

Multiscale method for viscoelastic polymeric flow

H. Mizerová, Bangwei She

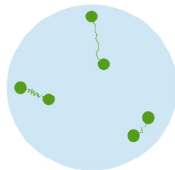


Modelling

A dumbbell model

Dilute polymer solutions: a dumbbell model

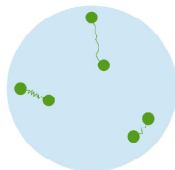
- polymer molecules surrounded by Newtonian fluid
- no interactions between molecules
- polymer molecules modeled as dumbbells



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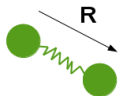
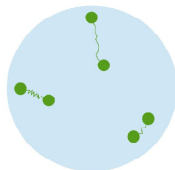
The Navier-Stokes equations

$$\begin{aligned} \frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla_x) \mathbf{u} &= 2\nu \mathbf{D}(\mathbf{u}) + \operatorname{div}_x \mathbf{T} - \nabla_x p && \text{in } (0, T) \times \Omega \\ \operatorname{div}_x \mathbf{u} &= 0 && \text{in } (0, T) \times \Omega \\ \mathbf{u} &= \mathbf{0} && \text{on } (0, T) \times \partial\Omega \\ \mathbf{u}(0) &= \mathbf{u}_0 && \text{in } \Omega \end{aligned}$$

A dumbbell model

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- the friction force from surrounding fluid
 $\mathbf{f} = \zeta(\dot{\mathbf{r}} - \mathbf{v}(\mathbf{r}, t))$
- the stochastic force due to the Brownian motion
 $\mathbf{B}_i = \sqrt{2kT\zeta} d\mathbf{W}_i/dt$
- the spring force $\mathbf{F}(\mathbf{R}) = \gamma_1(|\mathbf{R}|^2)\mathbf{R}$

$$-\zeta(\dot{\mathbf{r}}_1 - \mathbf{v}(\mathbf{r}_1, t)) + \mathbf{F}(\mathbf{R}) + \mathbf{B}_1 = 0,$$

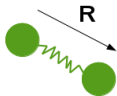
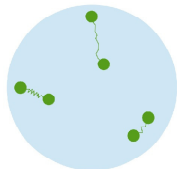
$$-\zeta(\dot{\mathbf{r}}_2 - \mathbf{v}(\mathbf{r}_2, t)) - \mathbf{F}(\mathbf{R}) + \mathbf{B}_2 = 0.$$

$$\dot{\mathbf{R}} = \nabla \mathbf{v} \cdot \mathbf{R} - \frac{2}{\zeta} \mathbf{F}(\mathbf{R}) + \sqrt{\frac{4kT}{\zeta}} \frac{d\mathbf{W}_t}{dt}.$$

A dumbbell model

Dilute polymer solutions: a dumbbell model

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The Fokker-Planck equation

$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \frac{kT}{2\zeta} \Delta_x \psi = \text{div}_R \left(-\nabla_x \mathbf{u} \cdot \mathbf{R} \psi \right) + \frac{2kT}{\zeta} \gamma_2(|\mathbf{R}|^2) \Delta_R \psi + \frac{2}{\zeta} \text{div}_R \left(\mathbf{F}(\mathbf{R}) \psi \right)$$

The Peterlin approximation

$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \frac{k_T}{2\zeta} \Delta_x \psi = \operatorname{div}_R \left(-\nabla_x \mathbf{u} \cdot \mathbf{R} \psi \right) + \frac{2k_T}{\zeta} \gamma_2(|\mathbf{R}|^2) \Delta_R \psi + \frac{2}{\zeta} \operatorname{div}_R \left(\mathbf{F}(\mathbf{R}) \psi \right)$$

► A. Peterlin: *Hydrodynamics of macromolecules in a velocity field with longitudinal gradient*,
J. Polym. Sci. Pol. Lett. 4 (1966), pp. 287-291

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length of the spring is replaced by the average length

$$\gamma_i(|\mathbf{R}|^2) \mapsto \gamma_i(\langle |\mathbf{R}|^2 \rangle) = \gamma_i(\operatorname{tr} \mathbf{C})$$



$$\operatorname{tr} \mathbf{C}(\psi) = \langle |\mathbf{R}|^2 \rangle := \int_{\mathbb{R}^d} |\mathbf{R}|^2 \psi(t, \mathbf{x}, \mathbf{R}) d\mathbf{R}$$

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Macroscopic closure of the Fokker-Planck equation

$$\frac{\partial \mathbf{C}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{C} - (\nabla \mathbf{u}) \mathbf{C} - \mathbf{C} (\nabla \mathbf{u})^T = \frac{\gamma_2(\operatorname{tr} \mathbf{C})}{\lambda} \mathbf{I} - \frac{\gamma_1(\operatorname{tr} \mathbf{C})}{\lambda \gamma_m} \mathbf{C} + \varepsilon \Delta \mathbf{C}$$

FENEP, Oldroyd-b

The kinetic Peterlin model

The **Navier-Stokes-Fokker-Planck** system

$$\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla_x) \mathbf{u} = 2\nu \mathbf{D}(\mathbf{u}) + \operatorname{div}_x \mathbf{T} - \nabla_x p$$

$$\operatorname{div}_x \mathbf{u} = 0$$

$$\mathbf{T} = \gamma_3(\operatorname{tr} \mathbf{C}(\psi)) \mathbf{C}(\psi) - \mathbf{I} \quad (\text{Kramer's expression})$$



Boundary and initial conditions: $\mathbf{u} = \mathbf{0}$ on $(0, T) \times \partial\Omega$, $\mathbf{u}(0) = \mathbf{u}_0$ in Ω

$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \frac{k_T}{2\zeta} \Delta_x \psi = \operatorname{div}_R \left(-\nabla_x \mathbf{u} \cdot \mathbf{R} \psi \right) + \frac{2k_T}{\zeta} \gamma_2(\operatorname{tr} \mathbf{C}) \Delta_R \psi + \frac{2}{\zeta} \operatorname{div}_R \left(\gamma_1(\operatorname{tr} \mathbf{C}) \mathbf{R} \psi \right)$$

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$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \varepsilon \Delta_x \psi = \operatorname{div}_R (-\nabla_x \mathbf{u} \cdot \mathbf{R} \psi) + \frac{\gamma_2(\operatorname{tr} \mathbf{C})}{2\lambda} \Delta_R \psi + \frac{\gamma_1(\operatorname{tr} \mathbf{C})}{2\lambda \gamma_M} \operatorname{div}_R (\mathbf{R} \psi)$$

$$\text{Deborah number: } \lambda = \frac{\zeta}{4\gamma_M} \frac{u_0}{L_0}$$

$$\text{center-of-mass diffusion: } \varepsilon = \left(\frac{l_0}{L_0} \right)^2 \frac{1}{8\lambda}$$

$$\frac{\gamma_1(\operatorname{tr} \mathbf{C})}{\gamma_2(\operatorname{tr} \mathbf{C})} = \frac{\gamma_1(\operatorname{tr} \mathbf{C}_M)}{\gamma_2(\operatorname{tr} \mathbf{C}_M)} = \gamma_M$$

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Boundary/decay and initial conditions:

$$\psi \rightarrow 0 \quad \text{on } (0, T] \times \Omega \text{ as } |\mathbf{R}| \mapsto \infty$$

$$\varepsilon \frac{\partial \psi}{\partial \mathbf{n}} = 0 \quad \text{on } (0, T) \times \partial\Omega \times \mathbb{R}^d$$

$$\psi(0) = \psi_0 \quad \text{on } \Omega \times \mathbb{R}^d$$

Existence of global weak solutions for Navier-Stokes-Fokker-Planck

- * FENE: Barrett, Süli
- * Hookean: Barrett, Süli
- * Peterlin: P. Gwiazda, M. Lukáčová, H. Mizerová, A. Świerczewska-Gwiazda

Numerical Methods

Navier-Stokes: Characteristic FEM

$$\begin{aligned} \frac{Re}{\Delta t} (\mathbf{u}_h^{n+1}, \mathbf{v}_h) + 2\nu (D(\mathbf{u}_h^{n+1}), D(\mathbf{v}_h)) - (p_h^{n+1}, \nabla \cdot \mathbf{v}_h) - (\nabla \cdot \mathbf{u}_h^{n+1}, q_h) \\ + s_h(p_h^{n+1}, q_h) = \frac{Re}{\Delta t} (\mathbf{u}_h^n \circ X, \mathbf{v}_h) - (\mathbf{T}_h^n, \nabla \mathbf{v}_h) \end{aligned}$$

$$s_h(p, q) = -\delta \sum_{\kappa} h_{\kappa}^2 (\nabla p, \nabla q)_{\kappa}, \quad \mathbf{u}_h^n \circ X = ?$$

Navier-Stokes: Characteristic FEM

$$\begin{aligned} \frac{Re}{\Delta t}(\mathbf{u}_h^{n+1}, \mathbf{v}_h) + 2\nu (D(\mathbf{u}_h^{n+1}), D(\mathbf{v}_h)) - (\rho_h^{n+1}, \nabla \cdot \mathbf{v}_h) - (\nabla \cdot \mathbf{u}_h^{n+1}, q_h) \\ + s_h(\rho_h^{n+1}, q_h) = \frac{Re}{\Delta t}(\mathbf{u}_h^n \circ X, \mathbf{v}_h) - (\mathbf{T}_h^n, \nabla \mathbf{v}_h) \end{aligned}$$

$$s_h(p, q) = -\delta \sum_{\kappa} h_{\kappa}^2 (\nabla p, \nabla q)_{\kappa}, \quad \mathbf{u}_h^n \circ X = ?$$

Characteristic method

Let X be the position of a particle,

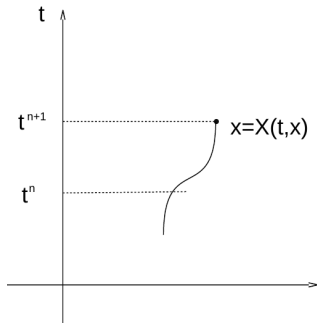
$$\begin{cases} \frac{d}{dt} X = \mathbf{u}(X, t), \quad \forall t \in [t^n, t^{n+1}], \\ X(t; x) = x. \end{cases}$$

Material derivative:

$$\frac{D\phi}{Dt} = \frac{\partial \phi}{\partial t} + \mathbf{u} \cdot \nabla \phi$$

is discretized as

$$\frac{D\phi}{Dt} \approx \frac{\phi - \phi(X(t - \Delta t; x), t - \Delta t)}{\Delta t}$$



linear symmetric No CFL condition.

Navier-Stokes: Characteristic FEM

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Fokker-Planck

High dimension

unbounded domain

Multiscale simulation in whole space

$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \varepsilon \Delta_x \psi = \operatorname{div}_R (-\nabla_x \mathbf{u} \cdot \mathbf{R} \psi) + \frac{\gamma_2(\operatorname{tr} \mathbf{C})}{2\lambda} \Delta_R \psi + \frac{\gamma_1(\operatorname{tr} \mathbf{C})}{2\lambda \gamma_M} \operatorname{div}_R (\mathbf{R} \psi)$$

→ **physical space:**
$$\frac{\partial \psi}{\partial t} + (\mathbf{u} \cdot \nabla_x) \psi - \varepsilon \Delta_x \psi = 0$$

finite volume + upwind

finite element + characteristics

→ **configuration space:**
$$\frac{\partial \psi}{\partial t} + \operatorname{div}_R (\nabla_x \mathbf{u} \cdot \mathbf{R} \psi) - \frac{\gamma_2(\operatorname{tr} \mathbf{C})}{2\lambda} \Delta_R \psi - \frac{\gamma_1(\operatorname{tr} \mathbf{C})}{2\lambda \gamma_M} \operatorname{div}_R (\mathbf{R} \psi) = 0$$

3 angle-preserving transformations
+ spectral method

Configuration space solver

1. transformation: Cartesian to polar coordinates

$$T_1 : \mathbb{R}^2 \longrightarrow [0, \infty) \times (-\pi, \pi], \quad \mathbf{R} \longmapsto (\rho, \theta), \quad \rho = \sqrt{R_1^2 + R_2^2}, \quad \theta = \arctan \frac{R_1}{R_2}$$

2. transformation: *infinite plane to unit circle*

$$T_2 : [0, \infty) \times (-\pi, \pi] \longrightarrow [0, 1] \times (-\pi, \pi], \quad (\rho, \theta) \longmapsto (r, \theta), \quad r = \frac{1}{1 + \rho}$$

3. transformation: due to boundary conditions

$$T_3 : [0, 1] \times [-\pi, \pi] \longrightarrow [-1, 1] \times [-\pi, \pi], \quad (r, \theta) \longmapsto (\eta, \theta), \quad \eta = 2(1 - r)^2 - 1$$

► A. Lozinski, C. Chauvière : *A fast solver for Fokker-Planck equation applied to viscoelastic flows calculations: 2D FENE model*, J. Comput. Phys. 189 (2003), pp. 607–625

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More general transformation:

$$\eta = 1 - 2e^{-s\rho}, \quad \eta = \frac{\rho - s}{\rho + s}, \quad s > 0.$$

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Spectral method:

$$\psi(t, \mathbf{x}, \eta, \theta) := (1 - \eta)^s \phi(t, \mathbf{x}, \eta, \theta)$$

$$\phi := \sum_{k=1}^{N_\eta} \sum_{z=0}^{N_\theta} \alpha_{zk} h_k(\eta) \cos(2z\theta) + \sum_{k=1}^{N_\eta} \sum_{z=1}^{N_\theta} \beta_{zk} h_k(\eta) \sin(2z\theta)$$

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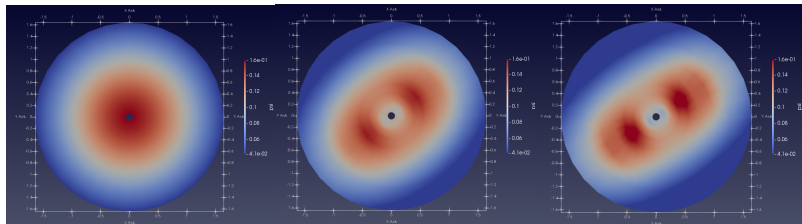
Configuration space solver

Numerical test

$$\frac{\partial \psi}{\partial t} + \operatorname{div}_R (\nabla_x \mathbf{u} \cdot \mathbf{R} \psi) - \frac{1}{2\lambda} \Delta_R \psi - \frac{1}{2\lambda} \operatorname{div}_R (\mathbf{R} \psi) = 0, \quad \lambda = 1$$

Shear flow: $\nabla \mathbf{u} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$

Initial value: $\psi_0 = \frac{1}{2\pi} \exp \left\{ \frac{-|\mathbf{R}|^2}{2} \right\}$



exact:

$$C_{11} = 1 + 2\lambda^2$$

$$C_{12} = \lambda$$

$$C_{22} = 1$$

$$\int_{\mathbb{R}^d} \psi = 1$$

numerical:

$$C_{11} = 3.017$$

$$C_{12} = 1.004$$

$$C_{22} = 1.003$$

$$\int \psi = 1.025$$

Weighted Hermite spectral

$$\tilde{H}_n(x) = \frac{\omega_\alpha^{-1}(x)}{\sqrt{2^n n!}} H_n(\alpha x), \quad \omega_\alpha(x) = e^{\alpha^2 x^2}, \quad H_n(x) = (-1)^n e^{x^2} \partial_x^n (e^{-x^2})$$

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Orthogonality

$$\int_{\mathbb{R}} \tilde{H}_m(x) \tilde{H}_n(x) \omega_\alpha(x) dx = \frac{\sqrt{\pi}}{\alpha} \delta_{m,n}$$

Derivatives

$$\alpha x \tilde{H}_n(x) = \sqrt{\frac{n+1}{2}} \tilde{H}_{n+1}(x) + \sqrt{\frac{n}{2}} \tilde{H}_{n-1}(x)$$

$$\partial_x \tilde{H}_n(x) = -\alpha \sqrt{2(n+1)} \tilde{H}_{n+1}(x)$$

$$x \partial_x \tilde{H}_n(x) = -\sqrt{(n+1)(n+2)} \tilde{H}_{n+2}(x) - (n+1) \tilde{H}_n(x)$$

$$\partial_x^2 \tilde{H}_n(x) = 2\alpha^2 \sqrt{(n+1)(n+2)} \tilde{H}_{n+2}(x)$$

Weighted Hermite spectral

$$\tilde{H}_n(x) = \frac{\omega_\alpha^{-1}(x)}{\sqrt{2^n n!}} H_n(\alpha x), \quad \omega_\alpha(x) = e^{\alpha^2 x^2}, \quad H_n(x) = (-1)^n e^{x^2} \partial_x^n (e^{-x^2})$$

Let $\psi(\mathbf{t}, \mathbf{x}, \mathbf{q}) = \sum_{m,n=0}^N \phi_{mn} \tilde{H}_m(r) \tilde{H}_n(s)$, $\mathbf{q} = (r, s)$.

Discretization of configuration space:

$r_i, i = 0, 1, \dots, N$ are the roots of $H_{N+1}(r) = 0$.

Test with $\tilde{H}_z(r) \tilde{H}_k(s) \omega_\alpha(r) \omega_\alpha(s)$ and integrate over the whole space:

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Test with $\tilde{H}_z(r) \tilde{H}_k(s) \omega_\alpha(r) \omega_\alpha(s)$ and integrate over the whole space:

$$\frac{\partial \phi_{zk}}{\partial t} = \mathcal{L}(\phi_{zk}),$$

where

$$\begin{aligned} \mathcal{L}(\phi_{zk}) = & \phi_{z-2,k} (2\alpha^2 \gamma_2 - A_{11}) \sqrt{z(z-1)} + \phi_{z-1,k-1} (-A_{12} - A_{21}) \sqrt{zk} \\ & + \phi_{z-1,k+1} (-A_{12}) \sqrt{z(k+1)} + \phi_{z,k-2} (2\alpha^2 \gamma_2 - A_{22}) \sqrt{k(k-1)} \\ & + \phi_{z,k} (-A_{11}z - A_{22}k) + \phi_{z+1,k-1} (-A_{12}) \sqrt{(z+1)k}, \end{aligned}$$

$$\text{and } A_{ij} = \gamma_1 \mathbf{l} - \nabla_{\mathbf{x}} \mathbf{u}, \quad \psi_{z,k} \equiv 0, \text{ for } m, n < 0 \text{ or } > N.$$

$$\frac{\phi_{zk}^* - \phi_{zk}^n}{\Delta t} = \mathcal{L}(\phi_{zk}^*), \quad (1)$$

$$\left(\frac{\phi_{zk}^{n+1} - \phi_{zk}^* \circ \mathbf{X}^n}{\Delta t}, \mathbf{q}_h \right) + \varepsilon (\nabla_{\mathbf{x}} \phi_{zk}, \nabla_{\mathbf{x}} \mathbf{q}_h) = 0, \quad (2)$$

Lemma

If the probability distribution function is initially independent of the physical position \mathbf{x} , i.e. $\psi(0, \mathbf{x}, \mathbf{q}) = \psi_0(\mathbf{q})$, then we have

$$\phi_{00}(t^n, \mathbf{x}) \equiv \phi_{00}(0, \mathbf{x}).$$

Step 1. from (1)

$$\phi_{00}^* - \phi_{00}^n = 0.$$

Step 2, if $\phi_{00}^n(\mathbf{x})$ is independent of \mathbf{x} , then $\phi_{zk}^* \circ \mathbf{X}^n = \phi_{zk}^*$ is a constant in the physical space, which results in $\phi_{00}^{n+1} = \phi_{00}^* = \phi_{00}^n$ from (2).

Lemma (Mohammadi & Borzi, Int. J. Uncertain. Quantif. 2015)

$$\int_{\mathbb{R}} \tilde{H}_n(x) dx = 0, \text{ for } n \geq 1.$$

If n is odd, the result is obvious as $\tilde{H}_n(-x) = (-1)^n \tilde{H}_n(x)$.

If n is even

$$\begin{aligned} \int_{\mathbb{R}} \tilde{H}_n(x) dx &= \frac{1}{\sqrt{2^n n!}} \int_{\mathbb{R}} H_n(\alpha x) e^{-\alpha^2 x^2} dx = \frac{1}{\alpha} \frac{1}{\sqrt{2^n n!}} \int_{\mathbb{R}} H_n(r) e^{-r^2} dr \\ &= \frac{2}{\alpha \sqrt{2^n n!}} \int_0^\infty H_n(r) e^{-r^2} dr = \frac{2}{\alpha \sqrt{2^n n!}} \lim_{x \rightarrow \infty} \int_0^x H_n(r) e^{-r^2} dr \\ &= \frac{2}{\alpha \sqrt{2^n n!}} \lim_{x \rightarrow \infty} \left(H_{n-1}(0) - e^{-x^2} H_{n-1}(x) \right) \\ &= 0. \end{aligned}$$

Lemma

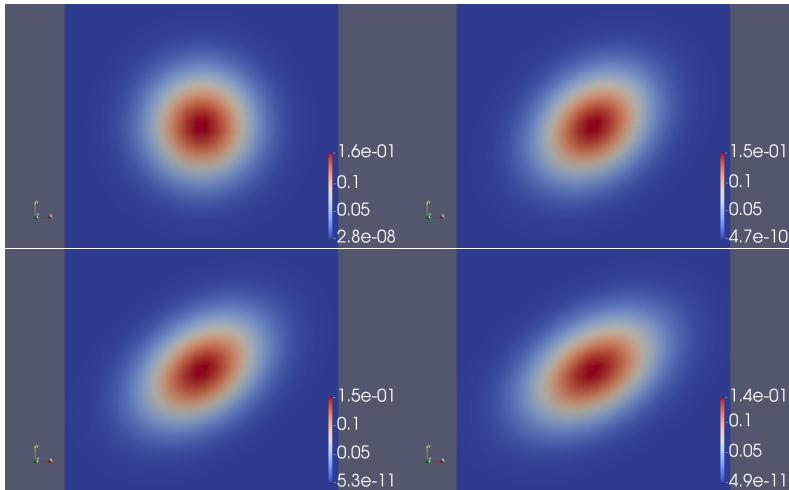
If the probability distribution function is initially independent of the physical position \mathbf{x} , i.e. $\psi(0, \mathbf{x}, \mathbf{q}) = \psi_0(\mathbf{q})$, then we have the conservation of mass

$$\int_{\mathbb{R}^2} \psi(t^n) = \int_{\mathbb{R}^2} \psi_0 = 1.$$

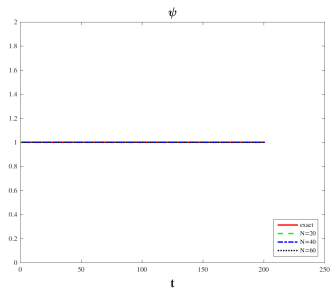
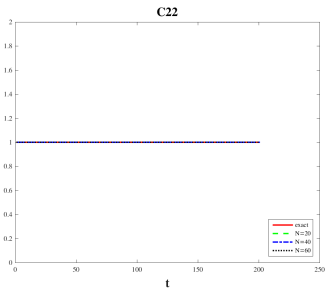
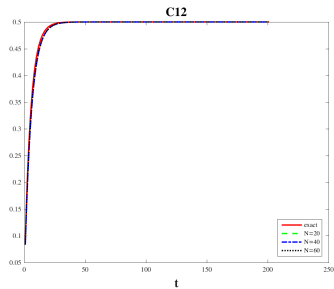
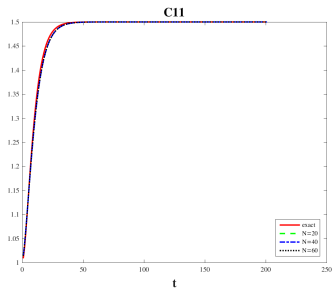
Application of the above lemmas:

$$\begin{aligned} \int_{\mathbb{R}^2} \psi(t^n) &:= \int_{\mathbb{R}^2} \sum_{i,j=0}^N \phi_{ij}(t^n) \tilde{H}_i(r) \tilde{H}_j(s) dr ds = \int_{\mathbb{R}^2} \phi_{00}(t^n) \tilde{H}_0(r) \tilde{H}_0(s) dr ds \\ &= \int_{\mathbb{R}^2} \phi_{00}(t^0) \tilde{H}_0(r) \tilde{H}_0(s) dr ds = \int_{\mathbb{R}^2} \sum_{i,j=0}^N \phi_{ij}(t^0) \tilde{H}_i(r) \tilde{H}_j(s) dr ds =: \int_{\mathbb{R}^2} \psi(t^0). \end{aligned}$$

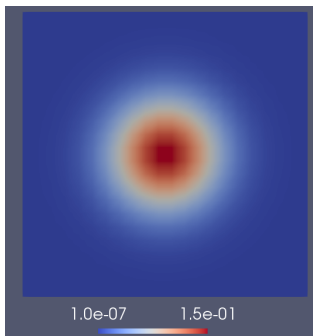
$\Delta t = 0.1$



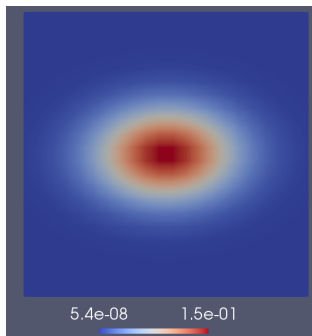
$$\Delta t = 0.1$$



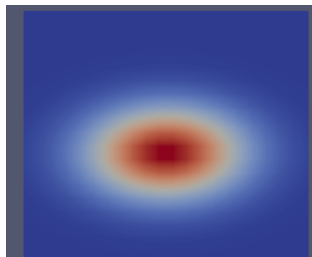
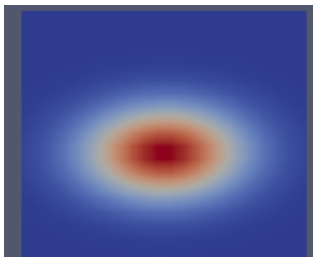
Extensional flow

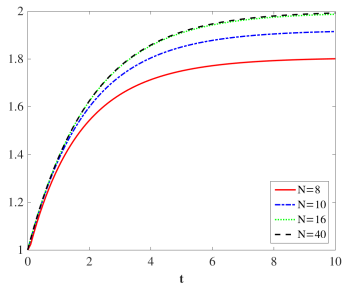


(a) $t=0$

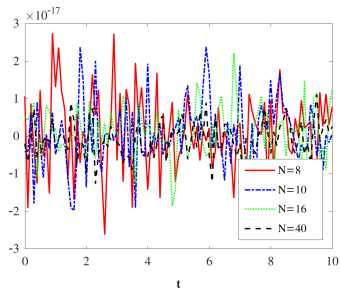


(b) $t=1$

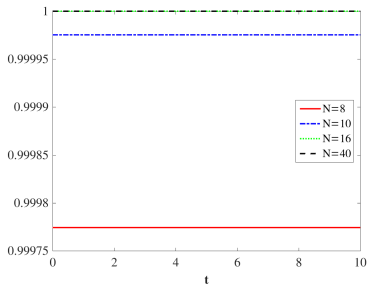
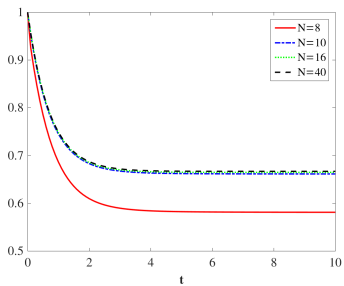




(a) C_{11}



(b) C_{12}



Steady state of extensional flow

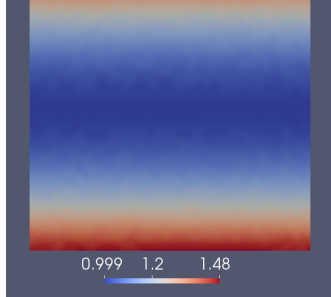
$$\psi_{\text{ref}} = cM \exp(\text{We} \mathbf{q}^T \nabla_{\mathbf{x}} \mathbf{u} \mathbf{q}),$$

$$M = \frac{1}{2\pi} \exp\left(-\frac{1}{2} |\mathbf{q}|^2\right)$$

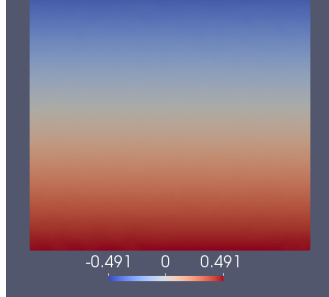
$$\mathbf{C}_{\text{ref}} = \text{diag}\{2, 2/3\}$$

Table : Numerical error of planar extensional flow

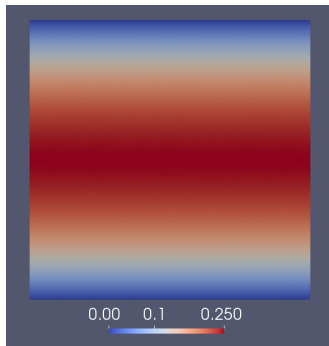
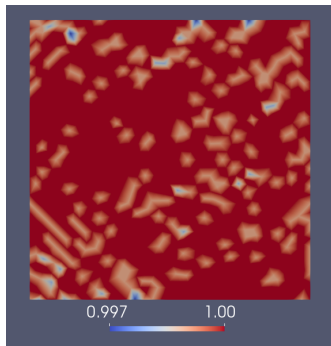
N	8	10	16	20	30
$\ \psi_h - \psi_{\text{exact}}\ _{L_2(\mathbb{D})}$	2.1e-02	1.3e-02	3.3e-03	1.3e-03	1.5e-04
$ \mathbf{C}_{11} - \mathbf{C}_{11\text{ref}} $	1.9e-1	7.9e-2	5.5e-3	8.8e-4	6.2e-5
$ \mathbf{C}_{22} - \mathbf{C}_{22\text{ref}} $	8.6e-2	5.5e-3	2.2e-3	7.0e-5	1.0e-6



(a) C_{11}



(b) C_{12}



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Thank you for your attention!