

# Miniworkshop on Fourier disentangling

Petr Hadrava

email: [had@sunstel.asu.cas.cz](mailto:had@sunstel.asu.cas.cz)

*Astronomical Institute, Academy of Sciences, Prague*

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# Plan of the miniworkshop

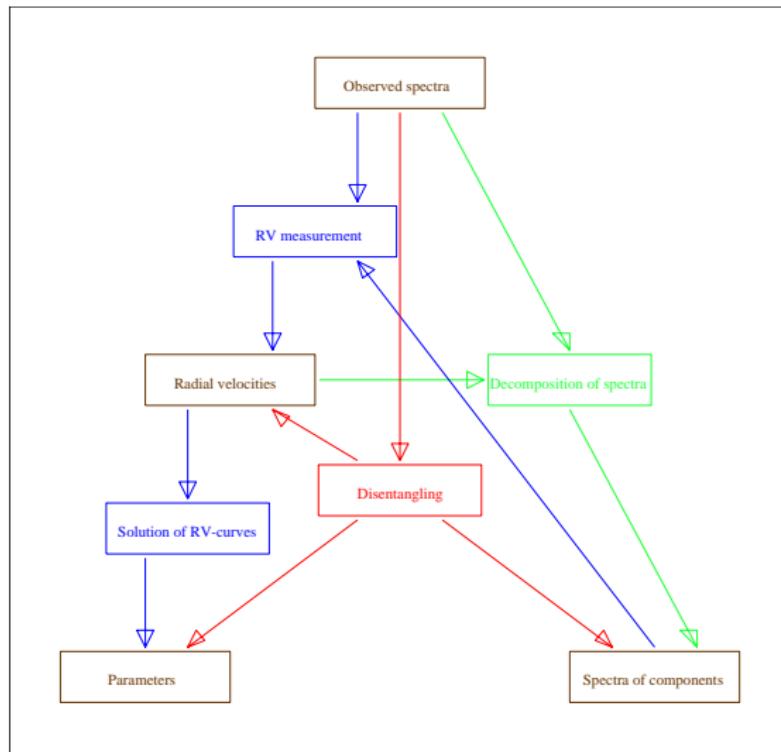
- Morning session: basis of the disentangling
  - Principle of spectra disentangling
  - Method of Fourier disentangling
  - Introduction to KOREL code
- Afternoon session: some advanced topics
  - Disentangling with line-profile variability
    - line-strength photometry
    - limb darkening
    - rotational efect
    - Cepheid pulsations
  - Disentangling with constraints
  - Super-resolution

# General preliminaries

arXiv0909.0172: "Disentangling of spectra – theory and practice"

- Disentangling of spectra = a tool for interpretation of observations of spectroscopic variables
- Any interpretation of data is dependent on theoretical model – the answer depends on question we ask
- Exploitation of all available data is preferable
- Disentangling of multiple stars = direct fit of observed spectra yielding simultaneously component spectra and parameters of the system

# Scheme of the disentangling



# Related methods

- Radial-velocity measurements
  - Classical, photoelectric with mask
  - Cross-correlation, 2-dim
  - Broadening function
  - TIRAVEL
- Decomposition of spectra
  - Subtraction (eclipsing, direct, iterative)
  - Tomographic separation
- Disentangling
  - Wavelength domain (SVD)
  - Fourier wavelength domain

# Fourier disentangling

1995 Astron. Astrophys. Suppl. 114, 393

$$x \equiv c \ln \lambda$$

$$I(x, t; p) = \sum_{j=1}^n I_j(x) * \delta(x - v_j(t; p))$$

$$\tilde{I}(y, t; p) = \sum_{j=1}^n \tilde{I}_j(y) \exp(iyv_j(t; p))$$

## LSF by a linear combination

$f(x_I) \simeq f_I, \quad f(x) \simeq \sum_j c_j g_j(x)$ :

$$0 = \delta \sum_I \left[ f_I - \sum_j c_j g_j(x_I) \right]^2$$

$$0 = 2 \sum_{kl} \left[ -f_l + \sum_j c_j g_j(x_l) \right] g_k(x_l) \delta c_k$$

$$\sum_j L_{kj} c_j \equiv \sum_j \left[ \sum_I g_k(x_I) g_j(x_I) \right] c_j = \sum_I f_I g_k(x_I) \equiv R_k$$

# Disentangling with a general broadening function

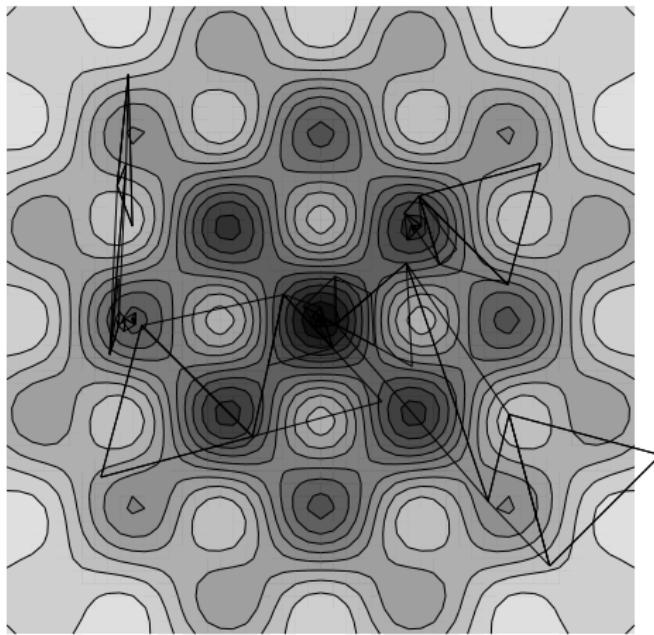
$$0 = \delta \sum_{l=1}^N \int |I(x, t_l) - \sum_{j=1}^n l_j(x) * \Delta_j(x, t_l, p)|^2 dx$$

$$0 = \delta \sum_{l=1}^N \int |\tilde{I}(y, t_l) - \sum_{j=1}^n \tilde{l}_j(y) \tilde{\Delta}_j(y, t_l, p)|^2 dy$$

$$\sum_j L_{kj}(y, p) \tilde{l}_j(y) = R_k(y, p)$$

# Simplex method

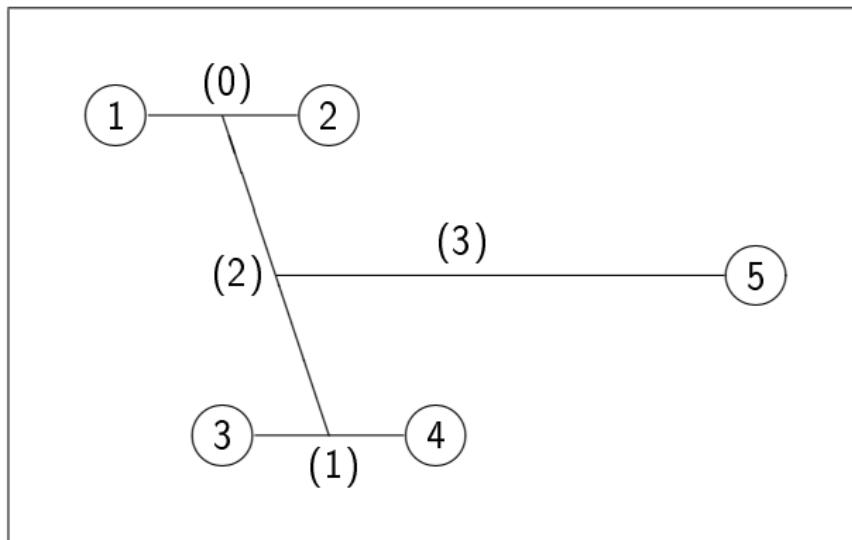
Non-linear optimization in  $p$



# KOREL code

<http://www.asu.cas.cz/had/korel.html>

<https://stelweb.asu.cas.cz/vo-korel/>



# Input for KOREL (Linux version)

- Input spectra – korel.dat

Rectified, in equidistant sampling of  $x$  ( $2^n \times 256$  pixels,  $n \geq 0$ )

```
49158.399 6540. 9. 1. 256
0.98226 0.97913 0.97816 0.9796 0.98242 0.98174 0.97786 0.97278
0.96863 0.95906 0.95437 0.95231 0.95204 0.95837 ...
```

- Controlling codes and starting approximation of parameters – korel.par

```
2 2 0 0 2 1 0 2 2 | key(1,...,5), k= Nr. of spectra>0, filter, plot
o 0 1 0 1 1 12.460326034 0.00001 | 96 Her, sum= 16.0811679
o 0 2 0 1 1 47527.278239438 0.001 = PERIASTRON EPOCH
...
```

- [Template spectra – korel.tmp]
- [Others in future]

# Relative line photometry

1997 Astron. Astrophys. Supl. 122, 581

$$\Delta_j(x, t_I, p) = s_{jI} \delta(x - v_j(t_I, p))$$

$$\delta \sum_I \int \left| \tilde{I}(y, t_I; p) - \sum_{j=1}^n \tilde{I}_j(y) s_{jI} \exp(iyv_j(t_I; p)) \right|^2 dy = 0$$

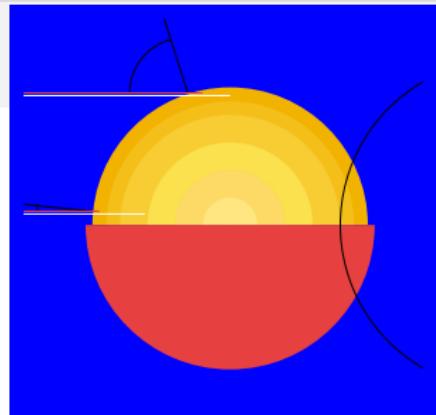
Applications:

- Eclipses, ellipticity...
- Intrinsic variability
- Telluric lines

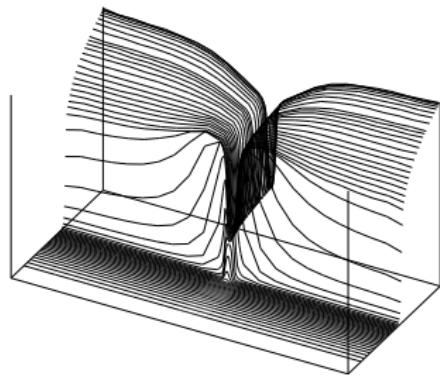
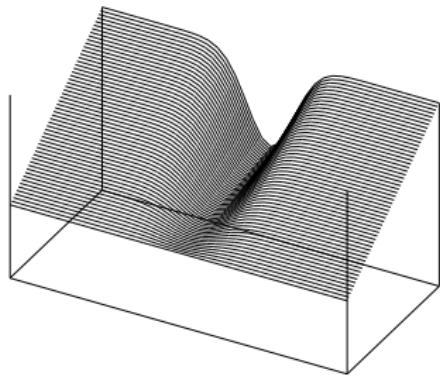
# Limb darkening

2003 ASP Conf. Ser. 288, 149

$$S_\nu(\tau_\nu) = \sum_k S_{\nu,k} \tau_\nu^k / k!$$

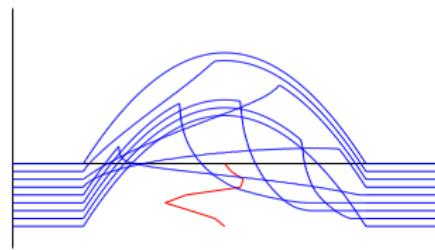
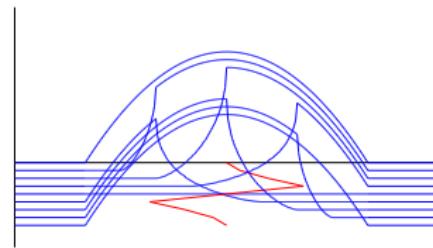
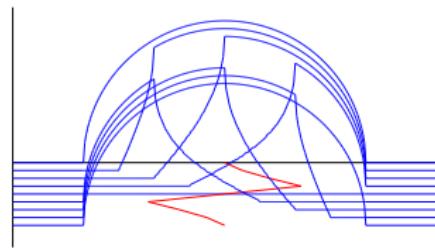


$$I_\nu(\tau = 0, \mu) = \int S_\nu(\tau_\nu) \exp(-\tau_\nu/\mu) d\tau_\nu / \mu = \sum_k S_{\nu,k} \mu^k$$



# Rotational effect

2007 ASP Conf. Ser. 370, 164

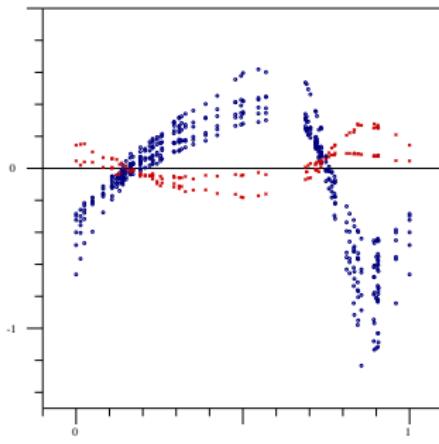
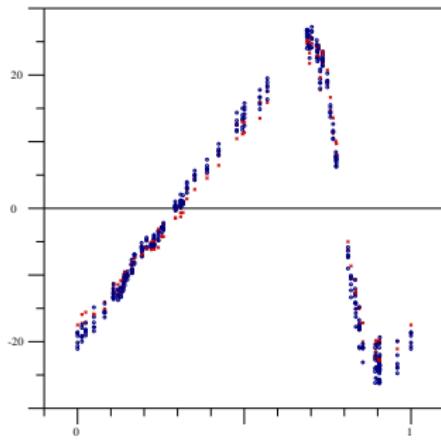
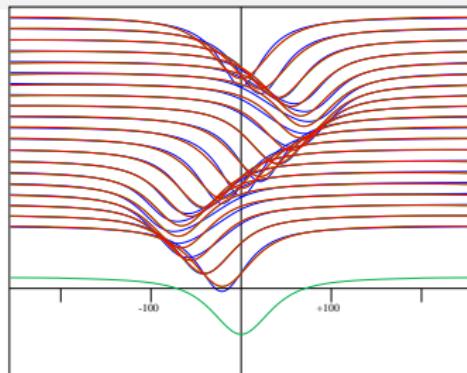


# Disentangling of Cepheid pulsations

2009 A&A 507, 397

$$\Delta^k(x, t) = \int_s \mu^{k+1} \delta(x - v(s, t)) d^2 s$$

$$= \frac{2\pi R^2}{v_p^{k+2}} [x^{k+1}]_0^{v_p}$$



# Disentangling with constraints

2006 *Astrophys. Sp. Sc.* 304, 337

Constrained spectra

$$\sum_j I_j * \Delta_j(t, p) = I(t) - \sum_j J_j * \Delta_j(t, p)$$

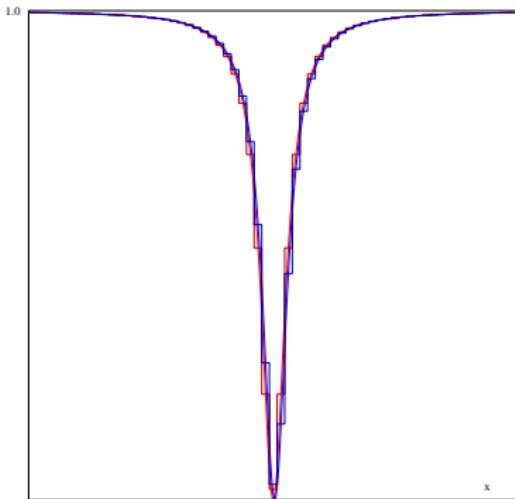
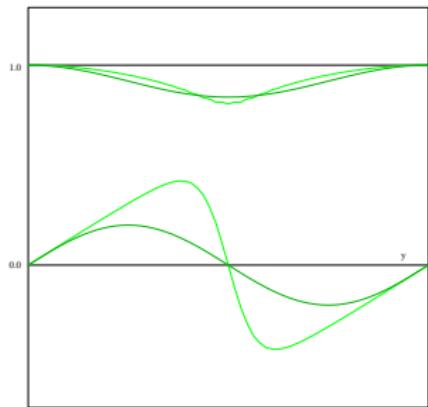
Application in KOREL: `korel.tmp`

Constrained parameters ( $F_k(p) = 0$ )

$$0 = \delta \left\{ \sum_t \int |I(t) - \sum_j I_j * \Delta_j(t, p)|^2 dx + \sum_k \lambda_k F_k^2(p) \right\}$$

# Super-resolution

2009 A&A 494, 399



$$\begin{aligned}\delta(x - v) &\simeq \delta(x) - \frac{v}{2\Delta_x}(\delta(x + \Delta_x) - \delta(x - \Delta_x)) + \\ &+ \frac{v^2}{2\Delta_x^2}(\delta(x + \Delta_x) - 2\delta(x) + \delta(x - \Delta_x)) + o(v^3)\end{aligned}$$

The end