

# On the well-posedness problems for (certain) complete fluid systems

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The reserach partially supported by ERC-CZ project LL1202 MORE  
Chateau Liblice, 24-27 November 2013

# Euler-Fourier system

## Equation of continuity

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum equation

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\varrho \vartheta) = \boxed{0}$$

## Energy balance

$$\frac{3}{2} [\partial_t(\varrho \vartheta) + \operatorname{div}_x(\varrho \vartheta \mathbf{u})] - \boxed{\Delta \vartheta} = -\varrho \vartheta \operatorname{div}_x \mathbf{u}$$

## Initial conditions

$$\varrho(0, \cdot) = \varrho_0, \quad \vartheta(0, \cdot) = \vartheta_0, \quad \mathbf{u}(0, \cdot) = \mathbf{u}_0$$

# Well posedness

## Local existence of classical solutions [Alazard , Serre (2008)]

For any given smooth initial data,

$$\varrho_0 > 0, \vartheta_0 > 0,$$

there exists  $T_{\max}$  such that the system possesses a classical solution defined on the time interval  $(0, T_{\max})$ . The classical solution is unique in the class of smooth solutions.

## Global existence of weak solutions [Chiodaroli, F., Kreml (2013)]

For any given smooth initial data,

$$\varrho_0 > 0, \vartheta_0 > 0,$$

and any  $T > 0$ , the system admits infinitely many (bounded) weak solutions in  $(0, T)$ .

# Convex integration - DeLellis and Shékelyhidi

## Incompressible Euler system

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x (\mathbf{v} \otimes \mathbf{v}) + \nabla_x \Pi = 0$$
$$\mathbf{v}(0, \cdot) = \mathbf{v}_0$$

## Reformulation

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \left( \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I} \right) + \nabla_x \Pi = 0$$

## Linear system vs. non-linear constitutive equation

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0$$
$$\mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I}, \quad \mathbb{U} \in R_{0, \text{sym}}^{3 \times 3}$$

# Convex integration continued

## Implicit constitutive relation

$$\lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}]$$

$$\frac{3}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] \geq \frac{1}{2} |\mathbf{v}|^2$$

$$\boxed{\frac{3}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] = \frac{1}{2} |\mathbf{v}|^2} \Leftrightarrow \mathbb{U} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I}$$

# Convex integration - subsolutions

## Equations

$\mathbf{v}, \mathbb{U}$  smooth in  $(0, T)$

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \mathbb{U} = 0$$

## Extremal values

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{v}(T, \cdot) = \mathbf{v}_T$$

## Energy

piece-wise smooth function  $e$

## Convex set

$$\frac{1}{2} |\mathbf{v}|^2 \leq \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{U}] < e \text{ in } (0, T)$$

# Oscillatory lemma

## Oscillatory increments

$$\operatorname{div}_x \mathbf{w}_\varepsilon = 0, \quad \partial_t \mathbf{w}_\varepsilon + \operatorname{div}_x \mathbf{V}_\varepsilon = 0$$

$$\mathbf{w}_\varepsilon, \mathbf{V}_\varepsilon \in C_c^\infty(Q)$$

$$\mathbf{w}_\varepsilon \rightarrow 0 \text{ weakly in } L^2(V)$$

$$\lambda_{\max} [(\mathbf{v} + \mathbf{w}_\varepsilon) \otimes (\mathbf{v} + \mathbf{w}_\varepsilon) - (\mathbb{U} + \mathbb{V}_\varepsilon)] < e$$

## Energy

$$\liminf_{\varepsilon \rightarrow 0} \int_V (|\mathbf{v} + \mathbf{w}_\varepsilon|^2) \geq \int_V |\mathbf{v}|^2 + c \int_V \left( e - \frac{1}{2} |\mathbf{v}|^2 \right)^\alpha$$

# Infinitely many solutions

## Necessary condition

There exists  $e$  such that the set of subsolutions is non-empty

## Infinitely many solutions

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x (\mathbf{v} \otimes \mathbf{v}) - \boxed{\nabla_x \left( \frac{1}{3} |\mathbf{v}|^2 \right)} = 0$$

## Pressure

$$\frac{1}{2} |\mathbf{v}|^2 = e, \quad p = -\frac{1}{3} |\mathbf{v}|^2 = -\frac{2}{3} e \text{ in } (0, T)$$



# Non-constant coefficients

## Convex set

$$\frac{1}{2} \frac{1}{r(t, x)} |\mathbf{v} + \mathbf{q}(t, x)|^2$$
$$\leq \lambda_{\max} \left[ \frac{(\mathbf{v} + \mathbf{q}(t, x)) \otimes (\mathbf{v} + \mathbf{q}(t, x))}{r(t, x)} - \mathbb{U} \right] < e \text{ in } (0, T)$$

## Equations

$$\operatorname{div}_x \mathbf{v} = 0$$
$$\partial_t (\mathbf{v} + \mathbf{q}) + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{q}) \otimes (\mathbf{v} + \mathbf{q})}{r} \right) - \frac{1}{3} \nabla_x \left( \frac{|\mathbf{v} + \mathbf{q}|^2}{r} \right) = 0$$

## Energy

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{q}(t, x)|^2}{r(t, x)} = e(t, x)$$

# Applications to the Euler-Fourier system, I.

## Ansatz

$$\varrho \mathbf{u} = \mathbf{v} + \nabla_x \Psi, \quad \operatorname{div}_x \mathbf{v} = 0$$

## Equations

$$\partial_t \varrho + \Delta \Psi = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} \right) + \nabla_x (\partial_t \Psi + \varrho \vartheta) = 0$$

$$\frac{3}{2} \left( \partial_t (\varrho \vartheta) + \operatorname{div}_x (\vartheta (\mathbf{v} + \nabla_x \Psi)) \right) - \Delta \vartheta = -\varrho \vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x \Psi}{\varrho} \right)$$

## Energy

$$e = \chi(t) - \frac{3}{2} \varrho \vartheta [\mathbf{v}] - \frac{3}{2} \partial_t \Psi$$

# Application to the Euler-Fourier system, II

## Construction of solutions

- 1 Fix  $\varrho$  and compute the acoustic potential  $\Psi$

$$-\Delta\Psi = \partial_t\varrho$$

- 2 Compute  $\vartheta = \vartheta[\mathbf{v}]$  for  $\mathbf{v} \in L^\infty$

$$\frac{3}{2} \left( \partial_t(\varrho\vartheta) + \operatorname{div}_x \left( \vartheta(\mathbf{v} + \nabla_x\Psi) \right) \right) - \Delta\vartheta = -\varrho\vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x\Psi}{\varrho} \right)$$

- 3 Observe that  $0 < \vartheta < \bar{\vartheta}$ ,  $\bar{\vartheta}$  independent of  $\mathbf{v}$

- 4 Take

$$e = \chi(t) - \frac{3}{2}\varrho\vartheta[\mathbf{v}]$$

and use the non-local variant of the results of DeLellis and Székelyhidi for the *incompressible* Euler system to find  $\mathbf{v}$

# Conservative solutions to the Euler-Fourier system

## Total energy conservation

$$\int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{3}{2} \varrho \vartheta \right) (\tau, \cdot) \, dx = \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + \frac{3}{2} \varrho_0 \vartheta_0 \right) \, dx$$

## Weak-strong uniqueness [Dafermos], [F. and Novotný]

A strong solution coincides with any conservative weak solution on their joint existence interval. Strong solutions are unique in the class of conservative weak solutions.

# Existence of conservative solutions

## Initial data

$$\varrho_0 \in C^2, \vartheta_0 \in C^2, \varrho_0 > 0, \vartheta_0 > 0$$

## Conservative weak solutions [Chiodaroli, F., Kreml [2013]]

For any regular initial data  $\varrho_0, \vartheta_0$ , there exists a velocity field  $\mathbf{u}_0$  such that the Euler-Fourier problem admits infinitely many conservative weak solutions in  $(0, T)$

# Weak formulation revisited

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\varrho \vartheta) = 0$$

## Entropy production

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) = \sigma \boxed{\geq} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta^2}$$

## Total energy conservation

$$\int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{3}{2} \varrho \vartheta \right) (\tau, \cdot) \, dx = \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + \frac{3}{2} \varrho_0 \vartheta_0 \right) \, dx$$

# Maximal dissipation criterion?

## Entropy production rate

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) = \sigma$$

$$s(\varrho, \vartheta) = -\log \left( \frac{\varrho}{\vartheta^{3/2}} \right)$$

$$\sigma \boxed{\geq} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta^2}$$

## Maximal dissipation [Dafermos 1974]

- Maximize the entropy production rate  $\sigma$
- Maximize the total entropy  $\int_{\Omega} \varrho s(\varrho, \vartheta) \, dx$
- Maximize the entropy  $\varrho s(\varrho, \vartheta)$