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## $L^{q}$-solution of the Robin problem for the Oseen system

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#### Abstract

We define Oseen single layer and double layer potentials and study their properties. Using the integral equation method we prove the existence and uniqueness of an $L^{q}$-solution of the Robin problem for the Oseen system.


Keywords: Oseen equations, Robin problem, single layer potential

## 1 Introduction

The Oseen system is one of the basic system of equations in hydrodynamics. The most studied problem for the Oseen system is the Dirichlet problem (see [6], [1], [2], [3], [4]). We shall study another problem - the Robin problem for the Oseen system. (For the formulation of the problem see for example [14].) Let $\Omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$. Denote by $\mathbf{n}^{\Omega}(\mathbf{x})$ (or shortly $\mathbf{n}$ ) the outward unit normal of $\Omega$ at $\mathbf{x} \in \partial \Omega$. If $\mathbf{u}=\left(u_{1}, \ldots, u_{m}\right)$ is a velocity, and $p$ is a pressure, we define by

$$
\begin{equation*}
T(\mathbf{u}, p)=2 \hat{\nabla} \mathbf{u}-p I \tag{1}
\end{equation*}
$$

the corresponding stress tensor, where $I$ denotes the identity matrix and

$$
\hat{\nabla} \mathbf{u}=\frac{1}{2}\left[\nabla \mathbf{u}+(\nabla \mathbf{u})^{T}\right]
$$

is the deformation tensor, with $(\nabla \mathbf{u})^{T}$ as the matrix transposed to $\nabla \mathbf{u}$. Let $\lambda \in R^{1} \backslash\{0\}$ be given, $h \in L^{\infty}(\partial \Omega), h \geq 0$. We shall study the Robin problem for the Oseen system

$$
\begin{gather*}
-\Delta \mathbf{u}+2 \lambda \partial_{1} \mathbf{u}+\nabla p=0 \quad \text { in } \Omega, \quad \nabla \cdot \mathbf{u}=0 \quad \text { in } \Omega,  \tag{2}\\
T(\mathbf{u}, p) \mathbf{n}-\lambda n_{1} \mathbf{u}+h \mathbf{u}=\mathbf{g} \quad \text { on } \partial \Omega . \tag{3}
\end{gather*}
$$

(If $h \equiv 0$ we say about the Neumann problem for the Oseen system.) We shall study a so called $L^{q}$-solution of the problem (2), (3) for $\mathbf{g} \in L^{q}\left(\partial \Omega, R^{m}\right)$, i.e. the non-tangential maximal functions of $\mathbf{u}, \nabla \mathbf{u}$ and $p$ are in $L^{q}(\partial \Omega)$ and the condition (3) is fulfilled in the sense of the non-tangential limit. We use the integral equation method. We define Oseen single layer and double layer potentials and prove that they have similar properties like corresponding Stokes potentials. It is a tradition to look for a solution of the Neumann and Robin problems in the form of a single layer potential. It fails for domains with holes (similarly like for the Stokes system). So, we shall look for a solution in the form of a modified single layer potential.

The integral equation method was used for the Neumann problem for the Stokes system - i.e. for $\lambda=0$ and $h \equiv 0$ (see [22]). If $\Omega$ is bounded and $q$ is
close to 2 then the Neumann problem for the Stokes system is solvable if and only if

$$
\int_{\partial \Omega} \mathbf{g} \cdot \mathbf{w} \mathrm{d} \mathcal{H}_{2}=0
$$

for all rigid body motions w (see [22]). For the Oseen system (i.e. $\lambda \in R^{1} \backslash\{0\}$ ) we prove a totally different result:

Let $\Omega$ be bounded and $1<q<\infty, h \in L^{\infty}(\partial \Omega), h \geq 0$. If $q \neq 0$ suppose moreover that $\Omega$ has a boundary of class $\mathcal{C}^{1}$. If $\mathbf{g} \in L^{q}\left(\partial \Omega, R^{m}\right)$ then the Robin problem (2), (3) has a unique $L^{q}$-solution.

For the exterior Robin problem for the Stokes system we prove the following result:

Let $\Omega$ be an unbounded domain with compact Lipschitz boundary and $1<$ $q<\infty, h \in L^{\infty}(\partial \Omega), h \geq 0$. If $q \neq 0$ suppose moreover that $\Omega$ has a boundary of class $\mathcal{C}^{1}$. Let $\mathbf{g} \in L^{q}\left(\partial \Omega, R^{m}\right)$. If $\mathbf{u}, p$ is an $L^{q}$-solution of the Robin problem (2), (3) then there exists a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}$, $\mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. On the other hand if $p_{\infty} \in R^{1}, \mathbf{u}_{\infty} \in R^{m}$ are given then there exists a unique $L^{q}$-solution $\mathbf{u}, p$ of the Robin problem (2), (3) such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$.

## 2 Definition of the problem

Let $\Omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$. Fix $a>0$. If $\mathbf{x} \in \partial \Omega$ denote the nontangential approach regions of opening $a$ at the point $\mathbf{x}$ by

$$
\Gamma(\mathbf{x})=\Gamma_{a}(\mathbf{x})=\{\mathbf{y} \in \Omega ;|\mathbf{x}-\mathbf{y}|<(1+a) \operatorname{dist}(\mathbf{y}, \partial \Omega)\}
$$

If now $\mathbf{v}$ is a vector function defined in $\Omega$ we denote the nontangential maximal function of $\mathbf{v}$ on $\partial \Omega$ by

$$
\mathbf{v}^{*}(x)=\sup \{|\mathbf{v}(\mathbf{y})| ; \mathbf{y} \in \Gamma(\mathbf{x})\} .
$$

It is well known that if $\mathbf{v}^{*} \in L^{q}(\partial \Omega)$ for one choice of $a$, where $1 \leq q<\infty$, then it holds for arbitrary choice of $a$. (See, e.g. [11] and [26], p. 62.) Next, define the nontangential limit of $\mathbf{v}$ at $\mathbf{x} \in \partial \Omega$

$$
\mathbf{v}(\mathbf{x})=\lim _{\substack{\mathbf{y} \rightarrow \mathbf{x} \\ \mathbf{y} \in \Gamma(\mathbf{x})}} \mathbf{v}(\mathbf{y})
$$

whenever the limit exists.
Fix $\lambda \in R^{1}, 1<q<\infty, \mathbf{g} \in L^{q}\left(\partial \Omega, R^{m}\right)$, $h \in L^{\infty}(\partial \Omega)$. We say that $\mathbf{u} \in \mathcal{C}^{\infty}\left(\Omega, R^{m}\right), p \in \mathcal{C}^{\infty}(\Omega)$ is an $L^{q}$-solution of the Robin problem for the Oseen system (2), (3) if (2) holds true, $|\mathbf{u}|^{*},|\nabla \mathbf{u}|^{*}, p^{*} \in L^{q}(\partial \Omega)$, there exist the
nontangential limits of $\mathbf{u}, \nabla \mathbf{u}$ and $p$ at almost all points of $\partial \Omega$ and (3) holds in the sense of the nontangential limits at almost all points of $\partial \Omega$.

Let $\mathbf{u}, p$ be defined on $\Omega$. Denote $\omega=\{\lambda \mathbf{x} ; \mathbf{x} \in \Omega\}, \tilde{\mathbf{u}}(\mathbf{x})=(2 \lambda)^{2} \mathbf{u}(\mathbf{x} /(2 \lambda))$, $\tilde{p}(\mathbf{x})=2 \lambda p(\mathbf{x} /(2 \lambda))$. Easy calculation yields that $\mathbf{u}, p$ is an $L^{q}$-solution of the Robin problem for the Oseen system (2), (3) if and only if $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem for the Oseen system

$$
\begin{gather*}
-\Delta \tilde{\mathbf{u}}+\partial_{1} \tilde{\mathbf{u}}+\nabla \tilde{p}=0, \quad \nabla \cdot \tilde{\mathbf{u}}=0 \quad \text { in } \omega,  \tag{4}\\
T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}-\frac{1}{2} n_{1} \tilde{\mathbf{u}}+\tilde{h} \tilde{\mathbf{u}}=\tilde{\mathbf{g}} \quad \text { on } \partial \omega, \tag{5}
\end{gather*}
$$

where

$$
\begin{equation*}
\tilde{h}(\mathbf{x})=2 \lambda h(\mathbf{x} /(2 \lambda)), \quad \tilde{\mathbf{g}}(\mathbf{x})=2 \lambda \mathbf{g}(\mathbf{x} /(2 \lambda)) . \tag{6}
\end{equation*}
$$

So, we can restrict ourselves to the case $2 \lambda=1$.

## 3 Stokes potentials

Let $\mathbf{x}=\left[x_{1}, \ldots, x_{m}\right] \in R^{m}$, where $m=2,3$. Denote the ball $B(\mathbf{x} ; r)=\{\mathbf{y} \in$ $\left.R^{m} ;|\mathbf{x}-\mathbf{y}|<r\right\}$. For $0 \neq \mathbf{x} \in R^{m}$ and $j, k \in\{1, \ldots, m\}$ we define the Stokes fundamental tensor by

$$
\begin{gather*}
E_{j k}(\mathbf{x})=\frac{1}{8 \pi}\left\{\delta_{j k} \frac{1}{|\mathbf{x}|}+\frac{x_{j} x_{k}}{|\mathbf{x}|^{3}}\right\}, \quad m=3  \tag{7}\\
E_{j k}(\mathbf{x})=\frac{1}{4 \pi}\left[\delta_{j k} \ln \frac{1}{|\mathbf{x}|}+\frac{x_{j} x_{k}}{|\mathbf{x}|^{2}}\right], \quad m=2  \tag{8}\\
Q_{k}(\mathbf{x})=\frac{x_{k}}{\mathcal{H}_{m-1}(\partial B(0 ; 1))|\mathbf{x}|^{m}} \tag{9}
\end{gather*}
$$

Here $\delta_{j k}=1$ for $j=k, \delta_{j k}=0$ otherwise and $\mathcal{H}_{k}$ denotes the $k$-dimensional Hausdorff measure normalized so that $\mathcal{H}_{k}$ is the Lebesgue measure in $R^{k}$.

Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary and $\boldsymbol{\Psi} \in$ $L^{q}\left(\partial \Omega, R^{m}\right), 1<q<\infty$. Define the Stokes single layer potential with density $\Psi$ by

$$
\left(E_{\Omega} \mathbf{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} E(\mathbf{x}-\mathbf{y}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y})
$$

and the corresponding pressure by

$$
\left(Q_{\Omega} \mathbf{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} Q(\mathbf{x}-\mathbf{y}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y})
$$

whenever it makes sense. Then the couple $\left(E_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}\right) \in C^{\infty}\left(R^{m} \backslash \partial \Omega, R^{m+1}\right)$ solves the Stokes system

$$
\begin{equation*}
\Delta \mathbf{u}=\nabla p, \quad \nabla \cdot \mathbf{u}=0 \tag{10}
\end{equation*}
$$

in $R^{m} \backslash \partial \Omega$. Moreover, $E_{\Omega} \boldsymbol{\Psi}(\mathbf{x})$ is the nontangential limit of $E_{\Omega} \boldsymbol{\Psi}$ with respect to $\Omega$ and $R^{m} \backslash \bar{\Omega}$ at almost all $\mathbf{x} \in \Omega$. We have $\left(Q_{\Omega} \boldsymbol{\Psi}\right)^{*} \in L^{q}(\partial \Omega),\left|\nabla E_{\Omega} \boldsymbol{\Psi}\right|^{*} \in$ $L^{q}(\partial \Omega)$. If $\Omega$ is bounded or $m=2$ or $\int \boldsymbol{\Psi} \mathrm{d} \mathcal{H}_{m-1}=0$ then $\left|E_{\Omega} \boldsymbol{\Psi}\right|^{*} \in L^{q}(\partial \Omega)$. (See [22].) (If $\Omega \subset R^{2}$ is unbounded and $\int \boldsymbol{\Psi} \mathrm{d} \mathcal{H}_{1} \neq 0$ then $\left|E_{\Omega} \boldsymbol{\Psi}\right|^{*} \equiv \infty$ on $\partial \Omega$.)

For $\mathbf{y} \in \partial \Omega$ we define $K^{\Omega}(\cdot, \mathbf{y})=T(E(\cdot-\mathbf{y}), Q(\cdot-\mathbf{y})) \mathbf{n}^{\Omega}(\mathbf{y})$ on $R^{m} \backslash\{\mathbf{y}\}$. We have

$$
K_{j, k}^{\Omega}(\mathbf{x}, \mathbf{y})=\frac{m}{\mathcal{H}_{m-1}(\partial B(0 ; 1))} \frac{\left(y_{j}-x_{j}\right)\left(y_{k}-x_{k}\right)(\mathbf{y}-\mathbf{x}) \cdot \mathbf{n}^{\Omega}(\mathbf{y})}{|\mathbf{x}-\mathbf{y}|^{m+2}}
$$

Denote

$$
\Pi_{k}^{\Omega}(\mathbf{x}, \mathbf{y})=\frac{2}{\mathcal{H}_{m-1}(\partial B(0 ; 1))}\left\{-m \frac{\left(y_{k}-x_{k}\right)(\mathbf{y}-\mathbf{x}) \cdot \mathbf{n}^{\Omega}(\mathbf{y})}{|\mathbf{y}-\mathbf{x}|^{m+2}}+\frac{n_{k}^{\Omega}(\mathbf{y})}{|\mathbf{y}-\mathbf{x}|^{m}}\right\}
$$

For $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$ we define the Stokes double layer potential with density $\Psi$ by

$$
\left(D_{\Omega} \mathbf{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} K^{\Omega}(\mathbf{x}, \mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}), \quad \mathbf{x} \in R^{m} \backslash \partial \Omega
$$

and the corresponding pressure by

$$
\left(\Pi_{\Omega} \boldsymbol{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} \Pi^{\Omega}(\mathbf{x}-\mathbf{y}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}), \quad \mathbf{x} \in R^{m} \backslash \partial \Omega
$$

Then the pair $\left(D_{\Omega} \boldsymbol{\Psi}, \Pi_{\Omega} \boldsymbol{\Psi}\right) \in C^{\infty}\left(R^{m} \backslash \partial \Omega\right)^{m+1}$ solves the Stokes system (10) in $R^{m} \backslash \partial \Omega$. For $\mathbf{x} \in \partial \Omega$ we denote

$$
\begin{aligned}
& \left(K_{\Omega} \mathbf{\Psi}\right)(\mathbf{x})=\lim _{\delta \downarrow 0} \int_{\partial \Omega \backslash B(\mathbf{x}, \delta)} K^{\Omega}(\mathbf{x}, \mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}), \\
& \left(K_{\Omega}^{\prime} \mathbf{\Psi}\right)(\mathbf{x})=\lim _{\delta \downarrow 0} \int_{\partial \Omega \backslash B(\mathbf{x}, \delta)} K^{\Omega}(\mathbf{y}, \mathbf{x}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) .
\end{aligned}
$$

Then $K_{\Omega}, K_{\Omega}^{\prime}$ are bounded linear operators on $L^{q}\left(\partial \Omega, R^{m}\right)$. Moreover, there exist the non-tangential limits of $\nabla E_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}$ and $D_{\Omega} \boldsymbol{\Psi}$ at almost all points of $\partial \Omega$. If we denote by $[f]_{+}$the non-tangential limit of $f$ with respect to $\Omega$ and by $[f]_{-}$the non-tangential limit of $f$ with respect to $R^{m} \backslash \bar{\Omega}$, then

$$
\begin{gather*}
{\left[D_{\Omega} \boldsymbol{\Psi}\right]_{ \pm}(\mathbf{x})= \pm \frac{1}{2} \boldsymbol{\Psi}(\mathbf{z})+K_{\Omega} \boldsymbol{\Psi}(\mathbf{z}),}  \tag{11}\\
{\left[T\left(E_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}\right)\right]_{ \pm} \mathbf{n}^{\Omega}= \pm \frac{1}{2} \boldsymbol{\Psi}-K_{\Omega}^{\prime} \boldsymbol{\Psi} .} \tag{12}
\end{gather*}
$$

(See [22].)

## 4 Oseen fundamental tensor

If $O_{j k}(\mathbf{x}), Z_{j}(\mathbf{x})$ are tempered distributions then $O_{j k}, Z_{j}$ is called a fundamental tensor for the Oseen equation (4) in $R^{m}, m=2,3$, if

$$
\begin{gathered}
-\Delta O_{j k}+\partial_{1} O_{j k}+\partial_{j} Z_{k}(\cdot)=\delta_{j k} \\
\partial_{1} O_{1 k}+\ldots+\partial_{m} O_{m k}=0
\end{gathered}
$$

for $j, k=1, \ldots, m$. We are interested in fundamental tensors such that $O_{j k}(\mathbf{x}) \rightarrow$ $0, Z_{j}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$. The existence of such fundamental tensor was proved in [10], §VII.3. The explicit formula of the fundamental tensor of the Oseen system is very complicated. We only gather properties of the fundamental tensor (see [10] or [24]): We have $O_{j k}=O_{k j} \in \mathcal{C}^{\infty}\left(R^{m} \backslash\{0\}\right.$ ),

$$
\begin{equation*}
Z_{k}(\mathbf{x})=Q_{k}(\mathbf{x}) \tag{13}
\end{equation*}
$$

If $\beta$ is a multi-index, then we have

$$
\begin{equation*}
\partial^{\beta} O_{j k}(\mathbf{x}) \mid=O\left(|\mathbf{x}|^{(1-m-|\beta|) / 2}\right) \quad \text { as }|\mathbf{x}| \rightarrow \infty \tag{14}
\end{equation*}
$$

If $|\mathbf{z}| \neq\left|z_{1}\right|$ then

$$
\begin{equation*}
\lim _{r \rightarrow \infty}|O(r \mathbf{z})| r^{(m-1) / 2}=0 \tag{15}
\end{equation*}
$$

If $r>0$ and $q>1+1 / m$ then we have

$$
\begin{equation*}
\left|\nabla O_{j k}\right| \in L^{q}\left(R^{m} \backslash B(0 ; r)\right) \tag{16}
\end{equation*}
$$

Denote

$$
\begin{equation*}
R_{j k}(\mathbf{x})=O_{j k}(\mathbf{x})-E_{j k}(\mathbf{x}) \tag{17}
\end{equation*}
$$

If $m=3$ then

$$
\begin{equation*}
\left|\partial^{\alpha} R(\mathbf{x})\right|=O\left(|x|^{-|\alpha|}\right) \quad \text { as }|\mathbf{x}| \rightarrow 0 . \tag{18}
\end{equation*}
$$

If $m=2$ then

$$
\begin{gather*}
|R(\mathbf{x})|=O(1) \quad \text { as }|\mathbf{x}| \rightarrow 0  \tag{19}\\
|\nabla R(\mathbf{x})|=O(\ln |\mathbf{x}|) \quad \text { as }|\mathbf{x}| \rightarrow 0  \tag{20}\\
\left|\partial^{\alpha} R(\mathbf{x})\right|=O\left(|x|^{-|\alpha|+1}\right) \quad \text { as }|\mathbf{x}| \rightarrow 0 \quad \text { for }|\alpha| \geq 2 \tag{21}
\end{gather*}
$$

Lemma 4.1. If $\lambda \neq 0$ and $u_{1}, \ldots, u_{m}, p$ are tempered distributions in $R^{m}$ satisfying (2) in $R^{m}$ in the sense of distributions, then $u_{1}, \ldots, u_{m}, p$ are polynomials.

Proof. For $R^{3}$ [15], Proposition 6.1. The proof is literally the same for other dimensions.
Corollary 4.2. Let $m=2$ or $m=3$. Then there exists a unique fundamental tensor $O_{j k}(\mathbf{x}), Z_{j}(\mathbf{x})$ for the Oseen equation (4) in $R^{m}$ such that $O_{j k}(\mathbf{x}) \rightarrow 0$, $Z_{j}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$.

Proof. If $\tilde{O}_{j k}(\mathbf{x}), \tilde{Z}_{j}(\mathbf{x})$ is another such fundamental tensor then $\tilde{O}_{j k}-O_{j k}$, $\tilde{Z}_{j}-Z_{j}$ is a solution of the equation (4) in $R^{m}$. Lemma 4.1 gives that $\tilde{O}_{j k}-O_{j k} \equiv$ $0, \tilde{Z}_{j}-Z_{j} \equiv 0$.

## 5 Oseen potentials

Let $\Omega \subset R^{m}$ be an open set with Lipschitz boundary, $m=2$ or $m=3$. For $\Psi \in L^{q}\left(\partial \Omega, R^{m}\right)$ with $1<q<\infty$ define the Oseen single layer potential with density $\boldsymbol{\Psi}$

$$
O_{\Omega} \boldsymbol{\Psi}(\mathbf{x})=\int_{\partial \Omega} O(\mathbf{x}-\mathbf{y}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y})
$$

Clearly $O_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}$ is a solution of the Oseen equation (4) in $R^{m} \backslash \partial \Omega$. Denote

$$
R_{\Omega} \boldsymbol{\Psi}(\mathbf{x})=\int_{\partial \Omega} R(\mathbf{x}-\mathbf{y}) \boldsymbol{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y})=O_{\Omega} \mathbf{\Psi}(\mathbf{x})-E_{\Omega} \mathbf{\Psi}(\mathbf{x})
$$

For $\mathbf{y} \in \partial \Omega$ and $\mathbf{x} \in R^{m} \backslash\{\mathbf{y}\}$ define $K^{\Omega, O s}(\cdot, \mathbf{y})=T\left(O\left(\cdot-\mathbf{y}, Q(\cdot-\mathbf{y}) \mathbf{n}^{\Omega}(\mathbf{y})-\right.\right.$ $n_{1}^{\Omega} O(\cdot-\mathbf{y}) / 2$, i.e.

$$
\begin{align*}
K_{j, k}^{\Omega, O s}(\mathbf{x}, \mathbf{y})= & \mathbf{n}^{\Omega}(\mathbf{y}) \cdot \nabla_{\mathbf{y}} O_{j k}(\mathbf{x}-\mathbf{y})+\sum_{i=1}^{m} n_{i}^{\Omega}(\mathbf{y}) \frac{\partial}{\partial y_{k}} O_{j i}(\mathbf{x}-\mathbf{y})  \tag{22}\\
& +n_{k}^{\Omega}(\mathbf{y}) Q_{j}(\mathbf{x}-\mathbf{y})+\frac{n_{1}^{\Omega}(\mathbf{y})}{2} O_{j k}(\mathbf{x}-\mathbf{y}) \tag{23}
\end{align*}
$$

Denote

$$
\begin{align*}
\Pi_{k}^{\Omega, O s}(\mathbf{x}, \mathbf{y})= & \mathbf{n}^{\Omega}(\mathbf{y}) \cdot \nabla_{\mathbf{y}} Q_{k}(\mathbf{x}-\mathbf{y})+\sum_{i=1}^{m} n_{i}^{\Omega}(\mathbf{y}) \frac{\partial}{\partial y_{k}} Q_{i}(\mathbf{x}-\mathbf{y})  \tag{24}\\
& -n_{k}^{\Omega}(\mathbf{y}) Q_{1}(\mathbf{x}-\mathbf{y})+\frac{n_{1}^{\Omega}(\mathbf{y})}{2} Q_{k}(\mathbf{x}-\mathbf{y}) \tag{25}
\end{align*}
$$

For $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$ we define the Oseen double layer potential with density $\Psi$ by

$$
\left(D_{\Omega}^{O s} \mathbf{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} K^{\Omega, O s}(\mathbf{x}, \mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}), \quad \mathbf{x} \in R^{m} \backslash \partial \Omega
$$

and the corresponding pressure by

$$
\left(\Pi_{\Omega}^{O s} \mathbf{\Psi}\right)(\mathbf{x})=\int_{\partial \Omega} \Pi^{\Omega, O s}(\mathbf{x}-\mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}), \quad \mathbf{x} \in R^{m} \backslash \partial \Omega
$$

For $\mathbf{x} \in \partial \Omega$ we denote

$$
\left(K_{\Omega, O s} \mathbf{\Psi}\right)(\mathbf{x})=\lim _{\delta \downarrow 0} \int_{\partial \Omega \backslash B(\mathbf{x}, \delta)} K^{\Omega, O s}(\mathbf{x}, \mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) .
$$

$$
\left(K_{\Omega, O s}^{\prime} \Psi\right)(\mathbf{x})=\lim _{\delta \downarrow 0} \int_{\partial \Omega \backslash B(\mathbf{x}, \delta)} K^{\Omega, O s}(\mathbf{y}, \mathbf{x}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) .
$$

Lemma 5.1. Let $m \in N$. Then there exists a constant $C$ such that for all Borel measurable function $f$, and $\mathbf{x} \in R^{m}, r>0,0<\alpha<m, \beta>0$

$$
\int_{B(\mathbf{x} ; r)} \frac{|f(\mathbf{y})|}{|\mathbf{x}-\mathbf{y}|^{m-\alpha}} \mathrm{d} \mathcal{H}_{m}(\mathbf{y}) \leq C r^{\alpha} M f(x)
$$

where

$$
M f(\mathbf{x})=\sup _{r>0} \int_{B(\mathbf{x} ; r)} \frac{|f(\mathbf{y})|}{\mathcal{H}_{m}(B(0 ; r))} \mathrm{d} \mathcal{H}_{m}(\mathbf{y})
$$

(See [28], Lemma 2.8.3.)
Proposition 5.2. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary. Let $\mathcal{K}$ be a function defined on $\bar{\Omega} \times \partial \Omega$. Suppose that $\mathcal{K}(\mathbf{x}, \cdot)$ is Borel measurable, $\mathcal{K}(\cdot, \mathbf{y})$ is continuous on $\bar{\Omega} \backslash\{\mathbf{y}\}$ for all $\mathbf{y} \in \partial \Omega$ and $|\mathcal{K}(\mathbf{x}, \mathbf{y})| \leq$ $C_{1}|\mathbf{x}-\mathbf{y}|^{\alpha+1-m}$ with $0<\alpha<m-1$. For $f \in L^{q}(\partial \Omega), 1<q<\infty$ define

$$
\begin{equation*}
\mathcal{K} f(\mathbf{x})=\int_{\partial \Omega} \mathcal{K}(\mathbf{x}, \mathbf{y}) f(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) \tag{26}
\end{equation*}
$$

Then there exists a constant $C_{2}$ dependent on $\Omega, q$ and $\alpha$ such that

$$
\left\|(\mathcal{K} f)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C_{2}\|f\|_{L^{q}(\partial \Omega)}
$$

$\mathcal{K} f$ is finite almost everywhere on $\partial \Omega, \mathcal{K} f(\mathbf{x})$ is the nontangential limit of $\mathcal{K} f$ for almost all $\mathbf{x} \in \partial \Omega$ and $\|\mathcal{K} f\|_{L^{q}(\partial \Omega)} \leq C_{2}\|f\|_{L^{q}(\partial \Omega)}$.

Proof. There are $\mathbf{z}^{1}, \ldots, \mathbf{z}^{k} \in \partial \Omega$ and $\delta>0$ such that $\partial \Omega \subset B\left(\mathbf{z}^{1} ; \delta\right) \cup \ldots \cup$ $B\left(\mathbf{z}^{k} ; \delta\right)$ and for each $j \in\{1, \ldots, k\}$ there is a coordinate system centered at $\mathbf{z}^{j}$ and a Lipschitz continuous function $\varphi^{j}$ such that $B(0 ; 2 \delta) \cap \Omega=\left\{\left[\mathbf{x}^{\prime}, x_{m}\right] \in\right.$ $\left.B(0 ; 2 \delta) ; x_{m}>\varphi^{j}\left(\mathbf{x}^{\prime}\right)\right\}$. Choose a constant $L$ such that $\left|\nabla \varphi^{j}\right| \leq L$. Let $\mathbf{z} \in \partial \Omega$. Choose $j$ such that $\mathbf{z} \in B\left(\mathbf{z}^{j} ; \delta\right)$. Let $\mathbf{x} \in \Gamma(\mathbf{z})$. If $|\mathbf{x}-\mathbf{z}| \geq \delta$ then $\operatorname{dist}(\mathbf{x}, \partial \Omega) \geq$ $\delta /(1+a)$ and

$$
|\mathcal{K} f(\mathbf{x})| \leq C_{1}\left(\frac{\delta}{1+a}\right)^{\alpha+1-m}\|f\|_{L^{1}(\partial \Omega)} \leq C_{3}\|f\|_{L^{q}(\partial \Omega)}
$$

where $C_{3}=C_{1}[\delta /(1+a)]^{\alpha+1-m} \mathcal{H}_{m-1}(\partial \Omega)^{(p-1) / p}$. Let now $|\mathbf{x}-\mathbf{z}|<\delta$. For $\tilde{\sim}^{0}<r \leq 1$ put $f_{r}=f$ on $\partial \Omega \cap B\left(\mathbf{z}^{j}, 2 r \delta\right), f_{r}=0$ elsewhere, $g_{r}=f-f_{r}$, $\tilde{f}_{1}\left(\mathbf{x}^{\prime}\right)=f_{1}\left(\mathbf{x}^{\prime}, \varphi^{j}\left(x^{\prime}\right)\right)$. Then

$$
\left|\mathcal{K} g_{1}(\mathbf{x})\right| \leq C_{1} \delta^{\alpha+1-m}\left\|g_{1}\right\|_{L^{1}(\partial \Omega)} \leq C_{3}\|f\|_{L^{q}(\partial \Omega)}
$$

If $\mathbf{y} \in \partial \Omega$ then $|\mathbf{z}-\mathbf{y}| \leq|\mathbf{z}-\mathbf{x}|+|\mathbf{y}-\mathbf{x}| \leq(1+a)|\mathbf{y}-\mathbf{x}|+|\mathbf{y}-\mathbf{x}|$. According to Lemma 5.1 there exists a constant $C_{4}$ such that

$$
\begin{aligned}
& \max \left(\left|\mathcal{K} f_{r}(\mathbf{z})\right|,\left|\mathcal{K} f_{r}(\mathbf{x})\right|\right) \leq \int_{B\left(\mathbf{z}^{j} ; r 2 \delta\right)} C_{1}\left(\frac{|\mathbf{y}-\mathbf{z}|}{2+a}\right)^{\alpha+1-m}|f(\mathbf{y})| \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) \\
\leq & \int_{\left\{\mathbf{y}^{\prime} \in R^{m-1} ;\left|\mathbf{y}^{\prime}\right|<r 2 \delta\right\}} C_{1}\left(\frac{\left|\mathbf{y}^{\prime}\right|}{2+a}\right)^{\alpha+1-m}\left|\tilde{f}_{1}\left(\mathbf{y}^{\prime}\right)\right| \sqrt{1+L^{2}} \mathrm{~d} \mathcal{H}_{m-1} \leq C_{4} r^{\alpha} M \tilde{f}_{1}\left(\mathbf{z}^{\prime}\right) .
\end{aligned}
$$

Thus $(\mathcal{K} f)^{*}(\mathbf{z}) \mid \leq C_{3}\|f\|_{L^{q}(\partial \Omega)}+C_{4} M \tilde{f}_{1}(\mathbf{z})$. Since there exists a constant $C_{5}$ such that $\|M g\|_{L^{q}} \leq C_{5}\|g\|_{L^{q}}$ (see [28], Theorem 2.8.2), we have $\left\|(\mathcal{K} f)^{*}\right\|_{L^{q}(\partial \Omega)} \leq$ $C_{3}\|f\|_{L^{q}(\partial \Omega)}+C_{4} C_{5}\left\|\tilde{f}_{1}\right\|_{L^{q}} \leq\left(C_{3}+C_{4} C_{5}\right)\|f\|_{L^{q}(\partial \Omega)}$.

Let $\mathbf{z}=\left[\mathbf{z}^{\prime}, z_{m}\right]$ be as above. We use the same notation. $M \tilde{f}_{1}$ is finite at almost all points of $\mathbf{x}^{\prime}$ with $\left|\mathbf{x}^{\prime}\right|<\delta$. Suppose that $M \tilde{f}_{1}\left(\mathbf{z}^{\prime}\right)<\infty$. Fix $\epsilon>0$. We can choose $0<r \leq 1$ such that $C_{4} r^{\alpha} M \tilde{f}_{1}\left(\mathbf{z}^{\prime}\right)<\epsilon / 3$. Then $\left|\mathcal{K} f_{r}(\mathbf{z})\right|<\epsilon / 3$. If $\mathbf{x} \in \Gamma(\mathbf{z}),|\mathbf{x}-\mathbf{z}|<\delta$ then $\left|\mathcal{K} f_{r}(\mathbf{z})\right|<\epsilon / 3$. Since $\mathcal{K} g_{r}$ is continuous in $\mathbf{z}$ by the Theorem on continuity of parametrized integrals there exist $\rho \in(0, \delta)$ such that $\left|\mathcal{K} g_{r}(\mathbf{x})-\mathcal{K} g_{r}(\mathbf{z})\right|<\epsilon / 3$ for $|\mathbf{x}-\mathbf{z}|<\rho$. If $\mathbf{x} \in \Gamma(\mathbf{z}),|\mathbf{x}-\mathbf{z}|<\rho$ then $|\mathcal{K} f(\mathbf{x})-\mathcal{K} f(\mathbf{z})| \leq\left|\mathcal{K} g_{r}(\mathbf{x})-\mathcal{K} g_{r}(\mathbf{z})\right|+\left|\mathcal{K} f_{r}(\mathbf{x})\right|+\left|\mathcal{K} f_{r}(\mathbf{z})\right|<\epsilon$.

By virtue of limit

$$
\|\mathcal{K} f\|_{L^{q}(\partial \Omega)} \leq\left\|(\mathcal{K} f)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C_{2}\|f\|_{L^{q}(\partial \Omega)}
$$

Proposition 5.3. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$, and $1<q<\infty$. If $\mathbf{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$ then $O_{\Omega} \boldsymbol{\Psi}(\mathbf{z})$ it the non-tangential limit of $O_{\Omega} \mathbf{\Psi}$ at $\mathbf{z}$ for almost all $\mathbf{z} \in \partial \Omega$. There exists a constant $C$ such that $\left\|\left(O_{\Omega} \boldsymbol{\Psi}\right)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$. The operator $O_{\Omega}$ is a compact bounded linear operator in $L^{q}\left(\partial \Omega, R^{m}\right)$.

Proof. For $\mathbf{x} \in \partial \Omega$ denote

$$
M_{1}(\mathbf{f})(\mathbf{x})=\sup \{|\mathbf{f}(\mathbf{y})| ; \mathbf{y} \in \Gamma(\mathbf{x}) \cap B(\mathbf{x} ; 1)\}
$$

According to [22] there exists a constant $C_{1}$ such that $\left\|M_{1}\left(E_{\Omega} \boldsymbol{\Psi}\right)\right\|_{L^{q}(\partial \Omega)} \leq$ $C_{1}\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$ for $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$. Moreover, if $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$ then $E_{\Omega} \boldsymbol{\Psi}(\mathbf{z})$ it the non-tangential limit of $E_{\Omega} \boldsymbol{\Psi}$ at $\mathbf{z}$ for almost all $\mathbf{z} \in \partial \Omega$. Since there exists a constant $C_{2}$ such that $|R(\mathbf{y})| \leq C_{2}$ for $|\mathbf{y}| \leq 1+\operatorname{diam} \partial \Omega$, Proposition 5.2 gives that $O_{\Omega} \boldsymbol{\Psi}(\mathbf{z})$ it the non-tangential limit of $O_{\Omega} \mathbf{\Psi}$ at $\mathbf{z}$ for almost all $\mathbf{z} \in \partial \Omega$, and there exists a constant $C_{3}$ such that $\left\|M_{1}\left(O_{\Omega} \boldsymbol{\Psi}\right)\right\|_{L^{q}(\partial \Omega)} \leq C_{3}\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$ for $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$. Since $O_{j k}(\mathbf{y}) \rightarrow 0$ as $|\mathbf{y}| \rightarrow \infty$, there exists a constant $C_{4}$ such that $\left\|\left(O_{\Omega} \boldsymbol{\Psi}\right)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C_{4}\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$ for $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$.

The operator $E_{\Omega}$ is a compact linear operator on $L^{q}\left(\partial \Omega, R^{m}\right)$ by [22]. Since $R(\mathbf{x}-\mathbf{y})$ is bounded on $\partial \Omega \times \partial \Omega$, the operator $R_{\Omega}$ is a compact linear operator on $L^{q}\left(\partial \Omega, R^{m}\right)$ by [9], $\S 4.5 .2$, Satz 2.

Lemma 5.4. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$, and $1<q<\infty$. If $\Psi \in L^{q}\left(\partial \Omega, R^{m}\right)$ and $j \in\{1, \ldots, m\}$ then

$$
\begin{equation*}
\partial_{j} R \Psi(\mathbf{x})=\lim _{\epsilon \downarrow 0} \int_{\partial \Omega \backslash B(\mathbf{x} ; \epsilon)} \partial_{j} R(\mathbf{x}-\mathbf{y}) \mathbf{\Psi}(\mathbf{y}) \mathrm{d} \mathcal{H}_{m-1}(\mathbf{y}) \tag{27}
\end{equation*}
$$

for $\mathbf{x} \in R^{m} \backslash \partial \Omega$. Define $\partial_{j} R \mathbf{\Psi}(\mathbf{x})$ by the limit (27) whenever this limit makes sense. Then $\partial_{j} R$ is a compact linear operator on $L^{q}\left(\partial \Omega, R^{m}\right)$. There exists a constant $C$ such that if $\Psi \in L^{q}\left(\partial \Omega, R^{m}\right)$ then

$$
\left\|\left(\partial_{j} R \Psi\right)^{*}\right\|_{L^{q}(\partial \Omega)} \leq\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}
$$

and $\partial_{j} R \Psi(\mathbf{x})$ is the non-tangential limit of $\partial_{j} R \Psi$ at almost all $\mathbf{x} \in \partial \Omega$.
Proof. Since there exists a constant $C_{1}$ such that $\left|\partial_{j} R(\mathbf{x}-\mathbf{y})\right| \leq C_{1} \mid \mathbf{x}-$ $\left.\mathbf{y}\right|^{1-m-1 / 2}$, the lemma is an easy consequence of Proposition 5.2.

Proposition 5.5. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$, and $1<q<\infty$. Then $K_{\Omega, O s}^{\prime}$ is a bounded linear operator on $L^{q}\left(\partial \Omega, R^{m}\right)$. If $\boldsymbol{\Psi} \in L^{q}(\partial \Omega)$ then $\left\|\left(\nabla O_{\Omega} \boldsymbol{\Psi}\right)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$ with $C$ dependent only on $\Omega$ and $q, \nabla O_{\Omega} \Psi$ has a non-tangential limit at almost all points of $\partial \Omega$, and

$$
\left[T\left(O_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}\right)\right]_{ \pm} \mathbf{n}^{\Omega}-\frac{1}{2} n_{1}^{\Omega} O_{\Omega} \boldsymbol{\Psi}= \pm \frac{1}{2} \boldsymbol{\Psi}-K_{\Omega, O s}^{\prime} \boldsymbol{\Psi}
$$

Proof. The proposition is an easy consequence of (12), Lemma 5.4 and Lemma 5.3.
Lemma 5.6. $\nabla \cdot Q=0,-\Delta Q+\partial_{1} Q-\nabla Q_{1}=0$ in $R^{m} \backslash\{0\}$ in the sense of distributions.

Proof. Denote $h_{\text {Lap }}(\mathbf{x})=-(2 \pi)^{-1} \ln |\mathbf{x}|$ for $m=2, h_{\text {Lap }}(\mathbf{x})=(4 \Pi)^{-1}|\mathbf{x}|$ for $m=3$. Then $h_{\text {Lap }}$ is a fundamental solution for the Laplace equation. We have $Q=-\nabla h_{\text {Lap }}$. Thus

$$
\begin{gathered}
\nabla \cdot Q=-\Delta h_{L a p}=0 \\
-\Delta Q_{j}+\partial_{1} Q_{j}=\Delta \partial_{j} h_{L a p}-\partial_{1} \partial_{j} h_{L a p}=\partial_{j}\left(\Delta h_{L a p}-\partial_{1} h_{L a p}\right)=\partial_{j} Q_{1}
\end{gathered}
$$

Proposition 5.7. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$, and $1<q<\infty$. If $\boldsymbol{\Psi} \in L^{q}\left(\partial \Omega, R^{m}\right)$ then $D_{\Omega}^{O s} \boldsymbol{\Psi}, \Pi_{\Omega}^{O s} \boldsymbol{\Psi}$ is a solution of the Oseen system (4) in $R^{m} \backslash \partial \Omega$.

Proof. If $\mathbf{y} \in \partial \Omega, k \in\{1, \ldots, m\}$ then $\left[K_{1, k}^{\Omega, O s}(\mathbf{x}, \mathbf{y}), \ldots, K_{m, k}^{\Omega, O s}(\mathbf{x}, \mathbf{y}), \Pi_{k}(\mathbf{x}, \mathbf{y})\right]$ is a solution of the Oseen system (4) in $R^{m} \backslash\{\mathbf{y}\}$ by Lemma 5.6. So, $D_{\Omega}^{O s} \boldsymbol{\Psi}$, $\Pi_{\Omega}^{O s} \mathbf{\Psi}$ is a solution of the Oseen system (4) in $R^{m} \backslash \partial \Omega$.

Proposition 5.8. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$, and $1<q<\infty$. Then $K_{\Omega, O s}$ is a bounded linear operator on $L^{q}\left(\partial \Omega, R^{m}\right)$. If $\boldsymbol{\Psi} \in L^{q}(\partial \Omega)$ then $\left\|\left(D_{\Omega}^{O s} \boldsymbol{\Psi}\right)^{*}\right\|_{L^{q}(\partial \Omega)} \leq C\|\boldsymbol{\Psi}\|_{L^{q}(\partial \Omega)}$ with $C$ dependent only on $\Omega$ and $q, D_{\Omega}^{O s} \boldsymbol{\Psi}$ has a non-tangential limit at almost all points of $\partial \Omega$, and

$$
\left.\left[D_{\Omega}^{O s} \mathbf{\Psi}\right)\right]_{ \pm} \mathbf{n}^{\Omega}= \pm \frac{1}{2} \boldsymbol{\Psi}+K_{\Omega, O s} \boldsymbol{\Psi}
$$

Proof. The proposition is an easy consequence of (11), Lemma 5.3 and Lemma 5.4.
Proposition 5.9. Let $\omega \subset R^{m}$ be a bounded domain with Lipschitz boundary, $\tilde{h} \equiv 0, \tilde{\mathbf{g}} \in L^{q}\left(\partial \Omega, R^{m}\right), 1<q<\infty, m=2$ or $m=3$. If $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Neumann problem (4), (5) then

$$
\begin{equation*}
\tilde{\mathbf{u}}=O_{\omega} \tilde{\mathbf{g}}+D_{\omega}^{O s} \tilde{\mathbf{u}}, \quad \tilde{p}=Q_{\omega} \tilde{\mathbf{g}}+\Pi_{\omega}^{O s} \tilde{\mathbf{u}} \tag{28}
\end{equation*}
$$

Proof. Let $\Omega(j)$ be domains from Lemma 6.1. Green's formula gives (28) for $\Omega(j)$ (see [10], §VII.6). By virtue of Lebesgue lemma be obtain (28) for $\omega$.

## 6 Regular $L^{2}$-solution of the Dirichlet problem

Let $\omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$, $\mathbf{g} \in W^{1,2}(\partial \omega)$. We say that $\tilde{\mathbf{u}} \in \mathcal{C}^{2}\left(\Omega, R^{m}\right), \tilde{p} \in \mathcal{C}^{1}(\Omega)$ is a regular $L^{2}$-solution of the Dirichlet problem (4),

$$
\begin{equation*}
\tilde{\mathbf{u}}=\mathbf{g} \quad \text { on } \partial \omega \tag{29}
\end{equation*}
$$

if $\tilde{\mathbf{u}}, \tilde{p}$ is a solution of the Oseen system (4) in $\omega$, the non-tangential maximal functions $(|\tilde{\mathbf{u}}|)^{*},(|\nabla \tilde{\mathbf{u}}|)^{*}, \tilde{p}^{*} \in L^{2}(\partial \omega)$, there exist the non-tangential limits of $\tilde{\mathbf{u}}, \nabla \tilde{\mathbf{u}}, \tilde{p}$ at almost all points of $\partial \omega$, and the Dirichlet condition (29) is fulfilled in the sense of the non-tangential limit at almost all points of $\partial \omega$.

If $\omega$ is a bounded open set with connected boundary we shall look for a solution in the form of an Oseen single layer potential $\tilde{\mathbf{u}}=O_{\omega} \boldsymbol{\Psi}, \tilde{p}=Q_{\omega} \boldsymbol{\Psi}$ with $\boldsymbol{\Psi} \in L^{2}\left(\partial \omega, R^{m}\right)$. Let now $G(1), \ldots, G(k)$ be all bounded components of $R^{m} \backslash \bar{\omega}$. If $k \in N$ we cannot look for a solution of this problem in this form because

$$
\begin{equation*}
\int_{\partial G(j)}\left(O_{\omega} \boldsymbol{\Psi}\right) \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=0 \tag{30}
\end{equation*}
$$

by the Divergence theorem. But this is not a necessary condition for the solvability of the problem. Fix open balls $B(j)$ such that $\bar{B}(j) \subset G(j)$. We shall
look for a solution of the Dirichlet problem (4), (29) in the form of a modified Oseen single layer potential

$$
\begin{align*}
& \tilde{\mathbf{u}}=O_{\omega} \boldsymbol{\Psi}+\sum_{j=1}^{k}\left(D_{B(j)}^{O s} \mathbf{n}^{B(j)}\right) \int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1},  \tag{31}\\
& \tilde{p}=Q_{\omega} \boldsymbol{\Psi}+\sum_{j=1}^{k}\left(\Pi_{B(j)}^{O s} \mathbf{n}^{B(j)}\right) \int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}^{\Omega} \mathrm{d} \mathcal{H}_{m-1} \tag{32}
\end{align*}
$$

with $\boldsymbol{\Psi} \in L^{2}\left(\partial \omega, R^{m}\right)$.
Lemma 6.1. If $\Omega \subset R^{m}$ is a bounded domain with Lipschitz boundary then there is a sequence of domains $\Omega_{j}$ with boundaries of class $C^{\infty}$ such that

- $\bar{\Omega}_{j} \subset \Omega$.
- There are $a>0$ and homeomorphisms $\Lambda_{j}: \partial \Omega \rightarrow \partial \Omega_{j}$, such that $\Lambda_{j}(\mathbf{y}) \in$ $\Gamma_{a}(\mathbf{y})$ for each $j$ and each $\mathbf{y} \in \partial \Omega$ and $\sup \left\{\left|\mathbf{y}-\Lambda_{j}(\mathbf{y})\right| ; \mathbf{y} \in \partial \Omega\right\} \rightarrow 0$ as $j \rightarrow \infty$.
- There are positive functions $\omega_{j}$ on $\partial \Omega$ bounded away from zero and infinity uniformly in $j$ such that for any measurable set $E \subset \partial \Omega, \int_{E} \omega_{j} d \mathcal{H}_{m-1}=$ $\mathcal{H}_{m-1}\left(\Lambda_{j}(E)\right)$, and so that $\omega_{j} \rightarrow 1$ point wise a.e. and in every $L^{s}(\partial \Omega)$, $1 \leq s<\infty$.
- The normal vectors to $\Omega_{j}, \mathbf{n}\left(\Lambda_{j}(\mathbf{y})\right)$, converge point wise a.e. and in every $L^{s}(\partial \Omega), 1 \leq s<\infty$, to $\mathbf{n}(\mathbf{y})$.
(See [27], Theorem 1.12)
Lemma 6.2. Let $\omega \subset \mathcal{N}^{m}$ be a domain with compact Lipschitz boundary, $1<$ $q<\infty, q^{\prime}=q /(q-1), \tilde{h} \in L^{\infty}(\partial \omega), \tilde{\mathbf{g}} \in L^{q}\left(\partial \Omega, R^{m}\right)$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be an $L^{q}$-solution of the Robin problem (4), (5). If $\omega$ is unbounded suppose moreover $|\tilde{\mathbf{u}}(\mathbf{x})|=$ $O\left(|\mathbf{x}|^{(1-m) / 2}\right),|\nabla \tilde{\mathbf{u}}(\mathbf{x})|+|\tilde{p}(\mathbf{x})|=O\left(|\mathbf{x}|^{-m / 2}\right)$ as $|\mathbf{x}| \rightarrow \infty ; r^{(m-1) / 2} \tilde{\mathbf{u}}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$. If $\mathbf{u}^{*} \in L^{q^{\prime}}(\partial \omega)$, then

$$
\begin{equation*}
\int_{\partial \omega} \tilde{\mathbf{g}} \cdot \tilde{\mathbf{u}} \mathrm{d} \mathcal{H}_{m-1}=\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+2 \int_{\omega}|\hat{\nabla} \tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m} \tag{33}
\end{equation*}
$$

Proof. Suppose first that $\omega$ is bounded. Let $\omega(j)$ be domains from Lemma 6.1. By virtue of Green's formula and Lebesgue's lemma

$$
\int_{\partial \omega} \tilde{\mathbf{g}} \cdot \tilde{\mathbf{u}} \mathrm{d} \mathcal{H}_{m-1}=\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+\lim _{j \rightarrow \infty} \int_{\partial \omega(j)} \tilde{\mathbf{u}} \cdot\left[T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}-n_{1} \tilde{\mathbf{u}} / 2\right] \mathrm{d} \mathcal{H}_{m-1}
$$

$$
\begin{gathered}
=\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+\lim _{j \rightarrow \infty} \int_{\omega(j)}\left[2|\hat{\nabla} \tilde{\mathbf{u}}|^{2}+\tilde{\mathbf{u}} \cdot\left(\Delta \tilde{\mathbf{u}}-\nabla p-\partial_{1} \tilde{\mathbf{u}}\right)\right] \mathrm{d} \mathcal{H}_{m} \\
=\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+2 \int_{\omega}|\hat{\nabla} \tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m}
\end{gathered}
$$

Let now $\omega$ be unbounded. Define $\tilde{h}=0$ on $R^{m} \backslash \partial \omega$.

$$
\begin{gathered}
\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+2 \int_{\omega}|\hat{\nabla} \tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m}=\lim _{r \rightarrow \infty}\left[\int_{\partial(\omega \cap B(0 ; r)} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}\right. \\
\left.+2 \int_{\omega \cap B(0 ; r)}|\hat{\nabla} \tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m}\right]=\int_{\partial \omega} \tilde{\mathbf{g}} \cdot \tilde{\mathbf{u}} \mathrm{d} \mathcal{H}_{m-1}+\lim _{r \rightarrow \infty} \int_{\partial B(0 ; r)} \tilde{\mathbf{u}} \cdot\left[T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}-n_{1} \tilde{\mathbf{u}} / 2\right] \\
=\int_{\partial \omega} \tilde{\mathbf{g}} \cdot \tilde{\mathbf{u}} \mathrm{d} \mathcal{H}_{m-1}+\lim _{r \rightarrow \infty} \int_{\partial B(0 ; 1)} r^{m-1} n_{1}|\tilde{\mathbf{u}}(r \mathbf{x})|^{2} / 2 \mathrm{~d} \mathcal{H}_{m-1}(\mathbf{x})
\end{gathered}
$$

There exists a constant $C$ such that $\left.\left|r^{m-1} n_{1}\right| \tilde{\mathbf{u}}(r \mathbf{x})\right|^{2} / 2 \mid \leq C$ for $\mathbf{x} \in \partial B(0 ; 1)$. Since $r^{m-1} n_{1}|\tilde{\mathbf{u}}(r \mathbf{x})|^{2} / 2 \rightarrow 0$, Lebesgue's lemma yields $(33)$.
Proposition 6.3. Let $\omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be a regular $L^{2}$-solution of the Dirichlet problem (4), (29) with $\mathbf{g} \equiv 0$. If $\Omega$ is unbounded suppose moreover $|\tilde{\mathbf{u}}(\mathbf{x})|=O\left(|\mathbf{x}|^{(1-m) / 2}\right)$, $|\nabla \tilde{\mathbf{u}}(\mathbf{x})|+|\tilde{p}(\mathbf{x})|=O\left(|\mathbf{x}|^{-m / 2}\right)$ as $|\mathbf{x}| \rightarrow \infty ; r^{(m-1) / 2} \tilde{\mathbf{u}}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$. Then $\tilde{\mathbf{u}} \equiv 0$ and $\tilde{p}$ is constant. If $\omega$ is unbounded then $\tilde{p} \equiv 0$.

Proof. Put $h \equiv 0$. By virtue of Lemma 6.2

$$
2 \int_{\omega}|\nabla \tilde{\mathbf{u}}|^{2}=0
$$

Since $\hat{\nabla} \tilde{\mathbf{u}} \equiv 0$ there exist an anti-symmetric matrix $A$ and a vector $\mathbf{b}$ such that $\tilde{\mathbf{u}}(\mathbf{x})=A \mathbf{x}+\mathbf{b}$ (see [20], Lemma 3.1). Therefore $\tilde{u}_{j}$ is a harmonic function on $\omega, \tilde{u}_{j}=0$ on $\partial \omega$. If $\omega$ is unbounded then $\tilde{u}_{j}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$. Thus $\tilde{u}_{j} \equiv 0$ by the maximum principle. Since $\nabla \tilde{p} \equiv 0$ by (4), the function $\tilde{p}$ is constant. If $\omega$ is unbounded then $\tilde{p} \equiv 0$ because $\tilde{p}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$.

Lemma 6.4. Let $\omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$. Let $G$ be a bounded component of $R^{m} \backslash \bar{\omega}$. Fix an open ball $B$ such that $\bar{B} \subset G$. Set $\mathbf{u}=D_{B}^{O s} \mathbf{n}^{B}$ in $R^{m} \backslash \bar{B}$. Then

$$
\begin{equation*}
\int_{\partial G} \mathbf{u} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=\mathcal{H}_{m-1}(\partial G) \neq 0 \tag{34}
\end{equation*}
$$

If $\tilde{G}$ is another bounded component of $R^{m} \backslash \bar{\omega}$ then

$$
\begin{equation*}
\int_{\partial \tilde{G}} \mathbf{u} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=0 . \tag{35}
\end{equation*}
$$

Proof. Denote $\tilde{\mathbf{u}}=D_{B}^{O s} \mathbf{n}^{B}, \tilde{p}=\Pi_{B}^{O s} \mathbf{n}^{B}$ in $B$. Then there are the nontangential limits of $\mathbf{u}$ and $\tilde{\mathbf{u}}$ on $\partial B$ and it hods $\tilde{\mathbf{u}}-\mathbf{u}=\mathbf{n}^{B}$ (see Proposition 5.8). Since $\nabla \cdot \tilde{\mathbf{u}}=0, \nabla \cdot \mathbf{u}=0$, the divergence theorem gives

$$
\begin{aligned}
0= & \int_{\partial(G \backslash B)} \mathbf{u} \cdot \mathbf{n}^{G \backslash B} \mathrm{~d} \mathcal{H}_{m-1}+\int_{\partial B} \tilde{\mathbf{u}} \cdot \mathbf{n}^{B} \mathrm{~d} \mathcal{H}_{m-1}=-\int_{\partial G} \mathbf{u} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1} \\
& +\int_{\partial B} \mathbf{n}^{B} \cdot \mathbf{n}^{B} \mathrm{~d} \mathcal{H}_{m-1}=-\int_{\partial G} \mathbf{u} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}+\mathcal{H}_{m-1}(\partial G)
\end{aligned}
$$

If $\tilde{G}$ is another bounded component of $R^{m} \backslash \bar{\omega}$ then (35) is a consequence of the divergence theorem.
Lemma 6.5. Let $\Omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $m=2$ or $m=3$. Suppose that $\boldsymbol{\Psi} \in L^{2}\left(\partial \Omega, R^{m}\right)$ and $O_{\Omega} \boldsymbol{\Psi}=0$ on $\partial \Omega$. If $S$ is a component of $\partial \Omega$ then there exists a constant $c_{S}$ such that $\mathbf{\Psi}=c_{S} \mathbf{n}^{\Omega}$ on $\partial \Omega$.

Proof. Let $\omega$ be a component of $R^{m} \backslash \partial \Omega$. Then $O_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}$ is a regular $L^{2}$ solution of the Dirichlet problem for the Oseen equation with the zero boundary condition (see Proposition 5.3 and Proposition 5.4). Taking in mind behavior of $O_{\Omega} \boldsymbol{\Psi}$ and $Q_{\Omega} \boldsymbol{\Psi}$ at infinity, Proposition 6.3 gives that there exists a constant $b_{\omega}$ such that $O_{\Omega} \boldsymbol{\Psi}=0, Q_{\Omega} \boldsymbol{\Psi}=b_{\omega}$ in $\omega$. If $S$ is a component of $\partial \Omega$ we choose two components $\omega$ and $G$ of $R^{m} \backslash \partial \Omega$ such that $S \subset \partial \omega \cap \partial G$. According to Proposition 5.5 we have on $S$

$$
\begin{gathered}
\boldsymbol{\Psi}=\left[\boldsymbol{\Psi} / 2-K_{\Omega, O s}^{\prime} \boldsymbol{\Psi}\right]-\left[-\boldsymbol{\Psi} / 2-K_{\Omega, O s}^{\prime} \boldsymbol{\Psi}\right]=\left[T\left(O_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}\right) \mathbf{n}^{\Omega}\right]_{+} \\
-\left[T\left(O_{\Omega} \boldsymbol{\Psi}, Q_{\Omega} \boldsymbol{\Psi}\right) \mathbf{n}^{\Omega}\right]_{-}=\left(-b_{\omega} \mathbf{n}^{\Omega}\right)-\left(-b_{G} \mathbf{n}^{\Omega}\right) .
\end{gathered}
$$

Proposition 6.6. Let $\omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$. Fix $\boldsymbol{\Psi} \in L^{2}\left(\partial \omega, R^{m}\right)$. If $\omega$ is a bounded domain with connected boundary define $U \mathbf{\Psi}=O_{\omega} \mathbf{\Psi}$. In other cases $U \mathbf{\Psi}=\tilde{\mathbf{u}}$, where $\tilde{\mathbf{u}}$ is given by (31). Then $U: L^{2}\left(\partial \omega, R^{3}\right) \rightarrow W^{1,2}\left(\partial \omega, R^{3}\right)$ is a Fredholm operator with index 0 .

- If $\omega$ is unbounded then $U$ is an isomorphism.
- If $\omega$ is bounded then $U\left(L^{2}\left(\partial \omega, R^{m}\right)\right)=\left\{\mathbf{u} \in W^{1,2}(\partial \omega) ; \int_{\partial \omega} \mathbf{u} \cdot \mathbf{n}^{\omega}=0\right\}$. If $G$ is the unbounded component of $R^{m} \backslash \bar{\omega}$ then the kernel of $U$ is $\left\{c \mathbf{n}^{\omega} \chi_{\partial G} ; c \in R^{1}\right\}$. (Here $\chi_{\partial G}$ denotes the characteristic function of $\partial G$.)

Proof. $E_{\Omega}: L^{2}\left(\partial \omega, R^{3}\right) \rightarrow W^{1,2}\left(\partial \omega, R^{3}\right)$ is a Fredholm operator with index 0 by [22], Theorem 5.4.1. Since $U-E_{\Omega}$ is a compact operator by Proposition 5.3 and Lemma 5.4, the operator $U: L^{2}\left(\partial \omega, R^{3}\right) \rightarrow W^{1,2}\left(\partial \omega, R^{3}\right)$ is a Fredholm operator with index 0 .

Let now $U \boldsymbol{\Psi}=0$. Let $G(j)$ be a bounded component of $R^{m} \backslash \bar{\omega}$. According to (30) and Lemma 6.4 we have

$$
0=\int_{\partial G(j)} \mathbf{n}^{\omega} \cdot U \boldsymbol{\Psi} \mathrm{~d} \mathcal{H}_{m-1}=\mathcal{H}_{m-1}(\partial G(j)) \int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}
$$

Therefore

$$
\begin{equation*}
\int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=0 \tag{36}
\end{equation*}
$$

It means that $0=U \boldsymbol{\Psi}=O_{\omega} \boldsymbol{\Psi}$. If $V$ is a component of $R^{m} \backslash \bar{\omega}$ then there exists a constant $c_{V}$ such that $\boldsymbol{\Psi}=c_{V} \mathbf{n}^{\omega}$ on $\partial V$ (see Lemma 6.5). If $V$ is bounded then $c_{V}=0$ by (36).

If $\omega$ is unbounded then the kernel of $U$ is trivial. Since $U$ is of index 0 , it must be surjective. Thus $U$ is an isomorphism.

Let now $\omega$ be bounded. We have proved that the kernel of $U$ is a subset of $\left\{c \mathbf{n}^{\omega} \chi_{\partial G} ; c \in R^{1}\right\}$. So, the dimension of the kernel of $U$ is at most 1. If $\tilde{\mathbf{u}}$ is given by (31) then the divergence theorem gives $\int_{\partial \omega} \mathbf{n}^{\omega} \cdot \tilde{\mathbf{u}} \mathrm{d} \mathcal{H}_{m-1}=0$. So, the range of $U$ is a subset of $\left\{\mathbf{u} \in W^{1,2}(\partial \omega) ; \int_{\partial \omega} \mathbf{u} \cdot \mathbf{n}^{\omega}=0\right\}$. Hence the co dimension of the range of $U$ is at least 1 . Since $U$ is a Fredholm operator of index 0 , the dimension of the kernel of $U$ and the co dimension of the range of $U$ are equal to 1 .

Theorem 6.7. Let $\omega \subset R^{m}$ be a bounded domain with Lipschitz boundary, $m=2$ or $m=3$. Fix $\mathbf{g} \in W^{1,2}\left(\partial \omega, R^{m}\right)$. Then there exists a regular $L^{2}$-solution of the Dirichlet problem (4), (29) if and only if

$$
\begin{equation*}
\int_{\partial \omega} \mathbf{g} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=0 . \tag{37}
\end{equation*}
$$

If $\mathbf{u}, p$ and $\tilde{\mathbf{u}}, \tilde{p}$ are two solutions of the problem, then $\mathbf{u}=\tilde{\mathbf{u}}$ and $p-\tilde{p}$ is constant.

Proof. If there exists a regular $L^{2}$-solution of the problem (4), (29), then the divergence theorem gives (37).

Let now (37) holds true. According to Proposition 6.6 there exists $\boldsymbol{\Psi} \in$ $L^{2}\left(\partial \omega, R^{m}\right)$ such that $\tilde{\mathbf{u}}, \tilde{p}$ given by (31), (32) is a regular $L^{2}$-solution of the problem (4), (29). Let now $\mathbf{u}, p$ be another solution of the problem. Then $\mathbf{u}-\tilde{\mathbf{u}} \equiv 0, p-\tilde{p}$ is constant by Proposition 6.3.

Theorem 6.8. Let $\Omega \subset R^{m}$ be an open set, $R^{m} \backslash \Omega$ be compact, $m=2$ or $m=3$. Let $\mathbf{u}, p$ be a bounded solution of the Oseen system (4) in $\Omega$. Then
there exist a number $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $\mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}, p(\mathbf{x}) \rightarrow p_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. If $\alpha$ is a multi index then $\left|\partial^{\alpha}\left[\mathbf{u}(\mathbf{x})-\mathbf{u}_{\infty}\right]\right|=O\left(|\mathbf{x}|^{(1-m-|\alpha|) / 2}\right)$, $\left|\partial^{\alpha}\left[p(\mathbf{x})-p_{\infty}\right]\right|=O\left(|\mathbf{x}|^{1-m-|\alpha|}\right)$ as $|\mathbf{x}| \rightarrow \infty$. Moreover, $r^{(m-1) / 2} \mathbf{u}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$.

Proof. Fix $r>0$ such that $R^{m} \backslash \Omega \subset B(0 ; r)$ and denote $\omega=R^{m} \backslash \overline{B(0 ; r)}$, $\mathbf{g}=\mathbf{u}$ on $\partial \omega$. According to Proposition 6.6 there exists $\mathbf{\Psi} \in L^{2}\left(\partial \Omega, R^{m}\right)$ such that $\tilde{\mathbf{u}}, \tilde{p}$ given by (31), (32) is a regular $L^{2}$-solution of the problem (4), (29). Remark that $\tilde{p} \in L^{2}(\omega \cap B(0 ; 2 r)), \tilde{\mathbf{u}} \in W^{1,2}(\omega \cap B(0 ; 2 r))$ (see [19], Lemma 2). If $\alpha$ is a multi index then $\left|\partial^{\alpha} \tilde{\mathbf{u}}(\mathbf{x})\right|=O\left(|\mathbf{x}|^{(1-m-|\alpha|) / 2}\right),\left|\partial^{\alpha} \tilde{p}(\mathbf{x})\right|=O\left(|\mathbf{x}|^{1-m-|\alpha|}\right)$ as $|\mathbf{x}| \rightarrow \infty$. Moreover, $r^{(m-1) / 2} \tilde{\mathbf{u}}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$. Denote $\mathbf{v}=$ $\mathbf{u}-\tilde{\mathbf{u}}, q=p-\tilde{p}$ in $\omega, \mathbf{v}=0, q=0$ elsewhere. Then $\mathbf{v} \in W_{l o c}^{1,2}\left(R^{m}\right), q \in L_{l o c}^{2}\left(R^{m}\right)$, $\nabla \cdot \mathbf{v}=0$. Moreover, $\mathbf{v}, q$ is a solution of the Oseen equation (4) in $R^{m} \backslash \partial \omega$. Denote $\mathbf{f}=-\Delta \mathbf{v}+\partial_{1} \mathbf{v}+\nabla q$. Then $\mathbf{f}$ is a compactly supported distribution. Denote $\mathbf{w}=O * \mathbf{f}, \eta=Q * \mathbf{f}$. Then $\mathbf{v}-\mathbf{w}, q-\eta$ is a solution of the Oseen equation (4) in the whole $R^{m}$. If $\alpha$ is a multi index then $\left|\partial^{\alpha} \mathbf{w}(\mathbf{x})\right|=O\left(|\mathbf{x}|^{(1-m-|\alpha|) / 2}\right)$, $\left|\partial^{\alpha} \eta(\mathbf{x})\right|=O\left(|\mathbf{x}|^{1-m-|\alpha|}\right)$ as $|\mathbf{x}| \rightarrow \infty$. Moreover, $r^{(m-1) / 2} \mathbf{w}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$. Since $\mathbf{v}-\mathbf{w}, q-\eta$ are bounded solutions of the Oseen equation (2) in $R^{m}$, they are constant by Lemma 4.1.

Theorem 6.9. Let $\omega \subset R^{m}$ be an unbounded domain with compact Lipschitz boundary, $m=2$ or $m=3$. Let $\mathbf{g} \in W^{1,2}\left(\partial \omega, R^{m}\right)$ be fixed. If $\mathbf{u}, p$ is a regular $L^{2}$-solution of the Dirichlet problem (4), (29) then there exist a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. On the other hand, if $p_{\infty}, \mathbf{u}_{\infty}$ are given then there exists a unique regular $L^{2}$-solution $\mathbf{u}, p$ of the Dirichlet problem (4), (29) such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. Moreover,

$$
\begin{equation*}
\left\|(\mathbf{u})^{*}+(\nabla \mathbf{u})^{*}+(p)^{*}\right\|_{L^{2}(\partial \Omega)} \leq C\left[\left|\mathbf{u}_{\infty}\right|+\left|p_{\infty}\right|+\|\mathbf{g}\|_{W^{1,2}\left(\partial \omega, R^{m}\right)}\right] \tag{38}
\end{equation*}
$$

where $C$ depends only on $\Omega$.
Proof. If $\mathbf{u}, p$ is a regular $L^{2}$-solution of the Dirichlet problem (4), (29) then there exist a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. (See Theorem 6.8.)

Let now $\mathbf{u}_{\infty}, p_{\infty}$ be given. According to Proposition 6.6 the operator $U$ is an isomorphism from $L^{2}\left(\partial \omega, R^{m}\right)$ onto $W^{1,2}\left(\partial \omega, R^{m}\right)$. Put $\boldsymbol{\Psi}=U^{-1} \mathbf{g}-\mathbf{u}_{\infty}$. Then $\tilde{\mathbf{u}}, \tilde{p}$ given by (31), (32) satisfy $\tilde{\mathbf{u}}=\mathbf{g}-\mathbf{u}_{\infty}$ on $\partial \omega$. Put $\mathbf{u}=\tilde{\mathbf{u}}+\mathbf{u}_{\infty}$, $p=\tilde{p}+p_{\infty}$. Then $\mathbf{u}, p$ is a regular $L^{2}$-solution of the Dirichlet problem (4), (29) such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. According to properties of Oseen potentials (38) holds true with $C$ depending only on $\Omega$.

If $\mathbf{v}, q$ is another solution of that problem then $|\mathbf{u}(\mathbf{x})-\mathbf{v}(\mathbf{x})|=O\left(|\mathbf{x}|^{(1-m) / 2}\right)$, $|\nabla \mathbf{u}(\mathbf{x})-\nabla \mathbf{v}(\mathbf{x})|+|p(\mathbf{x})-q(\mathbf{x})|=O\left(|\mathbf{x}|^{-m / 2}\right), r^{(m-1) / 2}|\mathbf{u}(r \mathbf{x})-\mathbf{v}(r \mathbf{x})| \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$ (see Theorem 6.8). Proposition 6.3 gives that $\mathbf{u}-\mathbf{v} \equiv 0$, $p-q \equiv 0$.

## $7 \quad L^{2}$-solutions of the Robin problem

Let $\omega \subset R^{m}$ be a domain with compact Lipschitz boundary, $m=2$ or $m=3$. Let now $G(1), \ldots, G(k)$ be all bounded components of $R^{m} \backslash \bar{\omega}$. If $\tilde{\mathbf{g}} \in L^{q}\left(\partial \omega, R^{m}\right)$ we shall look for an $L^{q}$-solution of the Robin problem (4), (5) in the form of a modified Oseen single layer potential (31), (32) with $\Psi \in L^{q}\left(\partial \omega, R^{m}\right)$. According to Proposition 5.3 and Proposition 5.5 the vector functions $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem (4), (5) if and only if

$$
\tau_{\tilde{h}} \boldsymbol{\Psi}=\tilde{g}
$$

where

$$
\tau_{\tilde{h}} \boldsymbol{\Psi}=\frac{1}{2} \mathbf{\Psi}-K_{\omega, O s}^{\prime} \mathbf{\Psi}+\tilde{h} O_{\omega} \mathbf{\Psi}+L_{\tilde{h}} \mathbf{\Psi}
$$

$L_{\tilde{h}} \boldsymbol{\Psi}=\sum_{j=1}^{m}\left(\int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}\right)\left[T\left(D_{B(j)}^{O s} \mathbf{n}^{B(j)}, \Pi_{B(j)}^{O s} \mathbf{n}^{B(j)}\right) \mathbf{n}+\left(\tilde{h}-n_{1} / 2\right) D_{B(j)}^{O s} \mathbf{n}^{B(j)}\right]$.
Proposition 7.1. Let $\omega \subset R^{m}$ be an open set with compact Lipschitz boundary, $1<q<\infty, m=2$ or $m=3$. Suppose that $q=2$ or $\partial \Omega$ is of class $\mathcal{C}^{1}$. If $\tilde{h} \in L^{\infty}(\partial \omega)$ then $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 in $L^{q}\left(\partial \omega, R^{m}\right)$.

Proof. $\frac{1}{2} I-K_{\omega}^{\prime}$ is a Fredholm operator with index 0 in $L^{2}\left(\partial \omega, R^{m}\right)$ by [22], Theorem 5.3.6. If $\partial \omega$ is of class $\mathcal{C}^{1}$, then $K_{\omega}$ is a compact operator on $L^{q^{\prime}}\left(\partial \omega, R^{m}\right)$ where $q^{\prime}=q /(q-1)$ (see [17], p. 232). Therefore $K_{\omega}^{\prime}$ is a compact operator in $L^{q}\left(\partial \omega, R^{m}\right)$ and $\frac{1}{2} I-K_{\omega}^{\prime}$ is a Fredholm operator with index 0 in $L^{q}\left(\partial \omega, R^{m}\right)$. Since $\tau_{\tilde{h}}-\left[\frac{1}{2} I-K_{\omega}^{\prime}\right]$ is a compact operator by Proposition 5.3 and Lemma 5.4, we deduce that $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 in $L^{q}\left(\partial \omega, R^{m}\right)$.
Proposition 7.2. Let $\omega \subset R^{m}$ be a bounded domain with Lipschitz boundary, $1<q<\infty, q^{\prime}=q /(q-1), \tilde{h} \in L^{\infty}(\partial \omega), \tilde{h} \geq 0$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be an $L^{q}$-solution of the Robin problem (4), (5) with $\tilde{\mathbf{g}} \equiv 0$. If $(\tilde{\mathbf{u}})^{*} \in L^{q^{\prime}}(\partial \omega)$ then $\tilde{\mathbf{u}} \equiv 0, \tilde{p} \equiv 0$.

Proof. Lemma 6.2 gives that $|\hat{\nabla} \tilde{\mathbf{u}}|=0$ in $\omega, \tilde{h} \tilde{\mathbf{u}}=0$ on $\partial \omega$. Since $\hat{\nabla} \tilde{\mathbf{u}} \equiv 0$ there exist an anti-symmetric matrix $A$ and a vector $\mathbf{b}$ such that $\tilde{\mathbf{u}}(\mathbf{x})=A \mathbf{x}+\mathbf{b}$ (see [20], Lemma 3.1). If $\int_{\partial \omega} \tilde{h} \mathrm{~d} \mathcal{H}_{m-1}>0$ then $\tilde{h} \tilde{\mathbf{u}}=0$ gives $\tilde{\mathbf{u}} \equiv 0$ (see [21], Lemma 5.1. Since $\nabla \tilde{p}=\Delta \tilde{\mathbf{u}}-\partial_{1} \tilde{\mathbf{u}}=0$ we infer that $\tilde{p}$ is constant. Since $0=T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}_{\tilde{h}}^{\omega}-n_{1} \tilde{\mathbf{u}} / 2+\tilde{h} \tilde{\mathbf{u}}=-\tilde{p} \mathbf{n}^{\omega}$ we deduce that $\tilde{p} \equiv 0$.

Let now $\tilde{h} \equiv 0$. If $j \neq 1$ then

$$
\begin{gathered}
\partial_{j} \tilde{p}(\mathbf{x})=\Delta \tilde{u}_{j}(\mathbf{x})-\partial_{1} \tilde{u}_{j}(\mathbf{x})=-a_{j 1} \\
\partial_{1} \tilde{p}(\mathbf{x})=\Delta \tilde{u}_{1}(\mathbf{x})-\partial_{1} \tilde{u}_{1}(\mathbf{x})=0
\end{gathered}
$$

Thus there exists a constant $c$ such that

$$
\tilde{p}(\mathbf{x})=-\sum_{j=2}^{m} a_{j 1} x_{j}+c .
$$

We have

$$
\begin{equation*}
0=T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}^{\omega}-n_{1} \tilde{\mathbf{u}} / 2=-\tilde{p} \mathbf{n}^{\omega}-n_{1} \tilde{\mathbf{u}} / 2 . \tag{39}
\end{equation*}
$$

Thus $n_{1}^{\omega}\left(\tilde{p}+\tilde{u}_{1} / 2\right)=0$. The function $\tilde{p}+\tilde{u}_{1} / 2$ is a polynomial of the first order. If $\tilde{p}+\tilde{u}_{1} / 2 \not \equiv 0$ then $M=\left\{\mathbf{x} ; \tilde{p}(\mathbf{x})+\tilde{u}_{1}(\mathbf{x}) / 2=0\right\}$ is a subset of a hyperplane. So, $n_{1}=0$ outside this hyperplane. It is not possible. Hence $\tilde{p}+\tilde{u}_{1} / 2 \equiv 0$ and

$$
\sum_{j=2}^{m} a_{j 1} x_{j}-c=-\tilde{p}(\mathbf{x})=\frac{\tilde{u}_{1}(\mathbf{x})}{2}=\sum_{j=2}^{m} \frac{a_{1 j}}{2} x_{j}+\frac{b_{1}}{2}=\sum_{j=2}^{m} \frac{-a_{j 1}}{2} x_{j}+\frac{b_{1}}{2}
$$

This forces that $a_{1 j}=a_{j 1}=0$ and $\tilde{p}=c=-b_{1} / 2, \tilde{u}_{1}=b_{1}=-2 c$.
Suppose first that $c=0$. Then $\tilde{p}=\tilde{u}_{1}=0$. If $j \neq 1$ then (39) gives $n_{1} \tilde{u}_{j}=0$. The function $\tilde{u}_{j}$ is a polynomial of the first order. If $\tilde{u}_{j} \not \equiv 0$ then $M_{j}=\left\{\mathbf{x} ; \tilde{u}_{j}(\mathbf{x})=0\right\}$ is a subset of a hyperplane. So, $n_{1}=0$ outside this hyperplane. It is not possible. Hence $\tilde{u}_{j} \equiv 0$.

Let now $c \neq 0$. Fix $\mathbf{z} \in \partial \omega$. We can choose a coordinate system in a such way that $\mathbf{z}=0$. Denote $p_{j}=\tilde{u}_{j}-b_{j}$. Then $p_{j}(\mathbf{x}) \rightarrow 0$ as $\mathbf{x} \rightarrow 0=\mathbf{z}$. From (39) we get $n_{j}^{\omega}=n_{1}^{\omega}\left(p_{j}+b_{j}\right) / b_{1}$. Since $p_{j}(\mathbf{x}) \rightarrow 0$ as $\mathbf{x} \rightarrow \mathbf{z}$ we deduce that $\mathbf{n}^{\omega}(\mathbf{x}) \rightarrow \mathbf{b} /|\mathbf{b}|$ or $\mathbf{n}^{\omega}(\mathbf{x}) \rightarrow-\mathbf{b} /|\mathbf{b}|$ as $\mathbf{x} \rightarrow \mathbf{z}$. (Since $\partial \omega$ is Lipschitz, it is not possible $\mathbf{n}^{\omega}\left(\mathbf{x}^{\mathbf{k}}\right) \rightarrow \mathbf{b} /|\mathbf{b}|$ and $\mathbf{n}^{\omega}\left(\mathbf{y}^{\mathbf{k}}\right) \rightarrow \mathbf{b} /|\mathbf{b}|$ for some sequences $\mathbf{y}^{k} \rightarrow \mathbf{z}, \mathbf{x}^{k} \rightarrow \mathbf{z}$.) This gives that $\partial \omega$ is of class $\mathcal{C}^{1}$. Now fix $\mathbf{z} \in \partial \omega$ such that $z_{2}=\max \left\{x_{2} ; \mathbf{x} \in \partial \omega\right\}$. Then $\mathbf{n}^{\omega}(\mathbf{z})=[0,1,0, \ldots, 0]$. But (39) forces $1=n_{2}^{\Omega}(\mathbf{z})=n_{1}^{\omega} \tilde{u}_{j}(\mathbf{z}) / b_{1}=0$, what is a contradiction.
Theorem 7.3. Let $\omega \subset R^{m}$ be a bounded domain with Lipschitz boundary, $m=2$ or $m=3, \tilde{h} \in L^{\infty}(\partial \omega), \tilde{h} \geq 0$. Then $\tau_{\tilde{h}}$ is an isomorphism on $L^{2}\left(\partial \omega, R^{m}\right)$. Fix $\tilde{\mathbf{g}} \in L^{2}\left(\partial \omega, R^{m}\right)$. Denote $\boldsymbol{\Psi}=\tau_{\tilde{h}}^{-1} \mathbf{g}$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be given by (31), (32). Then $\tilde{\mathbf{u}}, \tilde{p}$ is a unique $L^{2}$-solution of the Robin problem (4), (5). Moreover,

$$
\begin{equation*}
\left\|(|\tilde{\mathbf{u}}|+|\nabla \tilde{\mathbf{u}}|+|\tilde{p}|)^{*}\right\|_{L^{2}(\partial \omega)} \leq C\|\tilde{\mathbf{g}}\|_{L^{2}(\partial \omega)} \tag{40}
\end{equation*}
$$

where $C$ depends only on $\omega$ and $\tilde{h}$.
Proof. Let $\boldsymbol{\Psi} \in L^{2}\left(\partial \omega, R^{m}\right)$ and $\tau_{\tilde{h}} \boldsymbol{\Psi}=0$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be given by (31), (32). Then $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5) with $\tilde{\mathbf{g}} \equiv 0$. Proposition 7.2 gives that $\tilde{\mathbf{u}} \equiv 0, \tilde{p} \equiv 0$. According to (30) and Lemma 6.4

$$
0=\int_{\partial G(j)} \tilde{\mathbf{u}} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}=\mathcal{H}_{m-1}(\partial G(j)) \int_{\partial G(j)} \boldsymbol{\Psi} \cdot \mathbf{n}^{\omega} \mathrm{d} \mathcal{H}_{m-1}
$$

So, (36) holds and $\tilde{\mathbf{u}}=O_{\omega} \boldsymbol{\Psi}, \tilde{p}=Q_{\omega} \boldsymbol{\Psi}$. Let $G$ be an unbounded component of $R^{m} \backslash \bar{\omega}$. By virtue of Lemma 6.5 and (36) there exists a constant $c$ such that $\boldsymbol{\Psi}=c \chi_{G}$. Therefore $0=\tilde{p}=-c$ (see [20]). This forces that $\boldsymbol{\Psi}=0$. Since $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 by Proposition 7.1, it is an isomorphism.

Let now $\tilde{\mathbf{g}} \in L^{2}\left(\partial \omega, R^{m}\right)$. If $\mathbf{\Psi}=\tau_{\tilde{h}}^{-1} \mathbf{g}$ and $\tilde{\mathbf{u}}, \tilde{p}$ are given by (31), (32) then $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5). The uniqueness follows
from Proposition 7.2. The estimate (40) is a consequence of Proposition 5.3 and Proposition 5.5.
Proposition 7.4. Let $\omega \subset R^{m}$ be an unbounded domain with compact Lipschitz boundary, $m=2$ or $m=3, \tilde{h} \in L^{\infty}(\partial \omega), \tilde{h} \geq 0, \tilde{\mathbf{g}} \equiv 0$. If $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5) such that $\tilde{\mathbf{u}}(\mathbf{x}) \rightarrow 0, \tilde{p}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$, then $\tilde{\mathbf{u}} \equiv 0, \tilde{p} \equiv 0$.

Proof. If $\alpha$ is a multi index then $\left|\partial^{\alpha} \tilde{\mathbf{u}}(\mathbf{x})\right|=O\left(|\mathbf{x}|^{(1-m-\alpha \mid) / 2}\right),\left|\partial^{\alpha} p(\mathbf{x})\right|=$ $O\left(|\mathbf{x}|^{1-m-\alpha \mid}\right)$ as $|\mathbf{x}| \rightarrow \infty$, and $r^{(m-1) / 2} \mathbf{u}(r \mathbf{x}) \rightarrow 0$ as $r \rightarrow \infty$ for $|\mathbf{x}| \neq\left|x_{1}\right|$ (see Theorem 6.8). By virtue of Lemma 6.2

$$
\int_{\partial \omega} \tilde{h}|\tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m-1}+2 \int_{\omega}|\hat{\nabla} \tilde{\mathbf{u}}|^{2} \mathrm{~d} \mathcal{H}_{m}=0
$$

Since $\hat{\nabla} \tilde{\mathbf{u}} \equiv 0$ there exist an anti-symmetric matrix $A$ and a vector $\mathbf{b}$ such that $\tilde{\mathbf{u}}(\mathbf{x})=A \mathbf{x}+\mathbf{b}$ (see [20], Lemma 3.1). The relation $\tilde{\mathbf{u}}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$ forces $\tilde{\mathbf{u}} \equiv 0$. Since $\nabla \tilde{p} \equiv 0$ by (4), the function $\tilde{p}$ is constant. Hence $\tilde{p} \equiv 0$ because $\tilde{p}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$.

Proposition 7.5. Let $\omega \subset R^{m}$ be an unbounded domain with compact Lipschitz boundary, $1<q<\infty, m=2$ or $m=3$. Suppose that $q=2$ or $\partial \omega$ is of class $\mathcal{C}^{1}$. If $\tilde{h} \in L^{\infty}(\partial \omega), \tilde{h} \geq 0$ then $\tau_{h}$ is an isomorphism on $L^{q}\left(\partial \omega, R^{m}\right)$.

Proof. Let $\boldsymbol{\Psi} \in L^{q}\left(\partial \omega, R^{m}\right), \tau_{\tilde{h}} \boldsymbol{\Psi}=0$. Since $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 in $L^{q}\left(\partial \omega, R^{m}\right)$ and in $L^{2}\left(\partial \omega, R^{m}\right)$ (see Proposition 7.1), we have $\boldsymbol{\Psi} \in L^{2}\left(\partial \omega, R^{m}\right)$ by [18], Lemma 9. If $\tilde{\mathbf{u}}, \tilde{p}$ are given by (31), (32), then $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5) with $\tilde{\mathbf{g}} \equiv 0$. Proposition 7.4 gives that $\tilde{\mathbf{u}} \equiv 0, \tilde{p} \equiv 0$. So, $\boldsymbol{\Psi}=0$ by Proposition 6.6. Since $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 by Proposition 7.1, it is an isomorphism.

Theorem 7.6. Let $\omega \subset R^{m} \underset{\tilde{h}}{\text { be }}$ an unbounded domain with compact Lipschitz boundary, $m=2$ or $m=3, \tilde{h} \in L^{\infty}(\partial \omega)$, $\tilde{h} \geq 0$. Fix $\tilde{\mathbf{g}} \in L^{2}\left(\partial \omega, R^{m}\right)$. If $\tilde{\mathbf{u}}$, $\tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5) then there exists a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. Let now $p_{\infty} \in R^{1}, \mathbf{u}_{\infty} \in R^{m}$ be given. Denote $\mathbf{\Psi}=\tau_{\tilde{h}}^{-1}\left[\mathbf{g}+p_{\infty} \mathbf{n}^{\omega}+\left(n_{1}^{\omega}-\tilde{h}\right) \mathbf{u}_{\infty}\right]$. Let $\tilde{\mathbf{u}}$, $\tilde{p}$ be given by (31), (32). Then $\mathbf{u}=\tilde{\mathbf{u}}+\mathbf{u}_{\infty}, p=\tilde{p}+p_{\infty}$ is a unique $L^{2}$-solution of the Robin problem (4), (5) such that $p(\mathbf{x}) \rightarrow p_{\infty}, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. Moreover,

$$
\begin{equation*}
\left\|(|\mathbf{u}|+|\nabla \mathbf{u}|+|p|)^{*}\right\|_{L^{2}(\partial \omega)} \leq C\left[\|\tilde{\mathbf{g}}\|_{L^{2}(\partial \omega)}+\left|p_{\infty}\right|+\mid \mathbf{u}_{\infty}\right] \tag{41}
\end{equation*}
$$

where $C$ depends only on $\omega$ and $\tilde{h}$.
Proof. If $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the Robin problem (4), (5) then there exists a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. (See Theorem 6.8.)

Let now $p_{\infty} \in R^{1}, \mathbf{u}_{\infty} \in R^{m}$ be given. The operator $\tau_{\tilde{h}}$ is invertible by Proposition 7.5. Clearly, $\mathbf{u}, p$ is an $L^{2}$-solution of the Robin problem such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$. The uniqueness follows from Proposition 7.4. The estimate (41) is a consequence of Proposition 5.3 and Proposition 5.5.

## $8 \quad L^{q}$-solution of the Robin problem

In this section we prove the existence of an $L^{q}$-solution of the Robin problem for $\omega$ with boundary of class $\mathcal{C}^{1}$.
Theorem 8.1. Let $\omega \subset R^{m}$ be a bounded domain with boundary of class $\mathcal{C}^{1}$, $m=2$ or $m=3,1<q<\infty, \tilde{h} \in L^{\infty}(\partial \omega), \tilde{h} \geq 0$. Then $\tau_{\tilde{h}}$ is an isomorphism on $L^{q}\left(\partial \omega, R^{m}\right)$. Fix $\tilde{\mathbf{g}} \in L^{q}\left(\partial \omega, R^{m}\right)$. Denote $\boldsymbol{\Psi}=\tau_{\tilde{h}}^{-1} \mathbf{g}$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be given by (31), (32). Then $\tilde{\mathbf{u}}, \tilde{p}$ is a unique $L^{q}$-solution of the Robin problem (4), (5). Moreover,

$$
\begin{equation*}
\left\|(|\tilde{\mathbf{u}}|+|\nabla \tilde{\mathbf{u}}|+|\tilde{p}|)^{*}\right\|_{L^{q}(\partial \omega)} \leq C\|\tilde{\mathbf{g}}\|_{L^{q}(\partial \omega)} \tag{42}
\end{equation*}
$$

where $C$ depends only on $\omega, \tilde{h}$ and $q$.
Proof. $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 in $L^{2}\left(\partial \omega, R^{m}\right)$ and in $L^{q}\left(\partial \omega, R^{m}\right)$ by Proposition 7.1. Since $\tau_{\tilde{h}}$ is injective in $L^{2}\left(\partial \omega, R^{m}\right)$ it is injective in $L^{q}\left(\partial \omega, R^{m}\right)$ (see [18], Lemma 9). Since $\tau_{\tilde{h}}$ is a Fredholm operator with index 0 in $L^{q}\left(\partial \omega, R^{m}\right)$ it is an isomorphism.

Let $\boldsymbol{\Psi}=\tau_{\tilde{h}}^{-1} \mathbf{g}, \tilde{\mathbf{u}}, \tilde{p}$ be given by (31), (32). Clearly, $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem (4), (5).

Now we show the uniqueness. Let $\tilde{\mathbf{g}} \equiv 0, \tilde{\mathbf{u}}, \tilde{p}$ be an $L^{q}$-solution of the Robin problem (4), (5). Then $T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}^{\omega}-n_{1} \tilde{\mathbf{u}} / 2=-\tilde{h} \tilde{\mathbf{u}}$. Proposition 5.9 gives $\tilde{\mathbf{u}}=D_{\omega}^{O s} \tilde{\mathbf{u}}-O_{\omega} h \tilde{\mathbf{u}}$ in $\omega$. By virtue of Proposition 5.3 Proposition 5.8 we have $\tilde{\mathbf{u}}=\tilde{\mathbf{u}} / 2+K_{\omega, O s} \tilde{\mathbf{u}}-O_{\omega} h \tilde{\mathbf{u}}$ in $\partial \omega$. Put $q^{\prime}=q /(q-1)$. The operator $\tilde{\mathbf{u}} \mapsto K_{\omega, O s} \tilde{\mathbf{u}}-O_{\omega} h \tilde{\mathbf{u}}$ is compact in $L^{q}\left(\partial \omega, R^{m}\right)$ and in $L^{q^{\prime}}\left(\partial \omega, R^{m}\right)$ by Proposition 5.3, Proposition 5.4 and [17], p. 232. Since $\tilde{\mathbf{u}}-K_{\omega, O s} \tilde{\mathbf{u}}+O_{\omega} h \tilde{\mathbf{u}}=0$, [18], Lemma 9 gives that $\tilde{\mathbf{u}} \in L^{q^{\prime}}\left(\partial \omega, R^{m}\right)$. Since $\tilde{\mathbf{u}}=D_{\omega}^{O s} \tilde{\mathbf{u}}-O_{\omega} h \tilde{\mathbf{u}}$, Proposition 5.3 and Proposition 5.8 give $(\tilde{\mathbf{u}})^{*} \in L^{q^{\prime}}(\partial \omega)$. So, $\tilde{\mathbf{u}} \equiv 0$ by Proposition 7.2.

The estimate (42) is a consequence of Proposition 5.3 and Proposition 5.5.
Theorem 8.2. Let $\omega \subset R^{m}$ be an unbounded domain with compact Lipschitz boundary, $m=2$ or $m=3, \tilde{h} \in L^{\infty}(\partial \omega)$, $\tilde{h} \geq 0,1<q<\infty$. Fix $\tilde{\mathbf{g}} \in$ $L^{q}\left(\partial \omega, R^{m}\right)$. If $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem (4), (5) then there exists a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. Let now $p_{\infty} \in R^{1}, \mathbf{u}_{\infty} \in R^{m}$ be given. Denote $\mathbf{\Psi}=\tau_{\tilde{h}}^{-1}\left[\mathbf{g}+p_{\infty} \mathbf{n}^{\omega}+\right.$ $\left.\left(n_{1}^{\omega}-\tilde{h}\right) \mathbf{u}_{\infty}\right]$. Let $\tilde{\mathbf{u}}, \tilde{p}$ be given by (31), (32). Then $\mathbf{u}=\tilde{\mathbf{u}}+\mathbf{u}_{\infty}, p=\tilde{p}+p_{\infty}$ is a unique $L^{q}$-solution of the Robin problem (4), (5) such that $p(\mathbf{x}) \rightarrow p_{\infty}$, $\tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. Moreover,

$$
\begin{equation*}
\left\|(|\mathbf{u}|+|\nabla \mathbf{u}|+|p|)^{*}\right\|_{L^{q}(\partial \omega)} \leq C\left[\|\tilde{\mathbf{g}}\|_{L^{q}(\partial \omega)}+\left|p_{\infty}\right|+\mid \mathbf{u}_{\infty}\right] \tag{43}
\end{equation*}
$$

where $C$ depends only on $\omega, p$ and $\tilde{h}$.
Proof. If $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem (4), (5) then there exists a constant $p_{\infty}$ and a vector $\mathbf{u}_{\infty}$ such that $p(\mathbf{x}) \rightarrow p_{\infty}, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$ as $|\mathbf{x}| \rightarrow \infty$. (See Theorem 6.8.)

Let now $p_{\infty} \in R^{1}, \mathbf{u}_{\infty} \in R^{m}$ be given. The operator $\tau_{\tilde{h}}$ is invertible in $L^{q}\left(\partial \omega, R^{m}\right)$ by Proposition 7.5. Clearly, $\mathbf{u}, p$ is an $L^{q}$-solution of the Robin problem such that $p(\mathbf{x}) \rightarrow p_{\infty}, \mathbf{u}(\mathbf{x}) \rightarrow \mathbf{u}_{\infty}$.

Let now $\tilde{\mathbf{g}} \equiv 0$ and $\tilde{\mathbf{u}}, \tilde{p}$ be an $L^{q}$-solution of the Robin problem (4), (5) such that $p(\mathbf{x}) \rightarrow 0, \tilde{\mathbf{u}}(\mathbf{x}) \rightarrow 0$ as $|\mathbf{x}| \rightarrow \infty$. If $p \geq 2$ then $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the problem (4), (5). Let now $p<2$. Fix $r>0$ such that $\partial \omega \subset B(0 ; r)$ and set $\Omega=\omega \cap B(0 ; r)$. Define $\tilde{h}=0$ on $\partial B(0 ; r), \tilde{\mathbf{g}}=T(\tilde{\mathbf{u}}, \tilde{p}) \mathbf{n}^{\Omega}-n_{1}^{\Omega} \tilde{\mathbf{u}} / 2$ on $\partial B(0 ; r)$. Then $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{q}$-solution of the Robin problem (4), (5) in $\Omega$. Theorem 8.1 gives that $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of this problem. Hence $\tilde{\mathbf{u}}, \tilde{p}$ is an $L^{2}$-solution of the problem (4), (5) in $\omega$. Proposition 7.4 gives that $\tilde{\mathbf{u}} \equiv 0, \tilde{p} \equiv 0$.

The estimate (43) is a consequence of Proposition 5.3 and Proposition 5.5.
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