## Ergodic theory for energetically open fluid systems

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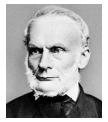
PDEs describing far from equilibrium systems, 8 ECM Portorož, 20 June – 26 June 2021





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# Motto



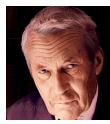
Rudolf Clasius 1822–1888

### Basic principles of thermodynamics of closed systems

Die Energie der Welt ist constant. Die Entropie der Welt strebt einem Maximum zu.

### Turbulence - ergodic hypothesis

Time averages along trajectories of the flow converge, for large enough times, to an ensemble average given by a certain probability measure



Andrey Nikolaevich Kolmogorov 1903–1987

Mass conservation

 $\partial_t \varrho + \operatorname{div}_x(\varrho \mathbf{u}) = \mathbf{0}$ 

Newton's Second law (momentum balance)

 $\partial_t(\rho \mathbf{u}) + \operatorname{div}_x(\rho \mathbf{u} \otimes \mathbf{u}) + \nabla_x \boldsymbol{\rho} = \operatorname{div}_x \mathbb{S} + \rho \mathbf{g}$ 

Second law of thermodynamics (entropy balance)

$$\partial_t(\varrho s(\varrho, \vartheta)) + \operatorname{div}_x(\varrho s(\varrho, \vartheta) \mathbf{u}) + \operatorname{div}_x\left(\frac{\mathbf{q}}{\vartheta}\right) = \frac{1}{\vartheta}\left(\mathbb{S}: \mathbb{D}_x \mathbf{u} - \frac{\mathbf{q} \cdot \nabla_x \vartheta}{\vartheta}\right)$$

Newton's rheological law

$$\mathbb{S}(\vartheta, \mathbb{D}_{\mathsf{x}} \mathsf{u}) = \mu(\vartheta) \left( \nabla_{\mathsf{x}} \mathsf{u} + \nabla^{t}_{\mathsf{x}} \mathsf{u} - \frac{2}{d} \mathrm{div}_{\mathsf{x}} \mathsf{u} \mathbb{I} \right) + \eta(\vartheta) \mathrm{div}_{\mathsf{x}} \mathsf{u} \mathbb{I}$$

Fourier's law

$$\mathbf{q}(artheta, 
abla_{x}artheta) = -\kappa(artheta) 
abla_{x}artheta$$

## **Boundary conditions**

**Closed systems** 

impermeability: 
$$\mathbf{u} \cdot \mathbf{n}|_{\partial\Omega} = 0$$
, no-slip:  $\mathbf{u} \times \mathbf{n}|_{\partial\Omega} = 0$ 

thermal insulation:  $\mathbf{q} \cdot \mathbf{n}|_{\partial\Omega} = 0$ 

Open systems

$$|\mathbf{u}|_{\partial\Omega} = \mathbf{u}_B$$
, inflow  $\Gamma_{in} : \mathbf{u}_B \cdot \mathbf{n} < 0$ , outflow  $\Gamma_{out} : \mathbf{u}_B \cdot \mathbf{n} > 0$ 

 $\varrho|_{\Gamma_{\rm in}}=\varrho_B$ 

 $\begin{array}{l} \mbox{heat flow: } \varrho e(\varrho, \vartheta)(\textbf{u}_B \cdot \textbf{n}) + \textbf{q} \cdot \textbf{n} = f_{i,B}(\textbf{u}_B \cdot \textbf{n}) \mbox{ on } \Gamma_{\rm in}, \ \textbf{q} \cdot \textbf{n} = 0 \mbox{ on } \Gamma_{\rm out} \\ \\ \mbox{ alternatively} \end{array}$ 

$$\vartheta = \vartheta_B$$
 on  $\partial \Omega$ 

# **Necessary ingredients**

• Global existence: The problem admits global-in-time solutions defined for all  $t \ge t_0$  for any admissible data

 Dissipativity (in the sense of Levinson): All solutions are eventually trapped in a bounded absorbing set

• Asymptotic compactness: Global in time solutions are precompact with respect to the time shifts; they approach a compact  $\omega$ -limit set as  $t \to \infty$ 

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## Long-time behavior, closed systems

Total energy

$$E(\varrho,\vartheta,\mathbf{u}) = \frac{1}{2}\varrho|\mathbf{u}|^2 + \varrho e(\varrho,\vartheta)$$

Dichotomy for the closed systems

$$\mathbf{g} = \mathbf{g}(x)$$

Either

 $\mathbf{g} = 
abla_{\mathbf{x}} \mathcal{G} \ \Rightarrow \ \text{all solutions tend to a single equilibrium}$ 

or

$$\mathbf{g} \neq 
abla_{\mathbf{x}} \mathbf{G} \; \Rightarrow \; \int_{\Omega} \mathbf{E}(t, \cdot) \; \mathrm{d} \mathbf{x} \to \infty \; \mathrm{as} \; t \to \infty$$

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## **Dynamical systems**

Dynamical system

 $\mathsf{U}(t,\cdot):[0,\infty) imes X o X$ 

• Closed system:  $U(t, X_0) \rightarrow U_{\infty}$  equilibrium solution as  $t \rightarrow \infty$ 

• Open system: 
$$\frac{1}{T} \int_0^T F(\mathbf{U}(t, X_0)) dt \to \int_X F(X) d\mu, \ T \to \infty$$
  
 $\mu$  a.s. in  $X_0$ 

Principal mathematical problems:

Low regularity of global in time solutions

Global in time solutions necessary. For many problems in fluid dynamics – Navier–Stokes or Euler system – only weak solutions available

#### Lack of uniqueness

Solutions do not, or at least are not known to, depend uniquely on the initial data. Spaces of trajectories: Sell, Nečas, Temam and others

#### Propagation of oscillations

Realistic systems are partly hyperbolic: propagation of oscillations "from the past", singularities

# Weak formulation

$$\partial_{t} \varrho + \operatorname{div}_{x}(\varrho \mathbf{u}) = \mathbf{0}, \ \varrho|_{\Gamma_{\mathrm{in}}} = \varrho_{B}$$
$$\partial_{t}(\varrho \mathbf{u}) + \operatorname{div}_{x}(\varrho \mathbf{u} \otimes \mathbf{u}) + \nabla_{x} \rho = \operatorname{div}_{x} \mathbb{S} + \varrho \mathbf{g}, \ \mathbf{u}|_{\partial\Omega} = \mathbf{u}_{B}$$
$$\partial_{t}(\varrho s) + \operatorname{div}_{x}(\varrho s \mathbf{u}) + \operatorname{div}_{x}\left(\frac{\mathbf{q}}{\vartheta}\right) \ge \frac{1}{\vartheta} \left(\mathbb{S} : \mathbb{D}_{x} \mathbf{u} - \frac{\mathbf{q} \cdot \nabla_{x} \vartheta}{\vartheta}\right)$$

ballistic energy balance

$$\frac{\mathrm{d}}{\mathrm{d}t}\int_{\Omega}\left(\frac{1}{2}\varrho|\mathbf{u}-\mathbf{u}_{B}|^{2}+\varrho \boldsymbol{e}(\varrho,\vartheta)-\widetilde{\vartheta}\varrho\boldsymbol{s}(\varrho,\vartheta)\right)\,\mathrm{d}x...$$

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# Abstract setting



Space of entire trajectories

$$\mathcal{T} = C_{\mathrm{loc}}(R; X), \ t \in (-\infty, \infty)$$

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George Roger Sell 1937–2015

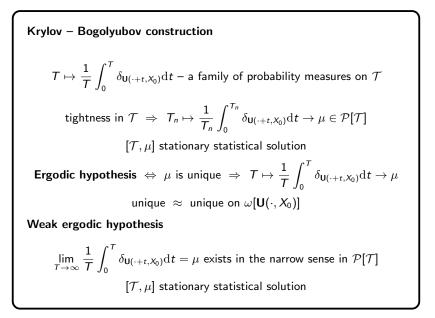
 $\omega\text{-limit set}$ 

$$\omega[\mathbf{U}(\cdot, X_0)] \subset \mathcal{T}$$
$$\omega[\mathbf{U}(\cdot, X_0)] = \left\{ \mathbf{V} \in \mathcal{T} \mid \mathbf{U}(\cdot + t_n, X_0) \to \mathbf{V} \text{ in } \mathcal{T} \text{ as } t_n \to \infty \right\}$$

**Necessary ingredients** 

- Dissipativity ultimate boundedness of trajectories
- Compactness in appropriate spaces

## Strong and weak ergodic hypothesis



Global in time weak solutions

 $U = [\varrho, m = \varrho u, S = \varrho s]$  – weak solution of the Navier–Stokes–Fourier system satisfying ballistic energy balance and defined for  $t > T_0$ 

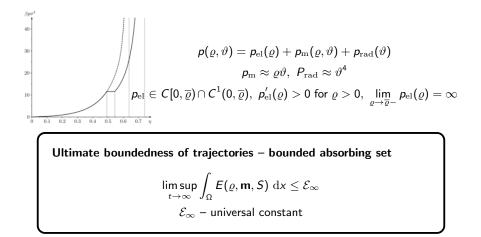
Bounded energy

$$\limsup_{t\to\infty}\int_{\Omega} E(\varrho,\mathbf{m},S) \, \mathrm{d} x \leq \mathcal{E}_{\infty}$$

#### Available

- Existence: E.F. and A. Novotný, Commun. Math. Phys. 2021
   N. Chaudhuri and E.F. (Dirichlet b.c. for the temperature) Preprint 2021
- Globally bounded solutions: F. Fanelli, E. F., and M. Hofmanová arxiv preprint No. 2006.02278, 2020
   J. Březina, E. F., and A. Novotný, Communications in PDE's 2020
   E.F., A. Novotný, M. Petcu book in preparation

### Hard sphere pressure EOS



Trajectory space

#### Fundamental result on compactness [Fanelli, EF, Hofmanová, 2020]

The  $\omega$ -limit set  $\omega[\varrho, \mathbf{m}, S]$  of each global in time trajectory with globally bounded energy is:

- non empty
- compact in  $\mathcal{T}$
- time shift invariant
- consists of entire (defined for all  $t \in R$ ) weak solutions of the Navier–Stokes–Fourier system

## **Propagation of oscillations**

Equation of continuity

$$\partial_t \varrho + \mathbf{u} \cdot \nabla_x \varrho = -\varrho \operatorname{div}_x \mathbf{u}$$

Renormalized equation of continuity

$$\partial_t b(\varrho) + \operatorname{div}_x(b(\varrho)\mathbf{u}) + (b'(\varrho)\varrho - b(\varrho))\operatorname{div}_x\mathbf{u} = 0$$

Weak convergence

$$\begin{split} b(\varrho_n) &\to \overline{b(\varrho)} \text{ weakly in } L^1 \\ \partial_t \Big[ \overline{b(\varrho)} - b(\varrho) \Big] + \operatorname{div}_x \Big( \overline{b(\varrho) \mathbf{u}} - b(\varrho) \mathbf{u} \Big) \\ &= \Big( b'(\varrho) \varrho - b(\varrho) \Big) \operatorname{div}_x \mathbf{u} - \overline{\Big( b'(\varrho) \varrho - b(\varrho) \Big) \operatorname{div}_x \mathbf{u}} \\ & \Big[ \overline{b(\varrho)} - b(\varrho) \Big] (0, \cdot) = 0 \text{ is needed!} \end{split}$$

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## Vanishing oscillation defect, I

**Compactness of densities:** 

$$\begin{split} \varrho_n &\equiv \varrho(\cdot + T_n) \to \varrho \text{ in } C_{\text{weak,loc}}(R; L^{\gamma}(\Omega)) \\ \varrho_n \log(\varrho_n) \to \overline{\varrho \log(\varrho)} \geq \varrho \log(\varrho) \\ \text{oscillation defect: } D(t) &\equiv \int_{\Omega} \overline{\varrho \log(\varrho)} - \varrho \log(\varrho) \, \mathrm{d} x \geq 0 \end{split}$$

**Renormalized equation:** 

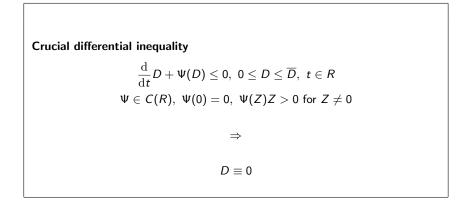
$$\frac{\mathrm{d}}{\mathrm{d}t}D + \int_{\Omega} \left[\overline{\varrho \mathrm{div}_{x} \mathbf{u}} - \varrho \mathrm{div}_{x} \mathbf{u}\right] \,\mathrm{d}x = \mathbf{0}, \ \mathbf{0} \leq D \leq \overline{D}, \ t \in R$$

Lions' identity

$$\overline{\varrho \mathrm{div}_{\mathsf{x}} \mathsf{u}} - \varrho \mathrm{div}_{\mathsf{x}} \mathsf{u} = \overline{\rho(\varrho, \vartheta)\varrho} - \overline{\rho(\varrho, \vartheta)} \ \varrho \geq 0$$

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## Vanishing oscillation defect, II



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## Statistical stationary solutions

### Application of Krylov – Bogolyubov method

$$\frac{1}{T_n} \int_0^{T_n} \delta_{\varrho(\cdot+t,\cdot),\mathsf{m}(\cdot+t,\cdot),S(\cdot+t,\cdot)} \, \mathrm{d}t \to \mu \in \mathcal{P}[\mathcal{T}] \text{ narrowly}$$

 $\left[\mathcal{T},\mu\right]$  (canonical representation) – statististical stationary solution

 $\mu(t)|_X$  (marginal) independent of  $t\in R$ 

Application of Birkhoff – Khinchin ergodic theorem

$$\frac{1}{T}\int_0^T F(\varrho(t,\cdot),\mathsf{m}(t,\cdot),S(t\cdot))\mathrm{d}t\to\overline{F} \text{ as } T\to\infty$$

F bounded Borel measurable on X for  $\mu$  – a.a. ( $\varrho$ , **m**)  $\in \omega$