

# On diffuse interface models of binary mixtures of compressible fluids

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**ECM 2016, Berlin, 18 July - 22 July 2016**

The research leading to these results has received funding from the European Research Council under the European Union's Seventh Framework Programme (FP7/2007-2013)/ ERC Grant Agreement 320078

# Basic fields in diffuse interface modeling

**Density**

$$\varrho = \varrho(t, x)$$

**Bulk velocity**

$$\mathbf{u} = \mathbf{u}(t, x)$$

**Phase variable - concentration difference**

$$c = c(t, x)$$

**Free energy, pressure, chemical potential**

$$f = f(\varrho, c), \quad p(\varrho, c) = \varrho^2 \frac{\partial f(\varrho, c)}{\partial \varrho}, \quad \mu(\varrho, c) \approx \frac{\partial f(\varrho, c)}{\partial c}$$

# Model by Anderson, McFadden and Wheeler

**Mass conservation - equation of continuity**

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

**Momentum equation**

$$\begin{aligned} & \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho, c) \\ &= \operatorname{div}_x \mathbb{S}(c, \nabla_x \mathbf{u}) - \operatorname{div}_x \left( \nabla_x c \otimes \nabla_x c - \frac{|\nabla_x c|^2}{2} \mathbb{I} \right) \\ \mathbb{S}(c, \nabla_x \mathbf{u}) &= \nu(c) \left( \nabla_x \mathbf{u} + \nabla_x^t \mathbf{u} - \frac{2}{3} \operatorname{div}_x \mathbf{u} \mathbb{I} \right) + \eta(c) \operatorname{div}_x \mathbf{u} \mathbb{I} \end{aligned}$$

**Cahn–Hilliard equation**

$$\partial_t(\varrho c) + \operatorname{div}_x(\varrho c \mathbf{u}) = \Delta \mu, \quad \varrho \mu = \varrho \frac{\partial f(\varrho, c)}{\partial c} - \Delta c$$

# Model by Lowengrub and Truskinovsky

**Mass conservation - equation of continuity**

$$\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = 0$$

**Momentum equation**

$$\begin{aligned} & \partial_t(\varrho \mathbf{u}) + \operatorname{div}_x(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_x p(\varrho, c) \\ &= -\operatorname{div}_x \left( \varrho \nabla_x c \otimes \nabla_x c - \varrho \frac{|\nabla_x c|^2}{2} \mathbb{I} \right) \end{aligned}$$

**Cahn–Hilliard equation**

$$\partial_t(\varrho c) + \operatorname{div}_x(\varrho c \mathbf{u}) = \Delta \mu, \quad \varrho \mu = \varrho \frac{\partial f(\varrho, c)}{\partial c} - \operatorname{div}_x(\varrho \nabla_x c)$$

# Existence of weak solution - viscous case

## Basic assumptions

$$p(\varrho, c) = p_e(\varrho) + \varrho H(c), \quad p_e(\varrho) \approx \varrho^\gamma, \quad \gamma > \frac{3}{2}$$

## Global-in-time weak solutions, H.Abels, EF [Indiana Univ. Math. J. 2008]

The model by Anderson, McFadden and Wheeler (viscous model) admits global-in-time weak solutions for any finite energy initial data

# Existence of weak solutions - inviscid case

## Basic assumption

$$f(\varrho, c) = H(c) + \log(\varrho) \left( \alpha_1 \frac{1-c}{2} + \alpha_2 \frac{1+c}{2} \right)$$

## Global-in-time weak solutions, EF [DCDS(S) 2016]

The model by Lowengrub and Truskinovsky (inviscid model) admits *infinitely many* global-in-time weak solutions for any initial data

$$\varrho_0, \mathbf{u}_0, c_0 \in C^3, \varrho_0 > 0.$$

The solutions satisfy  $\varrho > 0$  (no-vacuum)

# Total energy - dissipative solutions

## Total energy

$$E(\varrho, \mathbf{u}, c) = \int \left[ \frac{1}{2} \varrho |\mathbf{u}|^2 + \frac{1}{2} \varrho |\nabla_x c|^2 + \varrho f(\varrho, c) \right] dx$$

## Dissipative solutions

$E(t)$  non-increasing

$E(t) \leq E_0$  for all  $t > 0$

# Existence of dissipative solutions

## Theorem [EF, IM Preprint 2-2015 (to appear)]

Let  $\varrho_0 \in C^3$  be given.

Then for a dense (in  $L^2$ ) set of  $c_0 \in C^3$ , there exists  $u_0 \in L^\infty$  such that the model by Lowengrub and Truskinovsky (inviscid model) admits *infinitely many* global-in-time *dissipative* weak solutions



# Abstract formulation

## Variable coefficients “Euler system”

$$\partial_t \mathbf{v} + \operatorname{div}_x \left( \frac{(\mathbf{v} + \mathbf{H}[\mathbf{v}]) \odot (\mathbf{v} + \mathbf{H}[\mathbf{v}])}{h[\mathbf{v}]} + \mathbf{M}[\mathbf{v}] \right) = 0$$
$$\operatorname{div}_x \mathbf{v} = 0,$$

## Kinetic energy

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]} = E[\mathbf{v}]$$

## Data

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{v}(T, \cdot) = \mathbf{v}_T$$

# Abstract operators

## Boundedness

$b$  maps bounded sets in  $L^\infty((0, T) \times \Omega; R^N)$  on bounded sets in  $C_b(Q, R^M)$

## Continuity

$b[\mathbf{v}_n] \rightarrow b[\mathbf{v}]$  in  $C_b(Q; R^M)$  (uniformly for  $(t, x) \in Q$ )

whenever

$\mathbf{v}_n \rightarrow \mathbf{v}$  in  $C_{\text{weak}}([0, T]; L^2(\Omega; R^N))$

## Causality

$\mathbf{v}(t, \cdot) = \mathbf{w}(t, \cdot)$  for  $0 \leq t \leq \tau \leq T$  implies  $b[\mathbf{v}] = b[\mathbf{w}]$  in  $[(0, \tau) \times \Omega]$

# Subsolutions

## Field equations, differential constraints

$$\partial_t \mathbf{v} + \operatorname{div}_x \mathbb{F} = 0, \quad \operatorname{div}_x \mathbf{v} = 0$$

$$\mathbf{v}(0, \cdot) = \mathbf{v}_0, \quad \mathbf{v}(T, \cdot) = \mathbf{v}_T$$

## Non-linear constraint

$$\mathbf{v} \in C(Q; \mathbb{R}^N), \quad \mathbb{F} \in C(Q; \mathbb{R}_{\operatorname{sym},0}^{N \times N}),$$

$$\frac{N}{2} \lambda_{\max} \left[ \frac{(\mathbf{v} + \mathbf{H}[\mathbf{v}]) \otimes (\mathbf{v} + \mathbf{H}[\mathbf{v}])}{h[\mathbf{v}]} - \mathbb{F} + \mathbb{M}[\mathbf{v}] \right] < E[\mathbf{v}]$$

# Subsolution relaxation

## Algebraic inequality

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]} \leq \frac{N}{2} \lambda_{\max} \left[ \frac{(\mathbf{v} + \mathbf{H}[\mathbf{v}]) \otimes (\mathbf{v} + \mathbf{H}[\mathbf{v}])}{h[\mathbf{v}]} - \mathbb{F} + \mathbb{M}[\mathbf{v}] \right]$$
$$< E[\mathbf{v}]$$

## Solutions

$$\frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]} = E[\mathbf{v}]$$
$$\Rightarrow$$
$$\mathbb{F} = \frac{(\mathbf{v} + \mathbf{H}[\mathbf{v}]) \odot (\mathbf{v} + \mathbf{H}[\mathbf{v}])}{h[\mathbf{v}]} + \mathbb{M}[\mathbf{v}]$$

# Oscillatory lemma

## Hypotheses:

$U \subset \mathbb{R} \times \mathbb{R}^N$ ,  $N = 2, 3$  bounded open set

$\tilde{\mathbf{h}} \in C(U; \mathbb{R}^N)$ ,  $\tilde{\mathbb{H}} \in C(U; \mathbb{R}_{\text{sym},0}^{N \times N})$ ,  $\tilde{e}, \tilde{r} \in C(U)$ ,  $\tilde{r} > 0$ ,  $\tilde{e} \leq \bar{e}$  in  $U$

$$\frac{N}{2} \lambda_{\max} \left[ \frac{\tilde{\mathbf{h}} \otimes \tilde{\mathbf{h}}}{\tilde{r}} - \tilde{\mathbb{H}} \right] < \tilde{e} \text{ in } U.$$

## Conclusion:

$$\mathbf{w}_n \in C_c^\infty(U; R^N), \mathbb{G}_n \in C_c^\infty(U; R_{\text{sym},0}^{N \times N}), n = 0, 1, \dots$$

$$\partial_t \mathbf{w}_n + \text{div}_x \mathbb{G}_n = 0, \text{div}_x \mathbf{w}_n = 0 \text{ in } R \times R^N,$$

$$\frac{N}{2} \lambda_{\max} \left[ \frac{(\tilde{\mathbf{h}} + \mathbf{w}_n) \otimes (\tilde{\mathbf{h}} + \mathbf{w}_n)}{\tilde{r}} - (\tilde{\mathbb{H}} + \mathbb{G}_n) \right] < \tilde{e} \text{ in } U,$$

$$\mathbf{w}_n \rightarrow 0 \text{ weakly in } L^2(U; R^N)$$

$$\liminf_{n \rightarrow \infty} \int_U \frac{|\mathbf{w}_n|^2}{\tilde{r}} \, dxdt \geq \Lambda(\bar{e}) \int_U \left( \tilde{e} - \frac{1}{2} \frac{|\tilde{\mathbf{h}}|^2}{\tilde{r}} \right)^2 \, dxdt$$

# Basic ideas of proof

## Localization

Localizing the result of DeLellis and Székelyhidi to “small” cubes by means of scaling arguments

## Linearization

Replacing all continuous functions by their means on any of the “small” cubes

## Eliminating singular sets

Applying Whitney’s decomposition lemma to the non-singular sets (e.g. out of the vacuum  $\{h = 0\}$ )

## Energy and other coefficients depending on solutions

Applying compactness of the abstract operators in  $\mathcal{C}$

# Results

## Result (A)

The set of subsolutions is non-empty  $\Rightarrow$  there exists infinitely many weak solutions of the problem with the same initial data

## Initial energy jump

$$\frac{1}{2} \frac{|\mathbf{v}_0 + \mathbf{H}[\mathbf{v}_0]|^2}{h[\mathbf{v}_0]} \boxed{<} \liminf_{t \rightarrow 0} \frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]}$$

## Result (B)

The set of subsolutions is non-empty  $\Rightarrow$  there exists a dense set of times such that the values  $\mathbf{v}(t)$  give rise to non-empty subsolution set with

$$\frac{1}{2} \frac{|\mathbf{v}_0 + \mathbf{H}[\mathbf{v}_0]|^2}{h[\mathbf{v}_0]} \boxed{=} \liminf_{t \rightarrow 0} \frac{1}{2} \frac{|\mathbf{v} + \mathbf{H}[\mathbf{v}]|^2}{h[\mathbf{v}]}$$