# Guaranteed and robust error bounds for singularly perturbed problems in arbitrary dimension

Mark Ainsworth

#### Tomáš Vejchodský



Division of Applied Mathematics Brown University Providence, USA



Centre for Mathematical Biology Mathematical Institute University of Oxford



Institute of Mathematics Academy of Sciences Czech Republic

▲ロト ▲帰ト ▲ヨト ▲ヨト 三日 - の々ぐ

MAFELAP 2013, Brunel University, June 10-14, 2013

# Outline



$$\begin{aligned} -\Delta u + \kappa^2 u &= f \quad \text{in } \Omega \subset \mathbb{R}^d \\ u &= g_N \quad \text{on } \partial \Omega \qquad \qquad \kappa > 0 \end{aligned}$$

- Arbitrary dimension
- Neumann boundary conditions
- Guaranteed and robust upper bound on error
- Guaranteed bounds of trace constants

M. Ainsworth, T. Vejchodský: *Fully computable robust a posteriori error bounds for singularly perturbed reaction-diffusion problems*, Numer. Math. 119 (2), 2011, 219–243.

# Model problem



Classical formulation:  $-\Delta u + \kappa^2 u = f \text{ in } \Omega \subset \mathbb{R}^d$  $u = g_N \text{ on } \partial \Omega \qquad \kappa > 0$ 

Weak formulation:

$$u \in V$$
:  $\mathcal{B}(u, v) = (f, v)_{\Omega} \quad \forall v \in V$ 

Linear FEM on *d*-dimensional simplices:

$$u_h \in V_h$$
:  $\mathcal{B}(u_h, v_h) = (f, v_h)_{\Omega}$   $\forall$ 

Notation:

$$\begin{split} V &= H_0^1(\Omega) \\ \mathcal{B}(u, v) &= (\nabla u, \nabla v)_{\Omega} + \kappa^2 (u, v)_{\Omega} \\ (f, v)_{\Omega} &= \int_{\Omega} f v \, \mathrm{d}x \\ V_h &= \{ v_h \in V : v_h |_K \in P^1(K), K \in \mathcal{T}_h \} \end{split}$$



3

・ロト ・四ト ・ヨト ・ヨト

# Main result

Upper bound:  $\|\|\boldsymbol{u} - \boldsymbol{u}_h\|\|^2 \leq \sum_{K \in \mathcal{T}_h} \left[\eta_K(\mathbf{y}) + \operatorname{osc}_K(f) + \operatorname{osc}_{\partial\Omega \cap \partial K}(g_N)\right]^2$   $\forall \mathbf{y} \in \mathbf{H}(\operatorname{div}, \Omega) : \mathbf{y} \cdot \mathbf{n} = \Pi_{\gamma}^K g_N \text{ on all } \gamma \subset \partial\Omega \cap \partial K$ Local efficiency:  $\eta_K(\mathbf{y}) \leq C\left(\|\|\boldsymbol{u} - \boldsymbol{u}_h\|\|_{\widetilde{K}} + \min\{h_K, \kappa^{-1}\}\|f - \Pi f\|_{\widetilde{K}} + \min\{h_K, \kappa^{-1}\}^{1/2}\|g_N - \Pi_{\gamma}^K g_N\|_{\partial\Omega \cap \partial K}\right) \text{ for a special } \mathbf{y}$ 

• 
$$\eta_{K}^{2}(\mathbf{y}) = \|\mathbf{y} - \nabla u_{h}\|_{0,K}^{2} + \kappa^{-2} \|\Pi_{K}f - \kappa^{2}u_{h} + \operatorname{div} \mathbf{y}\|_{0,K}^{2}$$

•  $\operatorname{osc}_{\mathcal{K}}(f) = \min\left\{h_{\mathcal{K}}/\pi, \kappa^{-1}\right\} \|f - \Pi_{\mathcal{K}}f\|_{0,\mathcal{K}}$ 

•  $\operatorname{osc}_{\partial\Omega\cap\partial K}(g_N) = \min\{C_{\mathrm{T}}^K, C_{\mathrm{T}}^{K,\kappa}\} \|g_N - \Pi_{\gamma}^K g_N\|_{\partial\Omega\cap\partial K}$ 

$$\Pi_{K} f \in P^{1}(K): \quad (f - \Pi_{K} f, \varphi)_{K} = 0 \quad \forall \varphi \in P^{1}(K)$$
  
 
$$\Pi_{\gamma}^{K} g_{N} \in P^{1}(\gamma): \quad (f - \Pi_{\gamma}^{K} g_{N}, \varphi)_{\gamma} = 0 \quad \forall \varphi \in P^{1}(\gamma)$$

# Flux reconstruction



- Compute robust inter-element fluxes  $g_K$ 
  - ►  $g_K \approx \nabla u \cdot \mathbf{n}_K$  on  $\partial K$ [Ainsworth, Babuška, 1999], [Ainsworth, Vejchodský, 2011]
- For all elements K with  $\kappa \rho_K \leq 1$  construct  $\mathbf{y}_K^{(1)}$ :

▶ 
$$\mathbf{y}_{K}^{(1)} \cdot \mathbf{n}_{K} = g_{K}$$
 on  $\partial K$   
▶  $\Pi_{K}f - \kappa^{2}u_{h} + \operatorname{div} \mathbf{y}_{K}^{(1)} =$ 

• For all elements K with  $\kappa \rho_K > 1$  construct  $\mathbf{y}_K^{(2)}$ :

• 
$$\mathbf{y}_{K}^{(2)} \cdot \mathbf{n}_{K} = g_{K}$$
 on  $\partial K$ 

- Correct asymptotic behavior w.r.t. h and  $\kappa$ 

$$\mathbf{y}|_{\mathcal{K}} = \left\{ \begin{array}{ll} \mathbf{y}_{\mathcal{K}}^{(1)} & \text{if } \kappa \rho_{\mathcal{K}} \leq 1, \\ \mathbf{y}_{\mathcal{K}}^{(2)} & \text{if } \kappa \rho_{\mathcal{K}} > 1, \end{array} \right.$$



# Flux reconstruction #1

#### Definition:

$$\mathbf{y}_{K}^{(1)} = \nabla u_{h} + \mathbf{y}_{K}^{L} + \mathbf{y}_{K}^{Q}$$

$$\mathbf{y}_{K}^{L} = -\sum_{n=1}^{d+1} \lambda_{n} \sum_{\substack{m=1\\m\neq n}}^{d+1} R_{|\gamma_{m}}(\mathbf{x}_{n}) |\nabla \lambda_{m}| \mathbf{t}_{nm}$$

$$\mathbf{y}_{K}^{Q} = \frac{1}{d+1} \sum_{n=1}^{d+1} \sum_{\substack{m=2\\m>n}}^{d+1} \lambda_{m} \lambda_{n} \mathbf{t}_{mn} \mathbf{t}_{mn}^{T} \nabla r(\overline{\mathbf{x}}_{K})$$

#### Notation:

$$R = g_{K} - \nabla u_{h} \cdot \mathbf{n}_{K}$$
  

$$r = \Pi_{K} f - \kappa^{2} u_{h}$$
  

$$\lambda_{n} \dots \text{ barycentric coords in } K$$
  

$$\mathbf{t}_{mn} = \mathbf{x}_{m} - \mathbf{x}_{n} \dots \text{ edge vector}$$
  

$$\overline{\mathbf{x}}_{K} \dots \text{ barycentre of } K$$



◆□▶ ◆□▶ ◆臣▶ ◆臣▶ 臣 の�?

# Flux reconstruction #2



#### Definition:

$$\mathbf{y}_{K}^{(2)} = \nabla u_{h} + \mathbf{y}_{K}^{O}$$

$$\mathbf{y}_{K}^{O}|_{K_{\gamma}} = \frac{1}{\rho_{K}} \mathrm{e}^{-\kappa x_{d}} (\mathbf{x} - \mathbf{x}_{K}) R(x_{1}, \dots, x_{d-1}) \quad \text{ for all } \gamma \subset \partial K$$

#### Notation:

 $R = g_K - \nabla u_h \cdot \mathbf{n}_K$  $\mathbf{x}_K \dots \text{ incentre of } K$  $\rho_K \dots \text{ inradius of } K$ 



Example (cube)





 $N_{\rm DOF} = 29791$  h = 0.03125

 $I_{\rm eff} = \frac{\eta}{\|\boldsymbol{u} - \boldsymbol{u}_h\|}$ 

◆□▶ ◆□▶ ◆三▶ ◆三▶ 三三 のへ⊙

# Trace constants



Neumann oscillations:  $osc_{\partial\Omega\cap\partial K}(g_N) = \min\{C_{\mathrm{T}}^{K}, C_{\mathrm{T}}^{K,\kappa}\} \|g_N - \Pi_{\gamma}^{K}g_N\|_{\partial\Omega\cap\partial K}$ 

Trace theorems:

(1) 
$$\|\mathbf{v} - \overline{\mathbf{v}}\|_{0,\partial K} \leq C_{\mathrm{T}}^{K} \|\nabla \mathbf{v}\|_{0,K} \quad \forall \mathbf{v} \in H^{1}(K) \quad \overline{\mathbf{v}} = \frac{1}{|\partial K|} \int_{\partial K} \mathbf{v} \, \mathrm{d}\mathbf{x}$$
  
(2)  $\|\mathbf{v}\|_{0,\partial K} \leq C_{\mathrm{T}}^{K,\kappa} \left(\|\nabla \mathbf{v}\|_{0,K}^{2} + \kappa^{2} \|\mathbf{v}\|_{0,K}^{2}\right)^{1/2} \quad \forall \mathbf{v} \in H^{1}(K)$ 

Connection to eigenvalues:

Two-sided bounds: [Šebestová, Vejchodský, preprint 2013]

Trace constant (1) for triangles



$$\|v-\overline{v}\|_{0,\partial K} \leq C_{\mathrm{T}}^{K} \|
abla v\|_{0,K} \quad orall v \in H^{1}(K) \quad \overline{v} = rac{1}{|\partial K|} \int_{\partial K} v \, \mathrm{d}x$$

Scaling:  $C_{\mathrm{T}}^{K} = h_{K}^{1/2} C_{\mathrm{T},h=1}^{K}$ 



- Upper bound
- Error 1%



Trace constant (2) for triangles  $\|v\|_{0,\partial K} \leq C_{\mathrm{T}}^{K,\kappa} \left(\|\nabla v\|_{0,K}^{2} + \kappa^{2}\|v\|_{0,K}^{2}\right)^{1/2} \quad \forall v \in H^{1}(K)$ 

Scaling:  $C_{\mathrm{T}}^{K,\kappa} \leq \max\{1,\kappa^{-1}\}h_{K}^{1/2}C_{\mathrm{T},h=1}^{K,\kappa=1}$ 





Trace constant (2) for triangles  $\|v\|_{0,\partial K} \le C_{\mathrm{T}}^{K,\kappa} \left(\|\nabla v\|_{0,K}^{2} + \kappa^{2} \|v\|_{0,K}^{2}\right)^{1/2} \quad \forall v \in H^{1}(K)$ Numerical tests:  $C_{\rm T}^{K,\kappa} \leq \kappa^{-1/2} h_K^{1/2} C_{\rm T}^{K,\kappa=1}$  for  $\kappa > 1$ Trace const. vs. $\kappa$ , triangles 10<sup>2</sup> 10<sup>1</sup> 10<sup>0</sup> С<sub>то<sup>-1</sup></sub>  $10^{-2}$ \* α=1 β=1 Ο α=1 β=89 10 ο α=60 β=60 10 10<sup>2</sup> 10<sup>3</sup> 10<sup>5</sup> 10<sup>6</sup>  $10^{4}$  $10^{1}$ 

|▶ ◀圖▶ ◀필▶ ◀필▶ \_ 필 \_ 釣۹()

# Conclusions



▲□▶ ▲□▶ ▲□▶ ▲□▶ ▲□ ● ● ●

- Fast flux reconstruction
- Guaranteed upper bound on error
- Robust for all values of  $\kappa$
- Arbitrary dimension
- Neumann b.c. require bounds for trace constants

# Thank you for your attention

#### Mark Ainsworth

### Tomáš Vejchodský



Division of Applied Mathematics Brown University Providence, USA



Centre for Mathematical Biology Mathematical Institute University of Oxford



Institute of Mathematics Academy of Sciences Czech Republic

< □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > < □ > <

MAFELAP 2013, Brunel University, June 10-14, 2013