# SOME OSCILLATION CRITERIA FOR THE SECOND-ORDER LINEAR DELAY DIFFERENTIAL EQUATION 

Zdeněk Opluštil ${ }^{1}$, JiŘí ŠRemr ${ }^{2}$, Brno

(Received October 15, 2009)

Abstract. Some Wintner and Nehari type oscillation criteria are established for the second-order linear delay differential equation.

Keywords: second-order linear differential equation with a delay, oscillatory solution MSC 2010: 34K11

## 1. Introduction

On the half-line $\mathbb{R}_{+}=[0,+\infty[$ we consider the second-order linear delay differential equation

$$
\begin{equation*}
u^{\prime \prime}(t)+p(t) u(\tau(t))=0 \tag{1.1}
\end{equation*}
$$

where $p: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$is a locally integrable function and $\tau: \mathbb{R}_{+} \rightarrow \mathbb{R}_{+}$is a continuous function such that

$$
\begin{equation*}
\tau(t) \leqslant t \quad \text { for } t \geqslant 0, \quad \lim _{t \rightarrow+\infty} \tau(t)=+\infty \tag{1.2}
\end{equation*}
$$

Oscillation theory for the linear second-order ordinary differential equation is a widely studied and well-developed topic of the general theory of differential equations. As for the results which are closely related to the results of this paper, we

[^0]should mention, in particular, works of W. B. Fite, E. Hille, Z. Nehari, A. Wintner, and P.Hartman (see, e.g., [1], [3], [4], [10], [19]). These classical results were successfully extended to more general equations such as equations with $p$-Laplacian, difference equations, or equations on time-scales (see, e.g., [2], [5], [11], [15]-[18] and references therein). In this paper, some Wintner and Nehari type oscillation criteria known for the ordinary differential equations are generalized to the delay equation (1.1). We should also note that similar oscillation criteria for the differential equations with argument deviations and their systems can be found, e.g., in [6], [7], [9], [12], [14].

The following definitions introduce notions of proper oscillatory and non-oscillatory solutions of the equation (1.1) commonly used in literature.

Definition 1.1. Let $t_{0} \in \mathbb{R}_{+}$and $a_{0}=\inf \left\{\tau(t): t \geqslant t_{0}\right\}$. A continuous function $u:\left[a_{0},+\infty[\rightarrow \mathbb{R}\right.$ is said to be a proper solution of the equation (1.1) on the interval $\left[t_{0},+\infty[\right.$ if it is absolutely continuous together with its first derivative on every compact interval in $\left[t_{0},+\infty\left[\right.\right.$, satisfies the equality (1.1) almost everywhere in $\left[t_{0},+\infty[\right.$, and $\sup \{|u(s)|: s \geqslant t\}>0$ for $t \geqslant t_{0}$.

Definition 1.2. A proper solution $u$ of the equation (1.1) is said to be oscillatory if it has a sequence of zeros tending to infinity, and non-oscillatory otherwise.

Oscillation criteria presented in this paper are proved by using the Riccati technique, which is well-developed in the case of ordinary differential equations. Having a proper non-oscillatory solution $u$ of the equation (1.1) and putting $\varrho(t)=u^{\prime}(t) / u(t)$ for $t$ large enough, we get from the equality (1.1) that

$$
\varrho^{\prime}(t)=-p(t) \frac{u(\tau(t))}{u(t)}-\varrho^{2}(t) \quad \text { for large } t
$$

Therefore, in order to extend the Riccati technique to differential equations with argument deviations we need to find suitable lower and upper bounds of the quantity $u(\tau(t)) / u(t)$, which is equal to 1 in the case of ordinary differential equations. One of such estimates is given in Lemma 3.1 below.

## 2. Main Results

It is known (see, e.g., $[13, \S 3]$ ) that if the integral $\int_{0}^{+\infty} \tau(s) p(s) \mathrm{d} s$ is convergent, then the equation (1.1) has proper non-oscillatory solutions. Therefore, we will assume in the sequel that

$$
\begin{equation*}
\int_{0}^{+\infty} \tau(s) p(s) \mathrm{d} s=+\infty \tag{2.1}
\end{equation*}
$$

Theorem 2.1. Let the condition (2.1) hold and

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \frac{1}{t} \int_{0}^{t} s \tau(s) p(s) \mathrm{d} s>1 \tag{2.2}
\end{equation*}
$$

Then every proper solution of the equation (1.1) is oscillatory.
Remark 2.1. If the equation (1.1) is the ordinary one, i.e., if

$$
\begin{equation*}
\tau(t)=t \quad \text { for } t \geqslant 0 \tag{2.3}
\end{equation*}
$$

then the condition (2.2) is a particular case of the oscillation criterion proved by Z. Nehari (see [10, Theorem III]).

Now let us put

$$
\begin{equation*}
G_{*}=\liminf _{t \rightarrow+\infty} \frac{1}{t} \int_{0}^{t} s \tau(s) p(s) \mathrm{d} s . \tag{2.4}
\end{equation*}
$$

In view of Theorem 2.1, it is natural to suppose in what follows that

$$
\begin{equation*}
G_{*} \leqslant 1 . \tag{2.5}
\end{equation*}
$$

A Wintner type criterion is presented in the next theorem.
Theorem 2.2. Let the conditions (2.1) and (2.5) be fulfilled, and let

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty} \frac{\tau(t)}{t}>0 \tag{2.6}
\end{equation*}
$$

Moreover, let there exist $\lambda<1$ such that

$$
\begin{equation*}
\int_{0}^{+\infty} s^{\lambda}\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s=+\infty \tag{2.7}
\end{equation*}
$$

Then every proper solution of the equation (1.1) is oscillatory.
Remark 2.2. It is clear that if the condition (2.3) holds then the condition (2.6) is satisfied and the criterion (2.7) coincides with the well-known results (see E. Hille [4, Lemma 5]; see also A. Wintner [19] and W. B. Fite [1] for $\lambda=0$ ).

Finally, we give an oscillation criterion which generalizes a result of E. MüllerPfeiffer proved for ordinary differential equations in the paper [8].

Theorem 2.3. Let the conditions (2.1), (2.5), and (2.6) hold, and let

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \frac{1}{\ln t} \int_{0}^{t} s\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s>\frac{1}{4} \tag{2.8}
\end{equation*}
$$

Then every proper solution of the equation (1.1) is oscillatory.
Remark 2.3. The condition (2.6) in Theorems (2.2) and (2.3) is satisfied, in particular, if $\tau$ is a proportional delay, i.e., in the case where the equation (1.1) has the form

$$
u^{\prime \prime}(t)+p(t) u(\alpha t)=0
$$

with $0<\alpha \leqslant 1$.

## 3. Auxilliary statements

The next lemma contains a certain a priori estimate of non-oscillatory solutions of the equation (1.1), which plays a crucial role in the proofs of the main results.

Lemma 3.1. Let (2.1) hold and let the equation (1.1) have a solution $u$ such that there exists $t_{u}>0$ such that $u(t)>0$ for $t \geqslant t_{u}$.

Then

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \frac{1}{t} \int_{0}^{t} s \tau(s) p(s) \mathrm{d} s \leqslant 1 \tag{3.2}
\end{equation*}
$$

If, in addition, the inequality (2.6) holds then

$$
\begin{equation*}
\liminf _{t \rightarrow+\infty}\left(\frac{t}{\tau(t)}\right)^{1-G_{*}} \frac{u(\tau(t))}{u(t)} \geqslant 1 \tag{3.3}
\end{equation*}
$$

where the number $G_{*}$ is defined by the relation (2.4).
Proof. It is not difficult to verify that the inequality $u^{\prime}(t) \geqslant 0$ holds for sufficiently large $t$. Since the equation (1.1) is homogeneous, we can assume without loss of generality that $u(t) \geqslant 1$ for sufficiently large $t$. Consequently, in view of the assumption (1.2), there exists $t_{0} \geqslant t_{u}$ such that

$$
\begin{equation*}
u^{\prime}(t) \geqslant 0, \quad u(\tau(t)) \geqslant 1 \quad \text { for } t \geqslant t_{0} . \tag{3.4}
\end{equation*}
$$

It is clear that

$$
\left(t u^{\prime}(t)-u(t)\right)^{\prime}=-t p(t) u(\tau(t)) \quad \text { for a.e. } t \geqslant 0
$$

Integration of the latter inequality from $t_{0}$ to $t$ yields

$$
\begin{equation*}
t u^{\prime}(t)-u(t)=\delta-\int_{t_{0}}^{t} s p(s) u(\tau(s)) \mathrm{d} s \quad \text { for } t \geqslant t_{0} \tag{3.5}
\end{equation*}
$$

where $\delta=t_{0} u^{\prime}\left(t_{0}\right)-u\left(t_{0}\right)$.
Let $\varepsilon \in] 0,1]$ be arbitrary but fixed. Then, in view of the assumption (2.1), there exists $t_{1}(\varepsilon) \geqslant t_{0}$ such that

$$
\delta \leqslant \frac{\varepsilon}{2} \int_{t_{0}}^{t} s p(s) u(\tau(s)) \mathrm{d} s \quad \text { for } t \geqslant t_{1}(\varepsilon)
$$

Hence, it follows from the relation (3.5) that

$$
\begin{equation*}
t u^{\prime}(t)-u(t) \leqslant-\left(1-\frac{\varepsilon}{2}\right) \int_{t_{0}}^{t} s p(s) u(\tau(s)) \mathrm{d} s \leqslant 0 \quad \text { for } t \geqslant t_{1}(\varepsilon) \tag{3.6}
\end{equation*}
$$

Therefore,

$$
\left(\frac{u(t)}{t}\right)^{\prime}=\frac{1}{t^{2}}\left(t u^{\prime}(t)-u(t)\right) \leqslant 0 \quad \text { for } t \geqslant t_{1}(\varepsilon)
$$

Using this inequality and the assumption (1.2) in the formula (3.6), we get the existence of $t_{2}(\varepsilon) \geqslant t_{1}(\varepsilon)$ such that

$$
\begin{aligned}
t u^{\prime}(t)-u(t) & \leqslant-\left(1-\frac{\varepsilon}{2}\right) \int_{t_{2}(\varepsilon)}^{t} s \tau(s) p(s) \frac{u(\tau(s))}{\tau(s)} \mathrm{d} s \\
& \leqslant-\left(1-\frac{\varepsilon}{2}\right) \frac{u(t)}{t} \int_{t_{2}(\varepsilon)}^{t} s \tau(s) p(s) \mathrm{d} s \quad \text { for } t \geqslant t_{2}(\varepsilon)
\end{aligned}
$$

The last inequality implies, in particular, that

$$
\begin{equation*}
t u^{\prime}(t) \leqslant u(t)\left[1-\left(1-\frac{\varepsilon}{2}\right) \frac{1}{t} \int_{t_{2}(\varepsilon)}^{t} s \tau(s) p(s) \mathrm{d} s\right] \quad \text { for } t \geqslant t_{2}(\varepsilon) \tag{3.7}
\end{equation*}
$$

Hence, in view of (3.1) and (3.4), we get

$$
\frac{1}{t} \int_{t_{2}(\varepsilon)}^{t} s \tau(s) p(s) \mathrm{d} s \leqslant \frac{2}{2-\varepsilon} \quad \text { for } t \geqslant t_{2}(\varepsilon)
$$

and therefore

$$
\limsup _{t \rightarrow+\infty} \frac{1}{t} \int_{0}^{t} s \tau(s) p(s) \mathrm{d} s \leqslant \frac{2}{2-\varepsilon}
$$

Since $\varepsilon \in] 0,1]$ was arbitrary, the desired inequality (3.2) holds.
It remains to show the validity of the inequality (3.3). It follows from (2.4) that there exists $t_{3}(\varepsilon) \geqslant t_{2}(\varepsilon)$ such that

$$
\frac{1}{t} \int_{t_{3}(\varepsilon)}^{t} s \tau(s) p(s) \mathrm{d} s \geqslant\left(1-\frac{\varepsilon}{2}\right) G_{*} \quad \text { for } t \geqslant t_{3}(\varepsilon)
$$

By using this relation, from the inequality (3.7) we get

$$
t u^{\prime}(t)-u(t) \leqslant-\left(1-\frac{\varepsilon}{2}\right) u(t)\left(1-\frac{\varepsilon}{2}\right) G_{*} \leqslant-(1-\varepsilon) u(t) G_{*} \quad \text { for } t \geqslant t_{3}(\varepsilon)
$$

and thus we have

$$
\begin{equation*}
\left(\frac{u(t)}{t}\right)^{\prime}=\frac{1}{t^{2}}\left(t u^{\prime}(t)-u(t)\right) \leqslant-\frac{(1-\varepsilon) G_{*}}{t} \frac{u(t)}{t} \quad \text { for } t \geqslant t_{3}(\varepsilon) . \tag{3.8}
\end{equation*}
$$

Notice that, in view of (1.2), there exists $t_{4}(\varepsilon) \geqslant t_{3}(\varepsilon)$ such that $\tau(t) \geqslant t_{3}(\varepsilon)$ for $t \geqslant t_{4}(\varepsilon)$. Consequently, from the inequality (3.8) we obtain

$$
\ln \frac{u(t) / t}{u(\tau(t)) / \tau(t)} \leqslant-(1-\varepsilon) G_{*} \ln \frac{t}{\tau(t)} \quad \text { for } t \geqslant t_{4}(\varepsilon)
$$

On the other hand, by virtue of the assumption (2.6), there exists $t_{5}(\varepsilon) \geqslant t_{4}(\varepsilon)$ such that $\tau(t) / t \geqslant \alpha>0$ for $t \geqslant t_{5}(\varepsilon)$ and therefore

$$
\left(\frac{t}{\tau(t)}\right)^{1-G_{*}} \frac{u(\tau(t))}{u(t)} \geqslant \alpha^{\varepsilon G_{*}} \quad \text { for } t \geqslant t_{5}(\varepsilon)
$$

Consequently, we have

$$
\liminf _{t \rightarrow+\infty}\left(\frac{t}{\tau(t)}\right)^{1-G_{*}} \frac{u(\tau(t))}{u(t)} \geqslant \alpha^{\varepsilon G_{*}}
$$

which, due to the arbitrariness of $\varepsilon \in] 0,1]$, yields the validity of the desired inequality (3.3).

Lemma 3.2. Let $u$ be a solution of the equation (1.1) satisfying (3.1). Then there exists a finite limit

$$
\lim _{t \rightarrow+\infty} \int_{t_{u}}^{t} s^{\lambda} \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s
$$

for all $\lambda<1$. Furthermore,

$$
\begin{equation*}
\limsup _{t \rightarrow+\infty} \frac{1}{\ln t} \int_{t_{u}}^{t} s \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s \leqslant \frac{1}{4} . \tag{3.9}
\end{equation*}
$$

Proof. Let us choose $\lambda<1$ and put $\varrho(t)=u^{\prime}(t) / u(t)$ for $t \geqslant t_{u}$. Then the equality (1.1) yields that

$$
\varrho^{\prime}(t)=-p(t) \frac{u(\tau(t))}{u(t)}-\varrho^{2}(t) \quad \text { for } t \geqslant t_{u} .
$$

Multiplying both sides of this equality by $t^{\lambda}$ and integrating it from $t_{u}$ to $t$, we get

$$
\begin{align*}
t^{\lambda-1}\left[t \varrho(t)-\frac{\lambda}{2}\right]= & \delta_{1}-\frac{\lambda(2-\lambda)}{4(1-\lambda)} \frac{1}{t^{1-\lambda}}-\int_{t_{u}}^{t} s^{\lambda} \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s  \tag{3.10}\\
& -\int_{t_{u}}^{t} s^{\lambda-2}\left[s \varrho(s)-\frac{\lambda}{2}\right]^{2} \mathrm{~d} s \quad \text { for } t \geqslant t_{u}
\end{align*}
$$

where $\delta_{1}=t_{u}^{\lambda} \varrho\left(t_{u}\right)+\frac{1}{4} \lambda^{2}(1-\lambda)^{-1} t_{u}^{\lambda-1}$.
We first show that

$$
\begin{equation*}
\int_{t_{u}}^{+\infty} s^{\lambda-2}\left[s \varrho(s)-\frac{\lambda}{2}\right]^{2} \mathrm{~d} s<+\infty . \tag{3.11}
\end{equation*}
$$

Assume that, on the contrary, the integral in (3.11) is divergent. Then it follows from the relation (3.11) that, for some $t_{1} \geqslant t_{u}$, the inequality

$$
\begin{equation*}
t \varrho(t)-\frac{\lambda}{2} \leqslant-\frac{1}{2} t^{1-\lambda} \int_{t_{u}}^{t} s^{\lambda-2}\left[s \varrho(s)-\frac{\lambda}{2}\right]^{2} \mathrm{~d} s<0 \quad \text { for } t \geqslant t_{1} \tag{3.12}
\end{equation*}
$$

holds. Let us denote

$$
x(t):=\int_{t_{u}}^{t} s^{\lambda-2}\left[s \varrho(s)-\frac{\lambda}{2}\right]^{2} \mathrm{~d} s \quad \text { for } t \geqslant t_{1} .
$$

Then, using the relation (3.12), we get

$$
x^{\prime}(t)=t^{\lambda-2}\left[t \varrho(t)-\frac{\lambda}{2}\right]^{2} \geqslant \frac{1}{4 t^{\lambda}} x^{2}(t) \quad \text { for } t \geqslant t_{1} .
$$

Therefore, integration of the last inequality from $t_{1}$ to $t$ yields that $4(1-\lambda) / x\left(t_{1}\right)+$ $t_{1}^{1-\lambda} \geqslant t^{1-\lambda}$ holds for $t \geqslant t_{1}$, which is a contradiction. The contradiction obtained proves the validity of the inequality (3.11).

Now the equality (3.10) can be rewritten to the form

$$
\begin{align*}
\int_{t_{u}}^{t} s^{\lambda} \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s= & \delta_{2}-t^{\lambda} \varrho(t)-\frac{\lambda^{2}}{4(1-\lambda)} \frac{1}{t^{1-\lambda}}  \tag{3.13}\\
& +\int_{t}^{+\infty} s^{\lambda-2}\left[s \varrho(s)-\frac{\lambda}{2}\right]^{2} \mathrm{~d} s \quad \text { for } t \geqslant t_{u}
\end{align*}
$$

where $\delta_{2}=\delta_{1}-\int_{t_{u}}^{+\infty} s^{\lambda-2}[s \varrho(s)-\lambda / 2]^{2} \mathrm{~d} s$. Consequently, we get

$$
\begin{equation*}
-\infty<\lim _{t \rightarrow+\infty} \int_{t_{u}}^{t} s^{\lambda} \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s=\delta_{2}<+\infty \tag{3.14}
\end{equation*}
$$

because, in view of the condition (3.6), the inequality $\varrho(t) \leqslant 1 / t$ holds for large $t$.
It remains to show the validity of the relation (3.9). Multiplying both sides of the equality (3.13) by $t^{-\lambda}$, integrating it from $t_{u}$ to $t$ by parts, and using the above proved relation (3.14), we get

$$
\begin{aligned}
\int_{t_{u}}^{t} s \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s \leqslant & \delta_{3}+\frac{\lambda(2-\lambda)}{4} \ln t \\
& +\int_{t_{u}}^{t} \frac{1}{s}\left(s \varrho(s)-\frac{\lambda}{2}\right)\left(1-\lambda-\left[s \varrho(s)-\frac{\lambda}{2}\right]\right) \mathrm{d} s \quad \text { for } t \geqslant t_{u}
\end{aligned}
$$

where $\delta_{3}$ is a suitable constant. Hence, in view of the relation $4 x(1-\lambda-x) \leqslant(1-\lambda)^{2}$ for all $x \in \mathbb{R}$, it follows that

$$
\int_{t_{u}}^{t} s \frac{u(\tau(s)}{u(s)} p(s) \mathrm{d} s \leqslant \delta_{3}+\frac{1}{4} \ln t \quad \text { for } t \geqslant t_{u}
$$

and thus the desired condition (3.9) is satisfied.

## 4. Proofs of the main results

Pro of of Theorem 2.1. Suppose that the assertion of the theorem does not hold. Then there exists a solution $u$ of the equation (1.1) satisfying (3.1). According to Lemma 3.1, the relation (3.2) holds, which contradicts the assumption (2.2).

Pro of of Theorem 2.2. Suppose that the assertion of the theorem does not hold. Then there exists a solution $u$ of the equation (1.1) satisfying (3.1). Let $\varepsilon \in] 0,1[$ be arbitrary but fixed. According to Lemma 3.1, there exists $t_{0} \geqslant t_{u}$ such that

$$
\begin{equation*}
\left(\frac{t}{\tau(t)}\right)^{1-G_{*}} \frac{u(\tau(t))}{u(t)} \geqslant 1-\varepsilon \quad \text { for } t \geqslant t_{0} \tag{4.1}
\end{equation*}
$$

and thus we have

$$
\begin{aligned}
& \int_{0}^{t} s^{\lambda}\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s \\
& \quad \leqslant \int_{0}^{t_{0}} s^{\lambda}\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s+\frac{1}{1-\varepsilon} \int_{t_{u}}^{t} s^{\lambda} \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s \quad \text { for } t \geqslant t_{0}
\end{aligned}
$$

Hence, it follows from Lemma 3.2 that

$$
\int_{0}^{+\infty} s^{\lambda}\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s<+\infty
$$

which contradicts the assumption (2.7).
Proof of Theorem 2.3. Suppose that, on the contrary, the assertion of the theorem does not hold. Then there exists a solution $u$ of the equation (1.1) satisfy$\operatorname{ing}(3.1)$. Let $\varepsilon \in] 0,1[$ be arbitrary but fixed. According to Lemma 3.1, there exists $t_{0} \geqslant t_{u}$ such that the relation (4.1) holds. It is easy to verify that

$$
\begin{aligned}
& \frac{1}{\ln t} \int_{0}^{t} s\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s \\
& \quad \leqslant \frac{1}{\ln t} \int_{0}^{t_{0}} s\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s+\frac{1}{(1-\varepsilon) \ln t} \int_{t_{u}}^{t} s \frac{u(\tau(s))}{u(s)} p(s) \mathrm{d} s \quad \text { for } t \geqslant t_{0}
\end{aligned}
$$

Using the condition (3.9) of Lemma 3.2, we get

$$
\limsup _{t \rightarrow+\infty} \frac{1}{\ln t} \int_{0}^{t} s\left(\frac{\tau(s)}{s}\right)^{1-G_{*}} p(s) \mathrm{d} s \leqslant \frac{1}{4(1-\varepsilon)}
$$

which, due to the arbitrariness of $\varepsilon \in] 0,1[$, contradicts the assumption (2.8).

## References

[1] W. B. Fite: Concerning the zeros of the solutions of certain differential equations. Trans. Amer. Math. Soc. 19 (1918), 341-352.
zbl
[2] O. Došlý, P. Řehák: Half-linear Differential Equations. North-Holland Mathematics Studies 202, Elsevier, Amsterdam, 2005.
[3] P. Hartman: Ordinary Differential Equations. John Wiley, New York, 1964.
[4] E. Hille: Non-oscillation theorems. Trans. Amer. Math. Soc. 64 (1948), 234-252.
[5] N. Kandelaki, A.Lomtatidze, D. Ugulava: On oscillation and nonoscillation of a second order half-linear equation. Georgian Math. J. 7 (2000), 329-346.
[6] R. Koplatadze: On oscillatory solutions of second order delay differential inequalities. J. Math. Anal. Appl. 42 (1973), 148-157.
[7] R. Koplatadze: Oscillation criteria for solutions of second order differential inequalities and equations with retarded argument. Tr. Inst. Prikl. Mat. Im. I. N. Vekua 17 (1986), 104-121. (In Russian.)
[8] E. Müller-Pfeiffer: Oscillation criteria of Nehari-type for Schrödinger equation. Math. Nachr. 96 (1980), 185-194.
zbl
[9] A. D. Myshkis: Linear Differential Equations with Retarded Argument. Nauka, Moskva, 1972. (In Russian.)
zbl
[10] Z. Nehari: Oscillation criteria for second-order linear differential equations. Trans. Amer. Math. Soc. 85 (1957), 428-445.
zbl
[11] Z. Opluštil, Z. Pospíšil: An oscillation criterion for a dynamic Sturm-Liouville equation, New progress in difference equations. Proceedings of the 6th International Conference on Difference Equations, 2004, pp. 317-324.
[12] N. Partsvania: On oscillation of solutions of second-order systems of deviated differential equations. Georgian Math. J. 3 (1996), 571-582.
[13] N. Partsvania: On oscillatory and monote solutions of two-dimensional differential systems with deviated arguments. Ph.D. Thesis, A. Razmadze Mathematical Institute of the Georgian Academy of Sciences, Tbilisi, 1999.
[14] N. Partsvania: On the oscillation of solutions od two-dimensional linear differential systems with deviated arguments. Mem. Differential Equations Math. Phys. 13 (1998), 148-149.
[15] P. Řehák: Half-linear dynamic equations on time scales: IVP and oscillatory properties. Nonlinear Funct. Anal. Appl. 7 (2002), 361-403.
[16] P. Řehák: Hartman-Wintner type lemma, oscillation, and conjugacy criteria for halflinear difference equations. J. Math. Anal. Appl. 252 (2000), 813-827.
[17] C. A. Swanson: Comparison and Oscillation Theory of Linear Differential Equations. Academic Press, New York, 1968.
[18] D. Willett: Classification of second order linear differential equations with respect to oscillation. Adv. Math. 3 (1969), 594-623.
[19] A. Wintner: On the non-existence of conjugate points. Amer. J. Math. 73 (1951), 368-380.

Authors' addresses: Zdeněk Opluštil, Institute of Mathematics, Faculty of Mechanical Engineering, Brno University of Technology, Technická 2, 61669 Brno, Czech Republic, e-mail: oplustil@fme.vutbr.cz; Jiř̌́ Šremr, Institute of Mathematics, Academy of Sciences of the Czech Republic, Žižkova 22, 61662 Brno, Czech Republic, e-mail: sremr@ipm.cz.


[^0]:    ${ }^{1}$ Published results were acquired using subsidization of the Ministry of Education, Youth and Sports of the Czech Republic, research plan MSM 0021630518 "Simulation modelling of mechatronic systems".
    ${ }^{2}$ The research was supported by the Academy of Sciences of the Czech Republic, Institutional Research Plan No. AV0Z10190503.

