf{U})$$

$$\begin{aligned} &= \int_{\Omega} \left( \varrho \left( \partial_t \mathbf{U} + \mathbf{u} \cdot \nabla_x \mathbf{U} \right) \cdot (\mathbf{U} - \mathbf{u}) + \mathbb{S}(\vartheta, \nabla_x \mathbf{u}) : \nabla_x \mathbf{U} \right) dx \\ &\quad + \int_{\Omega} \left[ \left( p(r, \Theta) - p(\varrho, \vartheta) \right) \text{div} \mathbf{U} + \frac{\varrho}{r} (\mathbf{U} - \mathbf{u}) \cdot \nabla_x p(r, \Theta) \right] dx \\ &\quad - \int_{\Omega} \left( \varrho \left( s(\varrho, \vartheta) - s(r, \Theta) \right) \partial_t \Theta + \varrho \left( s(\varrho, \vartheta) - s(r, \Theta) \right) \mathbf{u} \cdot \nabla_x \Theta \right. \\ &\quad \quad \left. + \frac{\mathbf{q}(\vartheta, \nabla_x \vartheta)}{\vartheta} \cdot \nabla_x \Theta \right) dx \\ &\quad + \int_{\Omega} \frac{r - \varrho}{r} \left( \partial_t p(r, \Theta) + \mathbf{U} \cdot \nabla_x p(r, \Theta) \right) dx \end{aligned}$$

# Weak solutions - summary

## Global existence in the viscous case

Global-in-time weak dissipative solutions of the **Navier-Stokes-Fourier system** exist for any finite energy initial data (under some hypotheses imposed on constitutive relations)

## Compatibility

Regular weak solutions are strong solutions

## Weak-strong uniqueness

Weak and strong solutions emanating from the same (regular) initial data coincide as long as the latter exists. The strong solutions are unique in the class of weak solutions

# Conditional regularity

## Sufficient condition for regularity

Suppose that a dissipative weak solution to the Navier-Stokes-Fourier system emanating from regular initial data satisfies

$$\|\nabla_x \mathbf{u}\|_{L^\infty((0,T)\times\Omega)} < \infty.$$

Then the solution is regular in  $(0, T)$ .

# Example of a singular limit for the full system

## Oberbeck-Boussinesq approximation

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \mathbf{v} \cdot \nabla_x \mathbf{v} + \nabla_x \Pi = \mu \Delta \mathbf{v} + r \nabla_x G$$

$$\partial_t \Theta + \mathbf{v} \cdot \nabla_x \Theta - \alpha \operatorname{div}_x (\mathbf{v} G) = \kappa \Delta \Theta$$

## Boussinesq relation

$$r + \beta \Theta = 0$$

# Primitive system

## Full Navier-Stokes-Fourier system

$$\partial_t \varrho_\varepsilon + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0$$

$$\partial_t (\varrho_\varepsilon \mathbf{u}_\varepsilon) + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon \otimes \mathbf{u}_\varepsilon) + \left[ \frac{1}{\varepsilon^2} \right] p(\varrho_\varepsilon, \vartheta_\varepsilon) = \operatorname{div}_x \mathbb{S}(\vartheta, \nabla_x \mathbf{u}) + \left[ \frac{1}{\varepsilon} \right] \varrho \nabla_x G$$

$$\partial_t (\varrho_\varepsilon s(\varrho_\varepsilon, \vartheta_\varepsilon)) + \operatorname{div}_x (\varrho s(\varrho_\varepsilon, \vartheta_\varepsilon) \mathbf{u}_\varepsilon) + \operatorname{div}_x \left( \frac{\mathbf{q}(\vartheta_\varepsilon, \nabla_x \vartheta_\varepsilon)}{\vartheta_\varepsilon} \right)$$

$$\geq \frac{1}{\vartheta_\varepsilon} \left( \left[ \varepsilon^2 \right] \mathbb{S}(\vartheta_\varepsilon, \nabla_x \mathbf{u}_\varepsilon) : \nabla_x \mathbf{u}_\varepsilon - \frac{\mathbf{q}(\vartheta_\varepsilon, \nabla_x \vartheta_\varepsilon)}{\vartheta_\varepsilon} \right)$$

$$\frac{d}{dt} \int_{\Omega} \left( \left[ \frac{\varepsilon^2}{2} \right] \varrho_\varepsilon |\mathbf{u}_\varepsilon|^2 + \varrho_\varepsilon e(\varrho_\varepsilon, \vartheta_\varepsilon) - \left[ \varepsilon \right] \varrho_\varepsilon G \right) dx = 0$$

# Spatial domain

## Gravitational potential

$\Omega \subset R^3$ , unbounded

$-\Delta G = m$  in  $R^3$ ,  $\text{supp}[m] \subset R^3 \setminus \Omega$

# Entropy inequality and uniform bounds

## Entropy production equation

$$\partial_t(\varrho_\varepsilon s(\varrho_\varepsilon, \vartheta_\varepsilon)) + \operatorname{div}_x(\varrho_\varepsilon s(\varrho_\varepsilon, \vartheta_\varepsilon) \mathbf{u}_\varepsilon) + \operatorname{div}_x \left( \frac{\mathbf{q}(\vartheta_\varepsilon, \nabla_x \vartheta_\varepsilon)}{\vartheta_\varepsilon} \right) = \sigma_\varepsilon$$

$$\sigma_\varepsilon \geq \frac{1}{\vartheta_\varepsilon} \left( \varepsilon^2 \mathbb{S}(\vartheta_\varepsilon, \nabla_x \mathbf{u}_\varepsilon) : \nabla_x \mathbf{u}_\varepsilon - \frac{\mathbf{q}(\vartheta_\varepsilon, \nabla_x \vartheta_\varepsilon) \cdot \nabla_x \vartheta_\varepsilon}{\vartheta_\varepsilon} \right)$$

## Relative entropy inequality

$$\left[ \mathcal{E}_\varepsilon \left( \varrho_\varepsilon, \vartheta_\varepsilon, \mathbf{u}_\varepsilon \middle| r, \Theta, \mathbf{U} \right) \right]_{t=0}^\tau + \frac{1}{\varepsilon^2} \sigma_\varepsilon |_{[0, \tau]}$$

$$\equiv \int_0^\tau \mathcal{R}_\varepsilon(\varrho_\varepsilon, \vartheta_\varepsilon, \mathbf{u}_\varepsilon, r, \Theta, \mathbf{U}) \, dt$$

### III prepared initial data

#### Density

$$\varrho_{0,\varepsilon} = \bar{\varrho} + \varepsilon \boxed{\varrho_{0,\varepsilon}^{(1)}}$$

#### Temperature

$$\vartheta_{0,\varepsilon} = \bar{\vartheta} + \varepsilon \boxed{\vartheta_{0,\varepsilon}^{(1)}}$$

#### Velocity

$$\mathbf{u}_{0,\varepsilon} = \mathbf{v}_{0,\varepsilon} + \boxed{\nabla_x \Psi_\varepsilon}$$

# Acoustic analogy

## Acoustic analogy

$$\varepsilon \partial_t \left( \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} \right) + \operatorname{div}_x (\varrho_\varepsilon \mathbf{u}_\varepsilon) = 0$$

$$\varepsilon \partial_t (\varrho_\varepsilon \mathbf{u}_\varepsilon) + \nabla_x \left( p_\varrho(\bar{\varrho}, \bar{\vartheta}) \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} + p_\vartheta(\bar{\varrho}, \bar{\vartheta}) \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} - \bar{\varrho} F \right) = o(\varepsilon)$$

$$\varepsilon \partial_t \left( s_\varrho(\bar{\varrho}, \bar{\vartheta}) \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} + s_\vartheta(\bar{\varrho}, \bar{\vartheta}) \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} \right) = \sigma_\varepsilon + o(\varepsilon)$$

## Thermodynamics and acoustic equation

$$\frac{\partial s(\varrho, \vartheta)}{\partial \varrho} = - \frac{1}{\varrho^2} \frac{\partial p(\varrho, \vartheta)}{\partial \vartheta}$$

$$\varepsilon \partial_t Z + \operatorname{div}_x \mathbf{V} = 0, \quad \varepsilon \partial_t \mathbf{V} + \nabla_x Z = 0$$

$$Z = p_\varrho(\bar{\varrho}, \bar{\vartheta}) \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} + p_\vartheta(\bar{\varrho}, \bar{\vartheta}) \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} - \bar{\varrho} F$$

# Heat-entropy equation

## Heat equation

$$\begin{aligned} & \partial_t \left( s_\varrho(\bar{\varrho}, \bar{\vartheta}) \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} + s_\vartheta(\bar{\varrho}, \bar{\vartheta}) \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} \right) \\ & + \operatorname{div}_x \left[ \left( s_\varrho(\bar{\varrho}, \bar{\vartheta}) \frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} + s_\vartheta(\bar{\varrho}, \bar{\vartheta}) \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} \right) \mathbf{u} \right] \\ & - \tilde{\kappa}(\bar{\vartheta}) \Delta \left( \frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} \right) = o(\varepsilon) \end{aligned}$$

# Asymptotic limit

## Velocity

$$\mathbf{u}_\varepsilon \rightarrow \mathbf{v}$$

## Density deviation

$$\frac{\varrho_\varepsilon - \bar{\varrho}}{\varepsilon} \rightarrow r$$

## Temperature deviation

$$\frac{\vartheta_\varepsilon - \bar{\vartheta}}{\varepsilon} \rightarrow \Theta$$

# Other problems...

## Related issues

- stratified fluid, acoustic equations, problems with “vacuum”
- limit passage “weak → weak”
- bounded (periodic) domains
- boundary conditions, no-slip and the boundary layer problems

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- Ivan Straškraba (IM Praha)
- Takeo Takahashi (Nancy)
- Ping Zhang (Acad Sci Beijing)