

# Maximal dissipation and well posedness for models of inviscid fluids

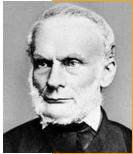
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# Thermodynamics



Rudolph Clausius,  
[1822–1888]

## First and Second law of thermodynamics

Die Energie der Welt ist constant; Die Entropie der Welt strebt einem Maximum zu

# Well posedness - classical sense



Jacques Hadamard,  
[1865 - 1963]

## Existence

Given problem is solvable for any choice of (admissible) data

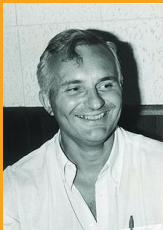
## Uniqueness

Solutions are uniquely determined by the data

## Stability

Solutions depend continuously on the data

# Well posedness - modern way



Jacques-Louis Lions,  
[1928 - 2001]

## Approximations

Given problem admits an approximation scheme that is solvable analytically and, possibly, numerically

## Uniform bounds

Approximate solutions possess uniform bounds depending solely on the data

## Stability

The family of approximate solutions admits a limit representing a (generalized) solution of the given problem

# Abstract conservation laws

## System of equations (conservation laws)

$$\partial_t \mathbf{U} + \operatorname{div}_x \mathbb{F}(\mathbf{U}) = 0,$$

$\mathbf{U}$  ..... state variable  
 $\mathbb{F}$  ..... flux

## “Entropies”

$$\partial_t E_i(\mathbf{U}) + \operatorname{div}_x \mathbf{F}_{E_i}(\mathbf{U}) = \boxed{(\leq)} 0, \quad i = 1, 2, \dots$$

$E_i$  ..... entropy  
 $\mathbf{F}_i$  ..... entropy flux

## *A priori* bounds

$\int E_i(\mathbf{U}) \, dx$  bounded in terms of the initial data,  $i = 1, 2, \dots$

# Weak vs. strong solutions

## Lack of regularity

- bounds available only in  $L^p$  ( $L^\infty$ )
- presence of oscillations
- discontinuities (shocks) appearing in finite time even for initial states

## Weak solutions

$$\begin{aligned} & \int_{\Omega} \mathbf{U} \cdot \varphi(\tau_2, \cdot) - \mathbf{U} \varphi(\tau_1, \cdot) \, dx \\ &= \int_{\tau_1}^{\tau_2} \int_{\Omega} [\mathbf{U} \cdot \partial_t \varphi + \mathbb{F}(\mathbf{U}) : \nabla_x \varphi] \, dx \, dt \end{aligned}$$

## Weak continuity

$t \mapsto \mathbf{U}(t, \cdot)$  weakly continuous

# Compensated compactness - DiPerna, Tartar

## Linear field equations

$$\begin{aligned}\partial_t \mathbf{U} + \operatorname{div}_x \mathbb{F} &= 0 \\ \partial_t E_i + \operatorname{div}_x \mathbf{F}_i &\leq 0, \quad i = 1, 2, \dots\end{aligned}$$

## Nonlinear constitutive equations

$$\mathbb{F} = \mathbb{F}(\mathbf{U}), \quad E_i = E_i(\mathbf{U}), \quad \mathbf{F}_i = \mathbf{F}_i(\mathbf{U}), \quad i = 1, 2, \dots$$

## Compensated compactness

- linear field equations yield constraints on possible oscillations described by Young measure
- nonlinear constrained imposed by constitutive equations reduce the Young measures to Dirac masses (no oscillations)

# Basic ideas of Young measures

**Oscillatory sequence - convergence in the sense of averages**

$$U_n \rightarrow U \text{ weakly-} (*) \Leftrightarrow \int_B U_n \rightarrow \int_B U \text{ for any } B$$

**Young measure associated to  $\{U_n\}$**

$$\langle \sigma_y(U), f \rangle = \lim_{r \rightarrow 0} \frac{1}{|B_r(y)|} \left[ \lim_{n \rightarrow \infty} \int_{B_r} f(U_n) \right]$$

**Strong (pointwise a.a.) convergence**

$$U_n \rightarrow U \text{ for a.a.} \Leftrightarrow \sigma_y(U) = \delta_{U(y)} \text{ for a.a. } y$$



# Convex integration

## Linear field equations

$$\partial_t \mathbf{U} + \operatorname{div}_x \mathbb{F} = 0$$

## Replacing constitutive equation

$$\mathbb{F} = \mathbb{F}(\mathbf{U}) \Leftrightarrow \Lambda(\mathbf{U}, \mathbb{F}) = E(\mathbf{U}) \quad \boxed{\text{"implicit"}}$$

$$\Lambda(\mathbf{U}, \mathbb{F}) \text{ convex, } \Lambda(\mathbf{U}, \mathbb{F}) \geq E(\mathbf{U})$$

## Relaxation of constitutive equation

$$E(\mathbf{U}) \leq \Lambda(\mathbf{U}, \mathbb{F}) \leq e, \quad e \text{ given "energy"}$$

$$\mathbb{F} = \mathbb{F}(\mathbf{U}) \Leftrightarrow \Lambda(\mathbf{U}, \mathbb{F}) = E(\mathbf{U}) \Leftarrow E(\mathbf{U}) = e$$

# Convex integration - DeLellis - Székelyhidi

## Incompressible Euler system

$$\operatorname{div}_x \mathbf{v} = 0, \quad \partial_t \mathbf{v} + \operatorname{div}_x \left( \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I} \right) + \nabla_x \left( \frac{1}{3} |\mathbf{v}|^2 + \Pi \right) = 0$$

$$\mathbb{F} = \left( \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I} \right) - \text{symmetric traceless}$$

## Relaxation

$$\Lambda(\mathbf{v}, \mathbb{F}) = \frac{3}{2} \lambda_{\max} [\mathbf{v} \otimes \mathbf{v} - \mathbb{F}]$$

$$\Lambda(\mathbf{v}, \mathbb{F}) \geq \frac{1}{2} |\mathbf{v}|^2$$

$$\Lambda(\mathbf{v}, \mathbb{F}) = \frac{1}{2} |\mathbf{v}|^2 \Leftrightarrow \mathbb{F} = \mathbf{v} \otimes \mathbf{v} - \frac{1}{3} |\mathbf{v}|^2 \mathbb{I}$$

# Oscillatory lemma

## Subsolutions

$$\partial_t \mathbf{U} + \operatorname{div}_x \mathbb{F} = 0, \quad E(\mathbf{U}) \leq \Lambda(\mathbf{U}, \mathbb{F}) \boxed{<} e$$

## Oscillatory increments

$$\partial_t \mathbf{w}_\varepsilon + \operatorname{div}_x \mathbb{G}_\varepsilon = 0, \quad \Lambda(\mathbf{U} + \mathbf{w}_\varepsilon, \mathbb{F} + \mathbb{G}_\varepsilon) < e$$

$\mathbf{w}_\varepsilon, \mathbb{G}_\varepsilon$  compactly supported in  $Q$ ,  $\mathbf{w}_\varepsilon \rightarrow 0$  weakly in  $L^2(Q)$

$$\liminf_{\varepsilon \rightarrow 0} \int_B |\mathbf{w}_\varepsilon|^2 \, dx \geq C \int_B (e - E(\mathbf{U}))^\alpha \, dx$$

$\Rightarrow$

$$\liminf_{\varepsilon \rightarrow 0} \int_B E(\mathbf{U} + \mathbf{w}_\varepsilon) \, dx \geq \int_B E(\mathbf{U}) \, dx + C \int_B (e - E(\mathbf{U}))^\alpha \, dx$$

# Admissibility criteria

## Entropy admissibility criterion - Second law

$$\partial_t E(\mathbf{U}) + \operatorname{div}_x \mathbf{F}(\mathbf{U}) \leq 0$$

## Entropy rate admissibility criterion - Dafermos [1973]

$\mathbf{U}$  maximal with respect to the relation  $\succ$

$$\mathbf{U} \succ \mathbf{V}$$

$$\Leftrightarrow$$

$$\mathbf{U}(t, \cdot) = \mathbf{V}(t, \cdot) \text{ for } t \leq \tau$$

$$\int_{\Omega} E(\mathbf{U}(t, \cdot)) \, dx \leq \int_{\Omega} E(\mathbf{V})(t, \cdot) \, dx \text{ for a.a. } t \in (\tau, \tau + \delta)$$

for some  $\delta > 0$

# Pointwise maximal entropy rate criterion

## Maximal dissipation admissibility criterion I

$$\mathbf{U} \succ_{\max} \mathbf{V}$$

$$\Leftrightarrow$$

$$\mathbf{U}(t, \cdot) = \mathbf{V}(t, \cdot) \text{ for } t \leq \tau$$

$$E(\mathbf{U}(t, \cdot)) \leq E(\mathbf{V})(t, \cdot) \text{ for a.a. } t \in (\tau, \tau + \delta)$$

for some  $\delta > 0$

$$\mathbf{U} \succ_{\max\text{-sharp}} \mathbf{V}$$

$$\Leftrightarrow$$

$$\mathbf{U}(t, \cdot) = \mathbf{V}(t, \cdot) \text{ for } t \leq \tau$$

$$E(\mathbf{U}(t, \cdot)) < E(\mathbf{V})(t, \cdot) \text{ for a.a. } t \in (\tau, \tau + \delta)$$

# Euler-Fourier system

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\varrho \vartheta) = \boxed{0} \text{ (inviscid)}$$

## Internal energy balance

$$\frac{3}{2} \left[ \partial_t(\varrho \vartheta) + \operatorname{div}_x(\varrho \vartheta \mathbf{u}) \right] - \boxed{\Delta \vartheta} = -\varrho \vartheta \operatorname{div}_x \mathbf{u} \text{ (heat conductive)}$$

# Existence of weak solutions

## Initial data

$$\varrho_0, \vartheta_0, \mathbf{u}_0 \in C^3, \varrho_0 > 0, \vartheta_0 > 0$$

## Global existence [Chiodaroli, F., Kreml [2013]]

For any (smooth) initial data  $\varrho_0, \vartheta_0, \mathbf{u}_0$  the Euler-Fourier system admits infinitely many weak solutions on a given time interval  $(0, T)$

## Regularity class

$$\varrho \in C^2, \partial_t \vartheta, \nabla_x^2 \vartheta \in L^p \text{ for any } 1 \leq p < \infty$$

$$\mathbf{u} \in C_{\text{weak}}([0, T]; L^2) \cap L^\infty, \operatorname{div}_x \mathbf{u} \in C^1$$

# Application of the convex integration method, I

## Ansatz

$$\varrho \mathbf{u} = \mathbf{v} + \nabla_x \Psi, \quad \operatorname{div}_x \mathbf{v} = 0$$

## Equations

$$\partial_t \varrho + \Delta \Psi = 0$$

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \nabla_x \Psi) \otimes (\mathbf{v} + \nabla_x \Psi)}{\varrho} \right) + \nabla_x (\partial_t \Psi + \varrho \vartheta) = 0$$

$$\frac{3}{2} \left( \partial_t (\varrho \vartheta) + \operatorname{div}_x (\vartheta (\mathbf{v} + \nabla_x \Psi)) \right) - \Delta \vartheta = -\varrho \vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x \Psi}{\varrho} \right)$$

## “Energy”

$$e = \chi(t) - \frac{3}{2} \varrho \vartheta [\mathbf{v}]$$



# Application of the convex integration method, II

## Construction of solutions

- 1 Fix  $\varrho$  and compute the acoustic potential  $\Psi$

$$-\Delta\Psi = \partial_t\varrho$$

- 2 Compute  $\vartheta = \vartheta[\mathbf{v}]$  for  $\mathbf{v} \in L^\infty$

$$\frac{3}{2} \left( \partial_t(\varrho\vartheta) + \operatorname{div}_x \left( \vartheta(\mathbf{v} + \nabla_x\Psi) \right) \right) - \Delta\vartheta = -\varrho\vartheta \operatorname{div}_x \left( \frac{\mathbf{v} + \nabla_x\Psi}{\varrho} \right)$$

- 3 Observe that  $0 < \vartheta < \bar{\vartheta}$ ,  $\bar{\vartheta}$  independent of  $\mathbf{v}$
- 4 Take

$$e = \chi(t) - \frac{3}{2}\varrho\vartheta[\mathbf{v}]$$

and use a non-local variant of the results of DeLellis and Székelyhidi for the *incompressible* Euler system to find  $\mathbf{v}$

# Conservative solutions to the Euler-Fourier system

## Total energy conservation

$$\int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{3}{2} \varrho \vartheta \right) (\tau, \cdot) \, dx = \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + \frac{3}{2} \varrho_0 \vartheta_0 \right) \, dx$$

## Initial data

$$\varrho_0 \in C^2, \vartheta_0 \in C^2, \varrho_0 > 0, \vartheta_0 > 0$$

## Conservative weak solutions [Chiodaroli, F., Kreml [2013]]

For any regular initial data  $\varrho_0, \vartheta_0$ , there exists a velocity field  $\mathbf{u}_0$  such that the Euler-Fourier problem admits infinitely many conservative weak solutions in  $(0, T)$

# Weak formulation revisited

## Mass conservation

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

## Momentum balance

$$\partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x(\varrho \vartheta) = 0$$

## Entropy production

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) = \sigma \boxed{\geq} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta^2}$$

## Total energy conservation

$$\int_{\Omega} \left( \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{3}{2} \varrho \vartheta \right) (\tau, \cdot) \, dx = \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\mathbf{u}_0|^2 + \frac{3}{2} \varrho_0 \vartheta_0 \right) \, dx$$

# Maximal dissipation criterion?

## Entropy production rate

$$\partial_t(\varrho s) + \operatorname{div}_x(\varrho s \mathbf{u}) + \operatorname{div}_x \left( \frac{\mathbf{q}}{\vartheta} \right) = \sigma$$

$$s(\varrho, \vartheta) = -\log \left( \frac{\varrho}{\vartheta^{3/2}} \right)$$

$$\sigma \stackrel{\square}{\geq} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta^2}$$

## Maximal dissipation

- Maximize the entropy production rate  $\sigma$
- Maximize the total entropy  $\int_{\Omega} \varrho s(\varrho, \vartheta) \, dx$
- Maximize the entropy  $\varrho s(\varrho, \vartheta)$