

# Maximal dissipation and well-posedness for the compressible Euler system

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# Compressible Euler system

## Equation of continuity

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho) = 0$$

## Periodic (impermeable) boundary conditions

$$\Omega = [[-1, 1]_{\{-1, 1\}}]^N, \quad N = \boxed{2, 3}$$

## Initial data

$$\varrho(0, \cdot) = \varrho_0, \quad (\varrho \mathbf{u}) = \varrho_0 \mathbf{u}_0, \quad \varrho_0 > 0$$

# Weak solutions

## Regularity

$$\begin{aligned} \varrho &\in L^\infty((0, T) \times \Omega) \cap C_{\text{weak}}([0, T]; L^1(\Omega)), \quad \varrho > 0 \\ \mathbf{u} &\in L^\infty((0, T) \times \Omega; \mathbb{R}^N), \quad (\varrho \mathbf{u}) \in C_{\text{weak}}([0, T]; L^2(\Omega; \mathbb{R}^N)) \end{aligned}$$

## Equation of continuity and momentum balance

$$\int_{\Omega} \left( \varrho(\tau, \cdot) \varphi(\tau, \cdot) - \varrho_0 \varphi(0, \cdot) \right) dx = \int_0^\tau \int_{\Omega} \left( \varrho \partial_t \varphi + \varrho \mathbf{u} \cdot \nabla_x \varphi \right) dx dt$$

for any  $\tau \in [0, T]$ , and any  $\varphi \in C^\infty([0, T] \times \Omega)$

$$\begin{aligned} &\int_{\Omega} \left( (\varrho \mathbf{u})(\tau, \cdot) \cdot \varphi(\tau, \cdot) - \varrho_0 \mathbf{u}_0 \cdot \varphi(0, \cdot) \right) dx \\ &= \int_0^\tau \int_{\Omega} \left( \varrho \mathbf{u} \cdot \partial_t \varphi + \varrho \mathbf{u} \otimes \mathbf{u} : \nabla_x \varphi + p(\varrho) \operatorname{div}_x \varphi \right) dx dt \end{aligned}$$

for any  $\tau \in [0, T]$ , and any  $\varphi \in C^\infty([0, T] \times \Omega; \mathbb{R}^3)$

# Energy and dissipation

## Mechanical energy

$$\frac{1}{2}\varrho|\mathbf{u}|^2 + P(\varrho) = \frac{1}{2} \frac{|\varrho\mathbf{u}|^2}{\varrho} + P(\varrho), \quad P(\varrho) = \varrho \int_1^{\varrho} \frac{p(z)}{z^2} dz$$

## Energy balance - regular solutions

$$\partial_t \left( \frac{1}{2}\varrho|\mathbf{u}|^2 + P(\varrho) \right) + \operatorname{div}_x \left[ \left( \frac{1}{2}\varrho|\mathbf{u}|^2 + P(\varrho) \right) \mathbf{u} \right] + \operatorname{div}_x (p(\varrho)\mathbf{u}) = 0$$

## Energy dissipation - weak solutions

$$\partial_t \left( \frac{1}{2}\varrho|\mathbf{u}|^2 + P(\varrho) \right) + \operatorname{div}_x \left[ \left( \frac{1}{2}\varrho|\mathbf{u}|^2 + P(\varrho) \right) \mathbf{u} \right] + \operatorname{div}_x (p(\varrho)\mathbf{u}) \leq 0$$

# Admissible weak solutions

## Entropy inequality - weak formulation

$$\int_0^T \int_{\Omega} \left[ \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right) \partial_t \varphi + \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right) \mathbf{u} \cdot \nabla_x \varphi \right] dx dt$$
$$+ \int_0^T \int_{\Omega} \rho(\varrho) \mathbf{u} \cdot \nabla_x \varphi dx dt + \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + P(\varrho_0) \right) \varphi(0, \cdot) dx \geq 0$$

for any  $\varphi \in C_c^\infty([0, T] \times \Omega)$ ,  $\varphi \geq 0$

## Energy - weak form

$$\int_{\Omega} E(\tau+) \varphi dx = \operatorname{ess\,lim}_{t \rightarrow \tau+} \int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right) \varphi dx, \quad \tau \in [0, T]$$

$$\int_{\Omega} E(\tau-) \varphi dx = \operatorname{ess\,lim}_{t \rightarrow \tau-} \int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + P(\varrho) \right) \varphi dx, \quad \tau \in (0, T]$$

# Principle of maximal dissipation

## Maximal dissipation [Dafermos 1974]

Let  $\tau \in [0, T)$  and let  $[\tilde{\varrho}, \tilde{\mathbf{u}}]$  be another weak solution, defined in  $[0, \tilde{T}]$ ,  $\tau < \tilde{T} \leq T$ , such that

$$\varrho = \tilde{\varrho}, \varrho \mathbf{u} = \tilde{\varrho} \tilde{\mathbf{u}} \text{ in } [0, \tau] \times \Omega.$$

Then there exists a sequence  $\{\tau_n\}_{n=1}^{\infty}$ ,  $\tau_n > \tau$ ,  $\tau_n \rightarrow \tau$  such that

$$\int_{\Omega} \tilde{E}(\tau_n+) \, dx \geq \int_{\Omega} E(\tau_n+) \, dx \text{ for all } n = 1, 2, \dots,$$

where  $E, \tilde{E}$  is the mechanical energy associated with  $u, \tilde{u}$

# Incompressible Euler system

## Equations

$$\operatorname{div}_x \mathbf{v} = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x (\mathbf{v} \otimes \mathbf{v}) + \nabla_x \Pi = 0$$

## Initial conditions

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

## DeLellis, Székelyhidi [2008]

There exist (infinite) set of initial data  $\mathbf{v}_0$  in  $L^2 \cap L^\infty(\Omega; \mathbb{R}^3)$  such that the incompressible Euler system possesses infinitely many global in time solutions, with prescribed energy

$$\frac{1}{2} |\mathbf{v}|^2 = e, \quad e(0, \cdot) = \frac{1}{2} |\mathbf{v}_0|^2 \quad \text{and the pressure } \Pi = -\frac{1}{3} |\mathbf{v}|^2$$

# Infinitely many admissible solutions

## Corollary of the result of DeLellis and Székelyhidi

$$\varrho(0, \cdot) = \bar{\varrho} > 0 \text{ const, } e = \text{const}$$

There exists  $\mathbf{u}_0 \in L^2 \cap L^\infty$  such that the *compressible* Euler system possesses infinitely many admissible weak solutions. The solutions satisfy  $\varrho = \bar{\varrho}$  for all  $t \geq 0$ .

## Improvement by Chiodaroli [2012]

$$\varrho(0, \cdot) = \varrho_0 > 0, \varrho_0 \in C^1(\Omega)$$

There exists  $\mathbf{u}_0 \in L^2 \cap L^\infty$  and  $T > 0$  such that the *compressible* Euler system possesses infinitely many admissible weak solutions in  $[0, T]$ . The solutions satisfy  $\varrho = \varrho_0$  for all  $t \in [0, T]$ .



# Method of convex integration, I

## Set of subsolutions

$$\begin{aligned} X_{0,e}[0, T] = & \left\{ \mathbf{v} \in C_{\text{weak}}([0, T]; L^2(\Omega; \mathbb{R}^3)) \mid \right. \\ & \mathbf{v}(0, \cdot) = \mathbf{v}_0, \mathbf{v}(T, \cdot) = \mathbf{v}_T, \operatorname{div}_x \mathbf{v} = 0, \\ & \mathbf{v} \in C^1((0, T) \times \Omega; \mathbb{R}^3), \partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0 \\ & \text{for a certain } \mathbb{U} \in C^1((0, T) \times \Omega; \mathbb{R}_{\text{sym},0}^{3 \times 3}), \\ & \left. \frac{3}{2} \lambda_{\max} \left[ \frac{\mathbf{v} \otimes \mathbf{v}}{\varrho} - \mathbb{U} \right] < e \text{ in } (0, T) \times \Omega \right\}, \end{aligned}$$

## Distance function

$$\frac{3}{2} \lambda_{\max} \left[ \frac{\mathbf{v} \otimes \mathbf{v}}{\varrho} - \mathbb{U} \right] \geq \frac{1}{2} \frac{|\mathbf{v}|^2}{\varrho},$$

# Method of convex integration, II

## Oscillatory lemma [DeLellis, Székelyhidi]

For any  $\mathbf{v} \in X_{0,e}[0, T]$  there exist sequences

$$\{\mathbf{w}_n\}_{n=1}^{\infty} \subset C_c^{\infty}((0, T) \times \Omega; \mathbb{R}^3), \quad \{\mathbb{U}_n\}_{n=1}^{\infty} \subset C_c^{\infty}((0, T) \times \Omega; \mathbb{R}^3)$$

such that the functions  $\mathbf{v} + \mathbf{w}_n$  belong to  $X_{0,e}[0, T]$ , with the associated tensor fields  $\mathbb{U} + \mathbb{U}_n$ ,

$$\mathbf{w}_n \rightarrow 0 \text{ in } C_{\text{weak}}([0, T]; L^2(\Omega; \mathbb{R}^3)),$$

and

$$\liminf_{n \rightarrow \infty} \|\mathbf{w}_n\|_{L^2((0, T) \times \Omega)}^2 \geq \Lambda \int_{\tau_1}^{\tau_2} \int_{\Omega} \left( e - \frac{1}{2} \frac{|\mathbf{v}|^2}{\varrho} \right)^2 dx dt, \quad \Lambda > 0,$$

where the constant  $\Lambda$  depends only on the norm of the quantities  $\varrho, \varrho^{-1}, e$  in  $L^{\infty}((0, T) \times \Omega)$ .

# Problem with constant (in time) density

## “Ansatz”

$$\varrho = \varrho_0 \in C^1(\Omega), \quad \mathbf{v} = \varrho \mathbf{u}$$
$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{\mathbf{v} \otimes \mathbf{v}}{\varrho} \right) + \nabla_x \Pi = 0$$

## Solutions by convex integration

$$\frac{1}{2} \frac{|\mathbf{v}|^2}{\varrho} = \frac{1}{2} \varrho |\mathbf{u}|^2 = e$$

$$\Pi = -\frac{1}{3} \frac{|\mathbf{v}|^2}{\varrho} = -\frac{2}{3} e$$

## Choice of kinetic energy

$$\Pi = p(\varrho) - \frac{2}{3} \chi(t) = -\frac{2}{3} e \Rightarrow e = \chi(t) - \frac{3}{2} p(\varrho)$$

# Construction by convex integration

## Step 1: Energy

Choose  $e$  (or rather  $\chi$ ) to ensure validity of the energy inequality

## Step 2: Subsolution

Make sure that the space of subsolutions is non-empty

## Step 3: Suitable subsolutions

Construct a new space of subsolutions (on a possibly shorter time interval) so that

$$\frac{1}{2} \frac{|\mathbf{v}_0|^2}{\rho} = e(0, \cdot)$$

# Modification via Helmholtz decomposition

## Helmholtz decomposition

$$\varrho \mathbf{u} = \mathbf{v} + \nabla_x \Psi, \quad \operatorname{div}_x \mathbf{v} = 0$$

## Reformulation

$$\partial_t \varrho + \Delta \Psi = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} \right) + \nabla_x (\partial_t \Psi + p(\varrho)) = 0$$

## Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \nabla_x \Psi|^2}{\varrho} = e$$

# Application of convex integration

## Set of subsolutions

$$\begin{aligned} X_{0,e}[0, T] = & \left\{ \mathbf{v} \in C_{\text{weak}}([0, T]; L^2(\Omega; R^3)) \mid \right. \\ & \mathbf{v}(0, \cdot) = \mathbf{v}_0, \mathbf{v}(T, \cdot) = \mathbf{v}_T, \operatorname{div}_x \mathbf{v} = 0, \\ & \mathbf{v} \in C^1((0, T) \times \Omega; R^3), \partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0 \\ & \text{for a certain } \mathbb{U} \in C^1((0, T) \times \Omega; R_{\text{sym},0}^{3 \times 3}), \\ & \left. \frac{3}{2} \lambda_{\max} \left[ \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} - \mathbb{U} \right] < e \text{ in } (0, T) \times \Omega \right\}, \end{aligned}$$

## Distance function

$$\frac{3}{2} \lambda_{\max} \left[ \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} - \mathbb{U} \right] \geq \frac{1}{2} \frac{|\mathbf{v} + \nabla_x \Psi|^2}{\varrho},$$

# Convex integration revisited

## Step 1: Energy

Choose  $e$  (or rather  $\chi$ ) to ensure validity of the energy inequality

## Step 2: Subsolution

Make sure that the space of subsolutions is non-empty

## Step 3: Suitable subsolutions

Construct a new space of subsolutions so that

$$\frac{1}{2} \frac{|\mathbf{v}_0 + \nabla_x \Psi_0|^2}{\rho_0} = e(0, \cdot)$$

# Global admissible solutions

## Global-in-time solutions

$$\varrho_0 \in C^1(\Omega), \varrho_0 > 0, \int_{\Omega} \varrho_0 \, dx = M_0, |\nabla_x \varrho_0| < \varepsilon(M_0)$$

There exists  $\mathbf{u}_0$  such that the compressible Euler system admits infinitely many global-in-time admissible solutions

## Remark

The solutions coincide with the static state  $[\bar{\varrho}, 0]$  for  $t$  large



# Convex integration and maximal dissipation

## Kinetic energy

$$\frac{1}{2}\varrho|\mathbf{u}|^2(t, \cdot) = e(t, \cdot), \quad \frac{1}{2}\varrho_0|\mathbf{u}_0|^2 = e(0, \cdot)$$

## Construction

- Choose  $\tilde{e}$ ,

$$\tilde{e}(0, \cdot) = e(0, \cdot), \quad \tilde{e}(T, \cdot) = e(T, \cdot)$$

$$\tilde{e}(t, \cdot) < e(t, \cdot), \quad t \in (0, T)$$

- Take

$$X_{0, \tilde{e}}[0, T] \subset X_{0, e}[0, T]$$

- Make sure

$$\frac{1}{2}\varrho_0|\mathbf{u}_0|^2 = e(0, \cdot), \quad X_{0, \tilde{e}}[0, T] \neq \emptyset$$